

HW 8

Math 2243

Linear Algebra and Differential Equations

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1 Problem 7, section 6.2

In Problems 1 through 28, determine whether or not the given matrix A is diagonalizable. If it is, find a diagonalizing matrix P and a diagonal matrix D such that $P^{-1}AP = D$

$$\begin{bmatrix} 6 & -10 \\ 2 & -3 \end{bmatrix}$$

solution The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 6 & -10 \\ 2 & -3 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 6 - \lambda & -10 \\ 2 & -3 - \lambda \end{bmatrix} &= 0 \\ (6 - \lambda)(-3 - \lambda) + 20 &= 0 \\ \lambda^2 - 3\lambda + 2 &= 0 \\ (\lambda - 2)(\lambda - 1) &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. From the above, these are

$$\begin{aligned} \lambda_1 &= 2 \\ \lambda_2 &= 1 \end{aligned}$$

This table summarizes the result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
2	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector.

$\lambda = 1$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned}
 A\vec{v} &= \lambda\vec{v} \\
 A\vec{v} - \lambda\vec{v} &= \vec{0} \\
 (A - \lambda I)\vec{v} &= \vec{0} \\
 \left(\begin{bmatrix} 6 & -10 \\ 2 & -3 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 6 & -10 \\ 2 & -3 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 5 & -10 \\ 2 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned}
 &\left[\begin{array}{cc|c} 5 & -10 & 0 \\ 2 & -4 & 0 \end{array} \right] \\
 R_2 = R_2 - \frac{2R_1}{5} &\implies \left[\begin{array}{cc|c} 5 & -10 & 0 \\ 0 & 0 & 0 \end{array} \right]
 \end{aligned}$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 5 & -10 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables. First row gives $5v_1 = 10t$ or $v_1 = 2t$. Hence the eigenvector for this eigenvalue is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 2t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = t \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$\lambda = 2$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned} A\vec{v} &= \lambda\vec{v} \\ A\vec{v} - \lambda\vec{v} &= \vec{0} \\ (A - \lambda I)\vec{v} &= \vec{0} \\ \left(\begin{bmatrix} 6 & -10 \\ 2 & -3 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \left(\begin{bmatrix} 6 & -10 \\ 2 & -3 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \begin{bmatrix} 4 & -10 \\ 2 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned} &\left[\begin{array}{cc|c} 4 & -10 & 0 \\ 2 & -5 & 0 \end{array} \right] \\ R_2 = R_2 - \frac{R_1}{2} &\implies \left[\begin{array}{cc|c} 4 & -10 & 0 \\ 0 & 0 & 0 \end{array} \right] \end{aligned}$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 4 & -10 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables. First row gives $4v_1 = 10v_2$ or $v_1 = \frac{5t}{2}$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{5t}{2} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = t \begin{bmatrix} \frac{5}{2} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{5}{2} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$$

The following table summarizes the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
1	1	1	No	$\begin{bmatrix} 2 \\ 1 \end{bmatrix}$
2	1	1	No	$\begin{bmatrix} 5 \\ 2 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$P = \begin{bmatrix} 2 & 5 \\ 1 & 2 \end{bmatrix}$$

Therefore

$$A = PDP^{-1}$$

$$\begin{bmatrix} 6 & -10 \\ 2 & -3 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 2 & 5 \\ 1 & 2 \end{bmatrix}^{-1}$$

2 Problem 15 section 6.2

In Problems 1 through 28, determine whether or not the given matrix A is diagonalizable. If it is, find a diagonalizing matrix P and a diagonal matrix D such that $P^{-1}AP = D$

$$\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

Solution

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 3 - \lambda & -3 & 1 \\ 2 & -2 - \lambda & 1 \\ 0 & 0 & 1 - \lambda \end{bmatrix} &= 0 \end{aligned}$$

Expanding along last row gives

$$\begin{aligned} (-1)^{3+3}(1 - \lambda) \begin{vmatrix} 3 - \lambda & -3 \\ 2 & -2 - \lambda \end{vmatrix} &= 0 \\ (1 - \lambda)((3 - \lambda)(-2 - \lambda) + 6) &= 0 \\ (1 - \lambda)(\lambda^2 - \lambda) &= 0 \\ (1 - \lambda)\lambda(\lambda - 1) &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. These are seen to be

$$\begin{aligned} \lambda_1 &= 0 \\ \lambda_2 &= 1 \\ \lambda_3 &= 1 \end{aligned}$$

This table summarizes the result

eigenvalue	algebraic multiplicity	type of eigenvalue
0	1	real eigenvalue
1	2	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector.

$$\underline{\lambda = 0}$$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned} A\vec{v} &= \lambda\vec{v} \\ A\vec{v} - \lambda\vec{v} &= \vec{0} \\ (A - \lambda I)\vec{v} &= \vec{0} \end{aligned}$$

$$\left(\left(\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} - (0) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\left(\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 3 & -3 & 1 & 0 \\ 2 & -2 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{2R_1}{3} \implies \left[\begin{array}{ccc|c} 3 & -3 & 1 & 0 \\ 0 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

$$R_3 = R_3 - 3R_2 \implies \left[\begin{array}{ccc|c} 3 & -3 & 1 & 0 \\ 0 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3 & -3 & 1 \\ 0 & 0 & \frac{1}{3} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1, v_3\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables. Second row gives $v_3 = 0$. First row gives $3v_1 - 3v_2 = 0$ or $v_1 = t$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} t \\ t \\ 0 \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$\lambda = 1$

