

$$\textcircled{1} \quad x = \frac{a}{2} \cosh u \cos \theta \quad y = \frac{a}{2} \sinh u \sin \theta$$

Using notation in lecture $\mathcal{F}^1 = x, \mathcal{F}^2 = y, x^1 = u, x^2 = \theta$

$$g_{kl} = \frac{\partial \mathcal{F}^i}{\partial x^k} \frac{\partial \mathcal{F}^j}{\partial x^l} \delta_{ij}$$

$$g_{uu} = \left(\frac{\partial x}{\partial u} \right)^2 + \left(\frac{\partial y}{\partial u} \right)^2 = \frac{a^2}{4} \left[\sinh^2 u \cos^2 \theta + \cosh^2 u \sin^2 \theta \right]$$

"
 $+ \sinh^2 u$

$$= \frac{a^2}{4} \left[\sinh^2 u + \sin^2 \theta \right] = \frac{a^2}{4} \left[\cosh^2 u - \cos^2 \theta \right]$$

$$g_{\theta\theta} = \left(\frac{\partial x}{\partial \theta} \right)^2 + \left(\frac{\partial y}{\partial \theta} \right)^2 = \frac{a^2}{4} \left[\cosh^2 u \sin^2 \theta + \sinh^2 u \cos^2 \theta \right] = g_{\theta\theta}$$

$$g_{u\theta} = g_{\theta u} = \frac{\partial x}{\partial u} \frac{\partial x}{\partial \theta} + \frac{\partial y}{\partial u} \frac{\partial y}{\partial \theta} = \frac{a^2}{4} \left[(\sinh u \cos \theta)(-\cosh u \sin \theta) \right.$$

$$\left. + (\cosh u \sin \theta)(\sinh u \cos \theta) \right] = 0$$

$$g_{uu} = g_{\theta\theta} = \frac{a^2}{4} \left[\sinh^2 u + \sin^2 \theta \right] = \frac{a^2}{4} \left[\cosh^2 u - \cos^2 \theta \right]$$

$$g_{u\theta} = g_{\theta u} = 0$$

$$\textcircled{2} \quad \Gamma_{jk}^i = \frac{1}{2} g^{li} \left[\frac{\partial g_{kl}}{\partial x^j} + \frac{\partial g_{jl}}{\partial x^k} - \frac{\partial g_{jk}}{\partial x^l} \right]$$

From lecture we know that $g_{rr} = 1$, $g_{\theta\theta} = r^2$, $g_{r\theta} = 0$.

Here $x^1 = r$ and $x^2 = \theta$. Since g_{ij} is diagonal we have $g^{rr} = 1$, $g^{\theta\theta} = \frac{1}{r^2}$, $g^{r\theta} = 0$.

$$\text{Hence } \Gamma_{jk}^i = \frac{1}{2} g^{ij} \left[\frac{\partial g_{kl}}{\partial x^j} + \frac{\partial g_{jl}}{\partial x^k} - \frac{\partial g_{jk}}{\partial x^l} \right] \quad \begin{array}{l} \text{no sum} \\ \text{on } i \end{array}$$

$$\Gamma_{rr}^r = \frac{1}{2} [0 + 0 - 0] = 0 \quad \boxed{\Gamma_{rr}^r = 0}$$

$$\Gamma_{\theta r}^r = \frac{1}{2} [0 + 0 - 0] = 0 \quad \boxed{\Gamma_{\theta r}^r = \Gamma_{r\theta}^r = 0}$$

$$\Gamma_{\theta\theta}^r = \frac{1}{2} [0 + 0 - 2r] = -r \quad \boxed{\Gamma_{\theta\theta}^r = -r}$$

$$\Gamma_{\theta\theta}^{\theta} = \frac{1}{2} \frac{1}{r^2} [0 + 0 - 0] = 0 \quad \boxed{\Gamma_{\theta\theta}^{\theta} = 0}$$

$$\Gamma_{rr}^{\theta} = \frac{1}{2} \frac{1}{r^2} [0 + 0 - 0] = 0 \quad \boxed{\Gamma_{rr}^{\theta} = 0}$$

$$\Gamma_{\theta r}^{\theta} = \frac{1}{2} \frac{1}{r^2} [0 + 2r - 0] = \frac{1}{r} \quad \boxed{\Gamma_{\theta r}^{\theta} = \Gamma_{r\theta}^{\theta} = \frac{1}{r}}$$

$$\textcircled{3} \quad \epsilon_{\hat{i}_1 \dots \hat{i}_n} = g_{\hat{i}_1 \hat{i}_1'} g_{\hat{i}_2 \hat{i}_2'} \dots g_{\hat{i}_n \hat{i}_n'} \epsilon^{i_1' i_2' \dots i_n'}$$

which convert contravariant to covariant.

