

- 9.3. Using an analysis similar to that used in Example 9.3, we know that the given signal has a Laplace transform of the form

$$X(s) = \frac{1}{s+5} + \frac{1}{s+\beta}.$$

The corresponding ROC is  $\mathcal{R}e\{s\} > \max(-5, \mathcal{R}e\{\beta\})$ . Since we are given that the ROC is  $\mathcal{R}e\{s\} > -3$ , we know that  $\mathcal{R}e\{\beta\} = 3$ . There are no constraints on the imaginary part of  $\beta$ .

- 9.9. Using partial fraction expansion

$$X(s) = \frac{4}{s+4} - \frac{2}{s+3}.$$

Taking the inverse Laplace transform,

$$x(t) = 4e^{-4t}u(t) - 2e^{-3t}u(t).$$

- 9.15. Taking the Laplace transforms of both sides of the two differential equations, we have

$$sX(s) = -2Y(s) + 1 \quad \text{and} \quad sY(s) = 2X(s).$$

Solving for  $X(s)$  and  $Y(s)$ , we obtain

$$X(s) = \frac{s}{s^2+4} \quad \text{and} \quad Y(s) = 2s^2+4.$$

The region of convergence for both  $X(s)$  and  $Y(s)$  is  $\mathcal{R}e\{s\} > 0$  because both are right-sided signals.

- 9.28. (a) The possible ROCs are

- (i)  $\mathcal{R}e\{s\} < -2$ .
- (ii)  $-2 < \mathcal{R}e\{s\} < -1$ .
- (iii)  $-1 < \mathcal{R}e\{s\} < 1$ .
- (iv)  $\mathcal{R}e\{s\} > 1$ .

- (b) (i) Unstable and anticausal.  
(ii) Unstable and non causal.  
(iii) Stable and non causal.  
(iv) Unstable and causal.

9.40. Taking the unilateral Laplace transform of both sides of the given differential equation, we get

$$s^3\mathcal{Y}(s) - s^2y(0^-) - sy'(0^-) - y''(0^-) + 6s^2\mathcal{Y}(s) - 6sy(0^-) - 6y(0^-) + 11s\mathcal{Y}(s) - 11y(0^-) + 6\mathcal{Y}(s) = \mathcal{X}(s). \quad (\text{S9.40-1})$$

(a) For the zero state response, assume that all the initial conditions are zero. Furthermore, from the given  $x(t)$  we may determine

$$\mathcal{X}(s) = \frac{1}{s+4}, \quad \Re\{s\} > -4.$$

From eq. (S9.40-1), we get

$$\mathcal{Y}(s)[s^3 + 6s^2 + 11s + 6] = \frac{1}{s+4}.$$

Therefore,

$$\mathcal{Y}(s) = \frac{1}{(s+4)(s^3 + 6s^2 + 11s + 6)}.$$

Taking the inverse unilateral Laplace transform of the partial fraction expansion of the above equation, we get

$$y(t) = \frac{1}{6}e^{-t}u(t) - \frac{1}{6}e^{-4t}u(t) + \frac{1}{2}e^{-2t}u(t) - \frac{1}{2}e^{-3t}u(t).$$

(b) For the zero-input response, we assume that  $\mathcal{X}(s) = 0$ . Assuming that the initial conditions are as given, we obtain from (S9.40-1)

$$\mathcal{Y}(s) = \frac{s^2 + 5s + 6}{s^3 + 6s^2 + 11s + 6} = \frac{1}{s+1}.$$

Taking the inverse unilateral Laplace transform of the above equation, we get

$$y(t) = e^{-t}u(t).$$

(c) The total response is the sum of the zero-state and zero-input responses.

$$y(t) = \frac{7}{6}e^{-t}u(t) - \frac{1}{6}e^{-4t}u(t) + \frac{1}{2}e^{-2t}u(t) - \frac{1}{2}e^{-3t}u(t).$$