We need now to determine the eigenvector \vec{v} where

$$A\vec{v} = \lambda\vec{v}$$

$$A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\left(\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -3 & 1 \\ 2 & -3 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 2 & -3 & 1 & 0 \\ 2 & -3 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{ccc|c} 2 & -3 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 2 & -3 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2, v_3\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Let $v_3 = s$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables. First row gives $2v_1 - 3v_2 + v_3 = 0$ or $v_1 = \frac{3t}{2} - \frac{s}{2}$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} \frac{3t}{2} - \frac{s}{2} \\ t \\ s \end{bmatrix}$$

Since there are two free Variable, we have found two eigenvectors associated with this eigenvalue. The above can be written as

$$\begin{aligned} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} \frac{3t}{2} \\ t \\ 0 \end{bmatrix} + \begin{bmatrix} -\frac{s}{2} \\ 0 \\ s \end{bmatrix} \\ &= t \begin{bmatrix} \frac{3}{2} \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

By letting $t = 1$ and $s = 1$ then the above becomes

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} \frac{3}{2} \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix}$$

Hence the two eigenvectors associated with this eigenvalue are

$$\left(\left(\begin{bmatrix} \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix} \right) \right)$$

Which can be normalized to

$$\left(\left(\begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} \right) \right)$$

The following table summarizes the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
0	1	1	No	$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$
1	2	2	No	$\begin{bmatrix} 3 & -1 \\ 2 & 0 \\ 0 & 2 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvalues found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 3 & -1 \\ 1 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 3 & -1 \\ 1 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & -1 \\ 1 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}^{-1}$$

3 Problem 19 section 6.2

In Problems 1 through 28, determine whether or not the given matrix A is diagonalizable. If it is, find a diagonalizing matrix P and a diagonal matrix D such that $P^{-1}AP = D$

$$\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix}$$

Solution

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 1-\lambda & 1 & -1 \\ -2 & 4-\lambda & -1 \\ -4 & 4 & 1-\lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 6\lambda^2 - 11\lambda + 6 &= 0 \end{aligned}$$

Expanding along first row gives

$$\begin{aligned} (1-\lambda)\begin{vmatrix} 4-\lambda & -1 \\ 4 & 1-\lambda \end{vmatrix} - \begin{vmatrix} -2 & -1 \\ -4 & 1-\lambda \end{vmatrix} - \begin{vmatrix} -2 & 4-\lambda \\ -4 & 4 \end{vmatrix} &= 0 \\ (1-\lambda)((4-\lambda)(1-\lambda) + 4) - (-2(1-\lambda) - 4) - (-8 + 4(4-\lambda)) &= 0 \\ -\lambda^3 + 6\lambda^2 - 13\lambda + 8 - (2\lambda - 6) - (8 - 4\lambda) &= 0 \\ -\lambda^3 + 6\lambda^2 - 11\lambda + 6 &= 0 \\ \lambda^3 - 6\lambda^2 + 11\lambda - 6 &= 0 \end{aligned}$$

Trying $\lambda = 1$

$$\begin{aligned} 1^3 - 6 + 11 - 6 &= 0 \\ 0 &= 0 \end{aligned}$$

Hence $(\lambda - 1)$ is a factor. Doing long division $\frac{\lambda^3 - 6\lambda^2 + 11\lambda - 6}{(\lambda - 1)} = \lambda^2 - 5\lambda + 6$. This can be factored as $(\lambda - 2)(\lambda - 3)$. Therefore

$$\lambda^3 - 6\lambda^2 + 11\lambda - 6 = (\lambda - 1)(\lambda - 2)(\lambda - 3)$$

Hence the eigenvalues are

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 3$$

This table summarizes the result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
2	1	real eigenvalue
3	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector.

$$\underline{\lambda = 1}$$

We need now to determine the eigenvector \vec{v} where

$$A\vec{v} = \lambda\vec{v}$$

$$A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & -1 \\ -2 & 3 & -1 \\ -4 & 4 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 1 & -1 & 0 \\ -2 & 3 & -1 & 0 \\ -4 & 4 & 0 & 0 \end{array} \right]$$

current pivot $A(1,1)$ is zero. Hence we need to replace current pivot row with one non-zero. Replacing row 1 with row 2 gives

$$\left[\begin{array}{ccc|c} -2 & 3 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ -4 & 4 & 0 & 0 \end{array} \right]$$

$$R_3 = R_3 - 2R_1 \implies \left[\begin{array}{ccc|c} -2 & 3 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -2 & 2 & 0 \end{array} \right]$$

$$R_3 = R_3 + 2R_2 \implies \left[\begin{array}{ccc|c} -2 & 3 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -2 & 3 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables. Second row gives $v_2 = v_3 = t$. First row gives $-2v_1 + 3v_2 - v_3 = 0$ or $-2v_1 = -3t + t = -2t$. Hence $v_1 = t$. Therefore the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$\lambda = 2$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned}
 A\vec{v} &= \lambda\vec{v} \\
 A\vec{v} - \lambda\vec{v} &= \vec{0} \\
 (A - \lambda I)\vec{v} &= \vec{0} \\
 \left(\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} -1 & 1 & -1 \\ -2 & 2 & -1 \\ -4 & 4 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned}
 &\left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ -2 & 2 & -1 & 0 \\ -4 & 4 & -1 & 0 \end{array} \right] \\
 R_2 = R_2 - 2R_1 &\Rightarrow \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ -4 & 4 & -1 & 0 \end{array} \right] \\
 R_3 = R_3 - 4R_1 &\Rightarrow \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 3 & 0 \end{array} \right] \\
 R_3 = R_3 - 3R_2 &\Rightarrow \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]
 \end{aligned}$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1, v_3\}$. Let $v_2 = t$. Third row gives