$$\text{By definition } \epsilon^{\hat{i}_1 \hat{i}_2 \dots \hat{i}_n} = \begin{cases} 1 & \text{if even permutation} \\ -1 & \text{if odd permutation} \\ 0 & \text{if any pair of indices} \\ & \text{are equal} \end{cases}$$

Then the same is true of $\epsilon_{\hat{i}_1 \hat{i}_2 \dots \hat{i}_n}$, because $g_{ij} = g_{ji}$.

$$\text{Thus } \epsilon_{\hat{i}_1 \dots \hat{i}_n} = \text{constant} \cdot \epsilon^{\hat{i}_1 \dots \hat{i}_n}$$

To find the constant choose $\hat{i}_1 \dots \hat{i}_n = 1 2 \dots n$,

$$\epsilon_{1 2 \dots n} = \text{constant} \underbrace{\epsilon^{1 2 \dots n}}_1 = \text{constant}$$

u

$$g_{1 \hat{i}_1} g_{2 \hat{i}_2} \dots g_{n \hat{i}_n} \epsilon^{\hat{i}_1 \hat{i}_2 \dots \hat{i}_n} = \det g_{ij} = g$$

$$\Rightarrow \boxed{\epsilon_{\hat{i}_1 \hat{i}_2 \dots \hat{i}_n} = g \epsilon^{\hat{i}_1 \hat{i}_2 \dots \hat{i}_n}$$

④ Spherical coordinates, are orthogonal so g_{ij} is diagonal.

$$x = r \cos\phi \sin\theta \quad y = r \sin\phi \sin\theta \quad z = r \cos\theta$$

$$h_r^2 = g_{rr} = \left(\frac{\partial x}{\partial r}\right)^2 + \left(\frac{\partial y}{\partial r}\right)^2 + \left(\frac{\partial z}{\partial r}\right)^2 = 1$$

$$h_\theta^2 = g_{\theta\theta} = \left(\frac{\partial x}{\partial \theta}\right)^2 + \left(\frac{\partial y}{\partial \theta}\right)^2 + \left(\frac{\partial z}{\partial \theta}\right)^2 = r^2$$

$$h_\phi^2 = g_{\phi\phi} = \left(\frac{\partial x}{\partial \phi}\right)^2 + \left(\frac{\partial y}{\partial \phi}\right)^2 + \left(\frac{\partial z}{\partial \phi}\right)^2 = r^2 \sin^2\theta$$

Ordinary vectors with components ordered by $\hat{r}, \hat{\theta}, \hat{\phi}$.

gradient components are $\frac{1}{h_i} \frac{\partial}{\partial x^i}$

$$\vec{\nabla} \Phi = \left(\frac{\partial \Phi}{\partial r}, \frac{1}{r} \frac{\partial \Phi}{\partial \theta}, \frac{1}{r \sin\theta} \frac{\partial \Phi}{\partial \phi} \right)$$

divergence $\vec{\nabla} \cdot \vec{V} = \frac{1}{h_1 h_2 h_3} \sum_i \frac{\partial}{\partial x^i} \left(\frac{h_1 h_2 h_3}{h_i} \bar{V}_i \right)$

$$\vec{\nabla} \cdot \vec{V} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \bar{V}_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta \bar{V}_\theta) + \frac{1}{r \sin\theta} \frac{\partial \bar{V}_\phi}{\partial \phi}$$

$$\text{curl} \left(\vec{\nabla} \times \vec{V} \right)_k = \frac{h_k}{h_1 h_2 h_3} \sum_{ij} \epsilon^{ijk} \frac{\partial}{\partial x^j} (h_i \bar{V}_i)$$

$$\vec{\nabla} \times \vec{V} = \left(\frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (\sin \theta \bar{V}_\theta) - \frac{\partial \bar{V}_\phi}{\partial \phi} \right], \right.$$

$$\frac{1}{r \sin \theta} \left[\frac{\partial \bar{V}_r}{\partial \theta} - \sin \theta \frac{\partial}{\partial r} (r \bar{V}_\theta) \right],$$

$$\left. \frac{1}{r} \left[\frac{\partial}{\partial r} (r \bar{V}_\phi) - \frac{\partial \bar{V}_r}{\partial \theta} \right] \right)$$

Laplacian $\nabla^2 \Phi = \frac{1}{h_1 h_2 h_3} \sum_i \frac{\partial}{\partial x^i} \left(\frac{h_1 h_2 h_3}{h_i^2} \frac{\partial \Phi}{\partial x^i} \right)$

$$\nabla^2 \Phi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \Phi}{\partial r} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Phi}{\partial \theta} \right)$$

$$+ \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \Phi}{\partial \phi^2}$$