$v_3 = 0$. First row gives $-v_1 + v_2 = 0$ or $v_1 = t$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} t \\ t \\ 0 \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$\lambda = 3$

We need now to determine the eigenvector \vec{v} where

$$A\vec{v} = \lambda\vec{v}$$

$$A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} - \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 1 & -1 \\ -2 & 1 & -1 \\ -4 & 4 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -2 & 1 & -1 & 0 \\ -2 & 1 & -1 & 0 \\ -4 & 4 & -2 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{ccc|c} -2 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -4 & 4 & -2 & 0 \end{array} \right]$$

$$R_3 = R_3 - 2R_1 \implies \left[\begin{array}{ccc|c} -2 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \end{array} \right]$$

current pivot $A(2,2)$ is zero. Hence we need to replace current pivot row with one non-zero. Replacing row 2 with row 3 gives

$$\left[\begin{array}{ccc|c} -2 & 1 & -1 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -2 & 1 & -1 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables. Second row gives $v_2 = 0$. First row gives $-2v_1 = v_3 = t$. Hence $v_1 = -\frac{t}{2}$. Therefore

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} -\frac{t}{2} \\ 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$$

The following table summarizes the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
1	1	1	No	$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$
2	1	1	No	$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$
3	1	1	No	$\begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 1 & -1 \\ -2 & 4 & -1 \\ -4 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix}^{-1}$$

4 Problem 7 section 6.3

In Problems 1 through 10, a matrix A is given. Use the method of Example 1 to compute A^5 .

$$\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

Solution

If A is diagonalizable, then by first writing $A = PDP^{-1}$ then $A^5 = PD^5P^{-1}$. And since D is diagonal matrix, it is easy to raise it to power. So the first step is to diagonalize A as we did in the above problems.

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 1 - \lambda & 3 & 0 \\ 0 & 2 - \lambda & 0 \\ 0 & 0 & 2 - \lambda \end{bmatrix} &= 0 \end{aligned}$$

Expansion along the first column gives

$$\begin{aligned} (1 - \lambda) \begin{vmatrix} 2 - \lambda & 0 \\ 0 & 2 - \lambda \end{vmatrix} &= 0 \\ (1 - \lambda)(2 - \lambda)(2 - \lambda) &= 0 \end{aligned}$$

Therefore the eigenvalues are

$$\begin{aligned} \lambda_1 &= 1 \\ \lambda_2 &= 2 \\ \lambda_3 &= 2 \end{aligned}$$

This table summarizes the result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
2	2	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector.

$\lambda = 1$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned}
 A\vec{v} &= \lambda\vec{v} \\
 A\vec{v} - \lambda\vec{v} &= \vec{0} \\
 (A - \lambda I)\vec{v} &= \vec{0} \\
 \left(\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 0 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned}
 &\left[\begin{array}{ccc|c} 0 & 3 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \\
 R_2 = R_2 - \frac{R_1}{3} &\implies \left[\begin{array}{ccc|c} 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]
 \end{aligned}$$

current pivot $A(2,3)$ is zero. Hence we need to replace current pivot row with one non-zero. Replacing row 2 with row 3 gives

$$\left[\begin{array}{ccc|c} 0 & 3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 0 & 3 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_1\}$ and the leading variables are $\{v_2, v_3\}$. Let $v_1 = t$. Now we start back substitution. Second row gives $v_3 = 0$. First row also gives $v_2 = 0$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} t \\ 0 \\ 0 \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\underline{\lambda = 2}$$

We need now to determine the eigenvector \vec{v} where

$$A\vec{v} = \lambda\vec{v}$$

$$A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\left(\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 3 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 & 3 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2, v_3\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Let $v_3 = s$. Now we start back substitution. First row gives $-v_1 = -3v_2 = -3t$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 3t \\ t \\ s \end{bmatrix}$$

Since there are two free Variable, we have found two eigenvectors associated with this eigenvalue. The above can be written as

$$\begin{aligned} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 3t \\ t \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ s \end{bmatrix} \\ &= t \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

By letting $t = 1$ and $s = 1$ then the above becomes

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Hence the two eigenvectors associated with this eigenvalue are

$$\left(\begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right)$$

The following table summarizes the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
1	1	1	No	$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
2	2	2	No	$\begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1}$$

Now that we have diagonalized A , we can finally answer the question.

$$\begin{aligned} \begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}^5 &= \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}^5 \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2^5 & 0 \\ 0 & 0 & 2^5 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 32 & 0 \\ 0 & 0 & 32 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \end{aligned}$$

But

$$\begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 32 & 0 \\ 0 & 0 & 32 \end{bmatrix} = \begin{bmatrix} 1 & 96 & 0 \\ 0 & 32 & 0 \\ 0 & 0 & 32 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}^5 = \begin{bmatrix} 1 & 96 & 0 \\ 0 & 32 & 0 \\ 0 & 0 & 32 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \tag{1}$$

We know need to find $\begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1}$. The augmented matrix is

$$\begin{bmatrix} 1 & 3 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$R_1 \rightarrow R_1 - 3R_2$$

$$\begin{bmatrix} 1 & 0 & 0 & 1 & -3 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

Since left half is now I then the right half is the inverse. Therefore $\begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

Hence (1) becomes

$$\begin{aligned} \begin{bmatrix} 1 & 3 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}^5 &= \begin{bmatrix} 1 & 96 & 0 \\ 0 & 32 & 0 \\ 0 & 0 & 32 \end{bmatrix} \begin{bmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 93 & 0 \\ 0 & 32 & 0 \\ 0 & 0 & 32 \end{bmatrix} \end{aligned}$$

5 Problem 13 section 6.3

Find A^{10} .

$$\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix}$$

Solution

If A is diagonalizable, then by first writing $A = PDP^{-1}$ then $A^{10} = PD^{10}P^{-1}$. And since D is diagonal matrix, it is easy to raise it to power. So the first step is to diagonalize A as we did in the above problems.

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 1 - \lambda & -1 & 1 \\ 2 & -2 - \lambda & 1 \\ 4 & -4 & 1 - \lambda \end{bmatrix} &= 0 \\ (1 - \lambda) \begin{vmatrix} -2 - \lambda & 1 \\ -4 & 1 - \lambda \end{vmatrix} + \begin{vmatrix} 2 & 1 \\ 4 & 1 - \lambda \end{vmatrix} + \begin{vmatrix} 2 & -2 - \lambda \\ 4 & -4 \end{vmatrix} &= 0 \\ (1 - \lambda)((-2 - \lambda)(1 - \lambda) + 4) + 2(1 - \lambda) - 4 + (-8) - 4(-2 - \lambda) &= 0 \\ -\lambda^3 - \lambda + 2 - 2\lambda - 2 + 4\lambda &= \\ \lambda - \lambda^3 &= 0 \\ \lambda(1 - \lambda^2) &= 0 \end{aligned}$$

Therefore the eigenvalues are

$$\begin{aligned} \lambda_1 &= 0 \\ \lambda_2 &= 1 \\ \lambda_3 &= -1 \end{aligned}$$

This table summarizes the result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
0	1	real eigenvalue
1	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector.

$\lambda = -1$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned}
 A\vec{v} &= \lambda\vec{v} \\
 A\vec{v} - \lambda\vec{v} &= \vec{0} \\
 (A - \lambda I)\vec{v} &= \vec{0} \\
 \left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} - \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 2 & -1 & 1 \\ 2 & -1 & 1 \\ 4 & -4 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned}
 &\left[\begin{array}{ccc|c} 2 & -1 & 1 & 0 \\ 2 & -1 & 1 & 0 \\ 4 & -4 & 2 & 0 \end{array} \right] \\
 R_2 = R_2 - R_1 &\implies \left[\begin{array}{ccc|c} 2 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 4 & -4 & 2 & 0 \end{array} \right] \\
 R_3 = R_3 - 2R_1 &\implies \left[\begin{array}{ccc|c} 2 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \end{array} \right]
 \end{aligned}$$

current pivot $A(2,2)$ is zero. Hence we need to replace current pivot row with one non-zero. Replacing row 2 with row 3 gives

$$\left[\begin{array}{ccc|c} 2 & -1 & 1 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 2 & -1 & 1 \\ 0 & -2 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Second row gives $v_2 = 0$. First row gives $2v_1 + t = 0$ or $v_1 = -\frac{t}{2}$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} -\frac{t}{2} \\ 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$$

$\lambda = 0$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned}
 A\vec{v} &= \lambda\vec{v} \\
 A\vec{v} - \lambda\vec{v} &= \vec{0} \\
 (A - \lambda I)\vec{v} &= \vec{0} \\
 \left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} - (0) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned}
 &\left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 2 & -2 & 1 & 0 \\ 4 & -4 & 1 & 0 \end{array} \right] \\
 R_2 = R_2 - 2R_1 &\Rightarrow \left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 4 & -4 & 1 & 0 \end{array} \right] \\
 R_3 = R_3 - 4R_1 &\Rightarrow \left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & -3 & 0 \end{array} \right] \\
 R_3 = R_3 - 3R_2 &\Rightarrow \left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]
 \end{aligned}$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1, v_3\}$. Let $v_2 = t$. Now we start back substitution. Second row gives $v_3 = 0$. First row give $v_1 - t = 0$ or $v_1 = t$. Hence the

solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} t \\ t \\ 0 \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$\lambda = 1$

We need now to determine the eigenvector \vec{v} where

$$A\vec{v} = \lambda\vec{v}$$

$$A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & -1 & 1 \\ 2 & -3 & 1 \\ 4 & -4 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & -1 & 1 & 0 \\ 2 & -3 & 1 & 0 \\ 4 & -4 & 0 & 0 \end{array} \right]$$

current pivot $A(1,1)$ is zero. Hence we need to replace current pivot row with one non-zero. Replacing row 1 with row 2 gives

$$\left[\begin{array}{ccc|c} 2 & -3 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 4 & -4 & 0 & 0 \end{array} \right]$$

$$R_3 = R_3 - 2R_1 \implies \left[\begin{array}{ccc|c} 2 & -3 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 2 & -2 & 0 \end{array} \right]$$

$$R_3 = R_3 + 2R_2 \implies \left[\begin{array}{ccc|c} 2 & -3 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} 2 & -3 & 1 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. From second row $-v_2 + t = 0$ or $v_2 = t$. First row gives $2v_1 - 3v_2 + t = 0$ or $2v_1 = 3v_2 - t$ or $v_1 = \frac{3t-t}{2} = t$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

The following table summarizes the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-1	1	1	No	$\begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$
0	1	1	No	$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$
1	1	1	No	$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix}^{-1}$$

Now that we have diagonalized A , we can finally answer the question.

$$\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix}^{10} = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}^{10} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix}^{-1}$$

But $\begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & 0 \\ 1 & 2 & 0 \end{bmatrix}$. The above becomes

$$\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix}^{10} = \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & 0 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{bmatrix}^{-1} \quad (1)$$

We now just need to find P^{-1} . Augmented matrix is

$$\begin{bmatrix} 1 & -1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 2 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - R_1$$

$$\begin{bmatrix} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 1 & 0 \\ 1 & 2 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_1$$

$$\begin{bmatrix} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 1 & 0 \\ 0 & 3 & -1 & -1 & 0 & 1 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - 3R_2$$

$$\begin{bmatrix} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 2 & -3 & 1 \end{bmatrix}$$

Now we start the reduced Echelon phase.

$$R_3 \rightarrow -R_3$$

$$\begin{bmatrix} 1 & -1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & -2 & 3 & -1 \end{bmatrix}$$

$$R_1 \rightarrow R_1 - R_3$$

$$\begin{bmatrix} 1 & -1 & 0 & 3 & -3 & 1 \\ 0 & 1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & -2 & 3 & -1 \end{bmatrix}$$

$$R_1 \rightarrow R_1 + R_2$$

$$\begin{bmatrix} 1 & 0 & 0 & 2 & -2 & 1 \\ 0 & 1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & -2 & 3 & -1 \end{bmatrix}$$

Since left half is now I then the inverse is the right half of the above augmented matrix.
Hence

$$P^{-1} = \begin{bmatrix} 2 & -2 & 1 \\ -1 & 1 & 0 \\ -2 & 3 & -1 \end{bmatrix}$$

Substituting the above in (1) gives

$$\begin{aligned} \begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 1 \\ 4 & -4 & 1 \end{bmatrix}^{10} &= \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & 0 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 2 & -2 & 1 \\ -1 & 1 & 0 \\ -2 & 3 & -1 \end{bmatrix} \\ &= \begin{bmatrix} 3 & -3 & 1 \\ 2 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

6 Problem 25 section 6.3

In Problems 25 through 30, a city-suburban population transition matrix A (as in Example 2) is given. Find the resulting long-term distribution of a constant total population between the city and its suburbs.

$$A = \begin{bmatrix} 0.9 & 0.1 \\ 0.1 & 0.9 \end{bmatrix}$$

Solution

The first step is diagonalize $A = PDP^{-1}$ and then evaluate A^k in the limit as $k \rightarrow \infty$. Writing A as

$$A = \begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} \frac{9}{10} - \lambda & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} - \lambda \end{bmatrix} &= 0 \\ \left(\frac{9}{10} - \lambda\right)\left(\frac{9}{10} - \lambda\right) - \frac{1}{100} &= 0 \\ \frac{1}{100}(10\lambda - 9)^2 - \frac{1}{100} &= 0 \\ \frac{1}{100}((10\lambda - 9)^2 - 1) &= 0 \\ (10\lambda - 9)^2 - 1 &= 0 \\ 100\lambda^2 - 180\lambda + 80 &= 0 \\ \lambda^2 - \frac{18}{10}\lambda + \frac{8}{10} &= 0 \\ (\lambda - 1)\left(\lambda - \frac{8}{10}\right) &= 0 \end{aligned}$$

Hence the eigenvalues are

$$\begin{aligned} \lambda_1 &= 1 \\ \lambda_2 &= \frac{4}{5} \end{aligned}$$

This table summarizes the result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
$\frac{4}{5}$	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector.

$$\underline{\lambda = 1}$$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned} A\vec{v} &= \lambda\vec{v} \\ A\vec{v} - \lambda\vec{v} &= \vec{0} \\ (A - \lambda I)\vec{v} &= \vec{0} \\ \left(\begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \left(\begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \begin{bmatrix} -\frac{1}{10} & \frac{1}{10} \\ \frac{1}{10} & -\frac{1}{10} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned} &\left[\begin{array}{cc|c} -\frac{1}{10} & \frac{1}{10} & 0 \\ \frac{1}{10} & -\frac{1}{10} & 0 \end{array} \right] \\ R_2 = R_2 + R_1 &\implies \left[\begin{array}{cc|c} -\frac{1}{10} & \frac{1}{10} & 0 \\ 0 & 0 & 0 \end{array} \right] \end{aligned}$$

Therefore the system in Echelon form is

$$\left[\begin{array}{cc|c} -\frac{1}{10} & \frac{1}{10} & 0 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. First row gives $v_1 = t$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\underline{\lambda = \frac{4}{5}}$$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned} A\vec{v} &= \lambda\vec{v} \\ A\vec{v} - \lambda\vec{v} &= \vec{0} \\ (A - \lambda I)\vec{v} &= \vec{0} \\ \left(\begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix} - \left(\frac{4}{5}\right) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \left(\begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix} - \begin{bmatrix} \frac{4}{5} & 0 \\ 0 & \frac{4}{5} \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \begin{bmatrix} \frac{1}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{1}{10} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned} &\left[\begin{array}{cc|c} \frac{1}{10} & \frac{1}{10} & 0 \\ \frac{1}{10} & \frac{1}{10} & 0 \end{array} \right] \\ R_2 = R_2 - R_1 &\implies \left[\begin{array}{cc|c} \frac{1}{10} & \frac{1}{10} & 0 \\ 0 & 0 & 0 \end{array} \right] \end{aligned}$$

Therefore the system in Echelon form is

$$\begin{bmatrix} \frac{1}{10} & \frac{1}{10} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. First row gives $v_1 = -t$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

The following table summarizes the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
1	1	1	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$
$\frac{4}{5}$	1	1	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 1 & 0 \\ 0 & \frac{4}{5} \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \frac{4}{5} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1}$$

And

$$\begin{aligned} \begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix}^k &= \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \frac{4}{5} \end{bmatrix}^k \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \left(\frac{4}{5}\right)^k \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} \end{aligned}$$

As $k \rightarrow \infty$ the term $\left(\frac{4}{5}\right)^k \rightarrow 0$. Hence in the limit the above becomes

$$\begin{aligned} \lim_{k \rightarrow \infty} \begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix}^k &= \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} \end{aligned}$$

But $\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{-1} = \frac{1}{\det \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^T = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$. The above becomes

$$\begin{aligned} \lim_{k \rightarrow \infty} \begin{bmatrix} \frac{9}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{9}{10} \end{bmatrix}^k &= \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \end{aligned}$$

Therefore

$$\begin{aligned} \vec{x}_k &= A^k \vec{x}_0 \\ \lim_{k \rightarrow \infty} \vec{x}_k &= \lim_{k \rightarrow \infty} A^k \vec{x}_0 \\ &= \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} C_0 \\ S_0 \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{2}C_0 + \frac{1}{2}S_0 \\ \frac{1}{2}C_0 + \frac{1}{2}S_0 \end{bmatrix} \\ &= (C_0 + S_0) \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} \end{aligned}$$

This means in long term each city will have half of the initial total population.

7 Additional problem 1

Solution

7.1 Part (a)

To show A is similar to itself, we need to show there exist P , such that $A = PAP^{-1}$, where P is matrix whose columns are linearly independent and hence invertible. Let $P = I$ (the identity matrix of same size as A). Hence $A = IAI^{-1}$. Since (a) I has linearly independent columns (basis vectors) and (b) I is clearly invertible and (c) $A = IAI^{-1}$ is true: Post multiplying both sides by I gives $AI^{-1} = IA$. But $AI^{-1} = AI$ and $IA = AI$ which means $AI = AI$ or $A = A$ which is true.

7.2 Part (b)

We are given that

$$A = PBP^{-1} \tag{1}$$

We need to show that $B = PAP^{-1}$. Starting with (1) given relation, and post multiplying both sides by P gives

$$\begin{aligned} AP &= PBP^{-1}P \\ AP &= PB \end{aligned}$$

Since $P^{-1}P = I$, pre multiplying both sides by P^{-1} gives

$$\begin{aligned} P^{-1}AP &= B \\ P^{-1}AP &= B \end{aligned}$$

Let $P^{-1} = Q$. Then the above can also be written as

$$B = QAQ^{-1}$$

Hence B is similar to A .

7.3 Part (c)

We are given that

$$A = PBP^{-1} \tag{1}$$

And that

$$B = QCQ^{-1} \tag{2}$$

We need to show that $A = VCV^{-1}$ for some invertible matrix V . Substituting (2) into (1) gives

$$\begin{aligned} A &= P(QCQ^{-1})P^{-1} \\ &= (PQ)C(Q^{-1}P^{-1}) \end{aligned}$$

But $Q^{-1}P^{-1} = (PQ)^{-1}$. The above becomes

$$A = (PQ)C(QP)^{-1}$$

Let $PQ = V$. The above becomes

$$A = VCV^{-1}$$

Hence A is similar to C .

8 Additional problem 2

Solution

$$\begin{aligned}\vec{x}_n &= A^n \vec{x}_0 \\ &= \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n \begin{bmatrix} 1 \\ 0 \end{bmatrix}\end{aligned}$$

8.1 Part (a)

To find eigenvalues and eigenvectors of A .

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned}\det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 1 - \lambda & 1 \\ 1 & -\lambda \end{bmatrix} &= 0 \\ \lambda^2 - \lambda - 1 &= 0\end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Using the quadratic formula $\lambda = \frac{-b}{2a} \pm \frac{1}{2a} \sqrt{b^2 - 4ac} = \frac{1}{2} \pm \frac{1}{2} \sqrt{(-1)^2 - 4(-1)} = \frac{1}{2} \pm \frac{1}{2} \sqrt{1 + 4} = \frac{1}{2} \pm \frac{1}{2} \sqrt{5}$. Hence

$$\begin{aligned}\lambda_1 &= \frac{1}{2} + \frac{\sqrt{5}}{2} \\ \lambda_2 &= \frac{1}{2} - \frac{\sqrt{5}}{2}\end{aligned}$$

This table summarizes the result

eigenvalue	algebraic multiplicity	type of eigenvalue
$\frac{1}{2} + \frac{\sqrt{5}}{2}$	1	real eigenvalue
$\frac{1}{2} - \frac{\sqrt{5}}{2}$	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector.

$$\lambda = \frac{1}{2} + \frac{\sqrt{5}}{2}$$

We need now to determine the eigenvector \vec{v} where

$$\begin{aligned} A\vec{v} &= \lambda\vec{v} \\ A\vec{v} - \lambda\vec{v} &= \vec{0} \\ (A - \lambda I)\vec{v} &= \vec{0} \\ \left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} - \left(\frac{1}{2} + \frac{\sqrt{5}}{2} \right) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} & 0 \\ 0 & \frac{1}{2} + \frac{\sqrt{5}}{2} \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \begin{bmatrix} \frac{1}{2} - \frac{\sqrt{5}}{2} & 1 \\ 1 & -\frac{1}{2} - \frac{\sqrt{5}}{2} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned} &\left[\begin{array}{cc|c} \frac{1}{2} - \frac{\sqrt{5}}{2} & 1 & 0 \\ 1 & -\frac{1}{2} - \frac{\sqrt{5}}{2} & 0 \end{array} \right] \\ R_2 &= R_2 - \frac{R_1}{\frac{1}{2} - \frac{\sqrt{5}}{2}} \implies \left[\begin{array}{cc|c} \frac{1}{2} - \frac{\sqrt{5}}{2} & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] \end{aligned}$$

Therefore the system in Echelon form is

$$\left[\begin{array}{cc|c} \frac{1}{2} - \frac{\sqrt{5}}{2} & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. First row gives $\left(\frac{1}{2} - \frac{\sqrt{5}}{2}\right)v_1 = -t$. Hence $\frac{1-\sqrt{5}}{2}v_1 = -t$. or $v_1 = \frac{-2}{1-\sqrt{5}}t$ or $v_1 = \frac{2}{\sqrt{5}-1}t$.

Or $v_1 = \frac{2(\sqrt{5}+1)}{(\sqrt{5}-1)(\sqrt{5}+1)}t = \frac{2(\sqrt{5}+1)}{4}t = \frac{\sqrt{5}+1}{2}t$. Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{5}+1}{2}t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = t \begin{bmatrix} \frac{\sqrt{5}+1}{2} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{5}+1}{2} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \sqrt{5} + 1 \\ 1 \end{bmatrix}$$

$$\lambda = \frac{1}{2} - \frac{\sqrt{5}}{2}$$

We need now to determine the eigenvector \vec{v} where

$$A\vec{v} = \lambda\vec{v}$$

$$A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

$$\begin{aligned} & \left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} - \left(\frac{1}{2} - \frac{\sqrt{5}}{2} \right) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ & \left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} \frac{1}{2} - \frac{\sqrt{5}}{2} & 0 \\ 0 & \frac{1}{2} - \frac{\sqrt{5}}{2} \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ & \begin{bmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} & 1 \\ 1 & \frac{\sqrt{5}}{2} - \frac{1}{2} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{aligned} & \left[\begin{array}{cc|c} \frac{1}{2} + \frac{\sqrt{5}}{2} & 1 & 0 \\ 1 & \frac{\sqrt{5}}{2} - \frac{1}{2} & 0 \end{array} \right] \\ R_2 = R_2 - \frac{R_1}{\frac{1}{2} + \frac{\sqrt{5}}{2}} & \implies \left[\begin{array}{cc|c} \frac{1}{2} + \frac{\sqrt{5}}{2} & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] \end{aligned}$$

Therefore the system in Echelon form is

$$\begin{bmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. First row gives $\left(\frac{1+\sqrt{5}}{2}\right)v_1 = -t$ or $v_1 = \frac{-2}{1+\sqrt{5}}t = \frac{-2(1-\sqrt{5})}{(1+\sqrt{5})(1-\sqrt{5})}t$ which simplifies to $v_1 = \frac{-2(1-\sqrt{5})t}{-4} = \frac{(1-\sqrt{5})t}{2}$ Hence the solution is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{(1-\sqrt{5})t}{2} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = t \begin{bmatrix} \frac{(1-\sqrt{5})}{2} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{(1-\sqrt{5})}{2} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 1 - \sqrt{5} \\ 2 \end{bmatrix}$$

The following table summarizes the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
$\frac{1+\sqrt{5}}{2}$	1	1	No	$\begin{bmatrix} 1 + \sqrt{5} \\ 2 \end{bmatrix}$
$\frac{1-\sqrt{5}}{2}$	1	1	No	$\begin{bmatrix} 1 - \sqrt{5} \\ 2 \end{bmatrix}$

8.2 Part(b)

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} \frac{1+\sqrt{5}}{2} & 0 \\ 0 & \frac{1-\sqrt{5}}{2} \end{bmatrix}$$

$$P = \begin{bmatrix} 1 + \sqrt{5} & 1 - \sqrt{5} \\ 2 & 2 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 + \sqrt{5} & 1 - \sqrt{5} \\ 2 & 2 \end{bmatrix} \begin{bmatrix} \frac{1+\sqrt{5}}{2} & 0 \\ 0 & \frac{1-\sqrt{5}}{2} \end{bmatrix} \begin{bmatrix} 1 + \sqrt{5} & 1 - \sqrt{5} \\ 2 & 2 \end{bmatrix}^{-1}$$

And now we can write

$$\begin{aligned} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n &= \begin{bmatrix} 1 + \sqrt{5} & 1 - \sqrt{5} \\ 2 & 2 \end{bmatrix} \left[\begin{bmatrix} \frac{1+\sqrt{5}}{2} & 0 \\ 0 & \frac{1-\sqrt{5}}{2} \end{bmatrix} \right]^n \begin{bmatrix} 1 + \sqrt{5} & 1 - \sqrt{5} \\ 2 & 2 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1 + \sqrt{5} & 1 - \sqrt{5} \\ 2 & 2 \end{bmatrix} \left[\begin{bmatrix} \left(\frac{1+\sqrt{5}}{2}\right)^n & 0 \\ 0 & \left(\frac{1-\sqrt{5}}{2}\right)^n \end{bmatrix} \right] \begin{bmatrix} 1 + \sqrt{5} & 1 - \sqrt{5} \\ 2 & 2 \end{bmatrix}^{-1} \end{aligned}$$

Using hint, let $\frac{1+\sqrt{5}}{2} = \varphi \approx 1.61803$ and $\frac{1-\sqrt{5}}{2} = 1 - \varphi \approx -0.61803$. The above becomes

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n = \begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix} \left[\begin{bmatrix} \varphi^n & 0 \\ 0 & (1-\varphi)^n \end{bmatrix} \right] \begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix}^{-1}$$

8.3 Part (c)

Since

$$\begin{aligned} \vec{x}_n &= A^n \vec{x}_0 \\ &= \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n \begin{bmatrix} 1 \\ 0 \end{bmatrix} \end{aligned}$$

Then using result from part b, we can now write

$$\begin{aligned} \vec{x}_n &= A^n \vec{x}_0 \\ &= \overbrace{\begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix} \left[\begin{bmatrix} \varphi^n & 0 \\ 0 & (1-\varphi)^n \end{bmatrix} \right] \begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix}^{-1}}^{A^n} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 2\varphi\varphi^n & 2(1-\varphi)(1-\varphi)^n \\ 2\varphi^n & 2(1-\varphi)^n \end{bmatrix} \begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 2\varphi^{n+1} & 2(1-\varphi)^{n+1} \\ 2\varphi^n & 2(1-\varphi)^n \end{bmatrix} \begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \end{aligned} \tag{1}$$

But

$$\begin{aligned}
\begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix}^{-1} &= \frac{1}{\det \begin{bmatrix} 2\varphi & 2(1-\varphi) \\ 2 & 2 \end{bmatrix}} \begin{bmatrix} 2 & -2(1-\varphi) \\ -2 & 2\varphi \end{bmatrix} \\
&= \frac{1}{4\varphi - 4(1-\varphi)} \begin{bmatrix} 2 & -2(1-\varphi) \\ -2 & 2\varphi \end{bmatrix} \\
&= \frac{1}{8\varphi - 4} \begin{bmatrix} 2 & -2(1-\varphi) \\ -2 & 2\varphi \end{bmatrix} \\
&= \frac{1}{4\varphi - 2} \begin{bmatrix} 1 & \varphi - 1 \\ -1 & \varphi \end{bmatrix}
\end{aligned}$$

Hence (1) becomes

$$\begin{aligned}
\vec{x}_n &= \frac{1}{4\varphi - 2} \begin{bmatrix} 2\varphi^{n+1} & 2(1-\varphi)^{n+1} \\ 2\varphi^n & 2(1-\varphi)^n \end{bmatrix} \begin{bmatrix} 1 & \varphi - 1 \\ -1 & \varphi \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\
&= \frac{1}{4\varphi - 2} \begin{bmatrix} 2\varphi^{n+1} - 2(1-\varphi)^{n+1} & 2\varphi(1-\varphi)^{n+1} - 2\varphi^{n+1} + 2\varphi^{n+2} \\ 2\varphi^n - 2(1-\varphi)^n & 2\varphi(1-\varphi)^n - 2\varphi^n + 2\varphi\varphi^n \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\
&= \frac{1}{4\varphi - 2} \begin{bmatrix} 2\varphi^{n+1} - 2(1-\varphi)^{n+1} \\ 2\varphi^n - 2(1-\varphi)^n \end{bmatrix} \\
&= \frac{1}{2\varphi - 1} \begin{bmatrix} \varphi^{n+1} - (1-\varphi)^{n+1} \\ \varphi^n - (1-\varphi)^n \end{bmatrix}
\end{aligned}$$

But $\vec{x}_n = \begin{bmatrix} f_{n+1} \\ f_n \end{bmatrix}$, hence

$$\begin{aligned}
f_n &= \frac{\varphi^n - (1-\varphi)^n}{2\varphi - 1} \\
&\approx \frac{1.61803^n - (-0.61803)^n}{2(1.61803) - 1} \\
&\approx \frac{1.61803^n - (-0.61803)^n}{2.2361}
\end{aligned}$$

Check: we see from problem statement that $f_0 = 0, f_1 = 1, \dots, f_{12} = 144$. Let us check the formula above for f_{12}

$$\begin{aligned} f_{12} &= \frac{\varphi^{12} - (1 - \varphi)^{12}}{2\varphi - 1} \\ &= \frac{\left(\frac{1+\sqrt{5}}{2}\right)^{12} - \left(1 - \frac{1+\sqrt{5}}{2}\right)^{12}}{2\left(\frac{1+\sqrt{5}}{2}\right) - 1} \\ &= \frac{144\sqrt{5}}{\sqrt{5}} \\ &= 144 \end{aligned}$$

Verified OK.