

HW 9

MATH 121B

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1 Chapter 13, problem 6.1 Mary Boas. Second edition

Chapter 13

6.1

will use

$$z = J_n(k_{mn}r) \cos n\theta \quad \text{or} \quad k_{mn} r^2 t$$

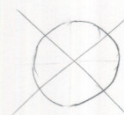
Complete Figure 6.1.

k_{mn} is the m^{th} zero of J_n .

Circle is divided into as many sectors as $2n$. for example, when $n=1$, we will set



when $n=2$, we will set



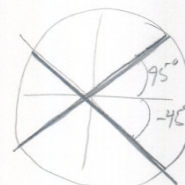
this is because we want a solution

$$\cos n\theta = \pm \frac{\pi}{2}$$

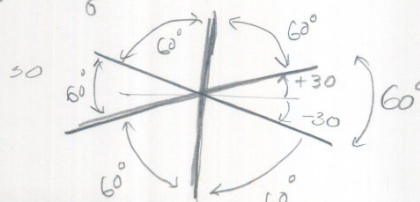
$$\text{which means } \theta = \pm \frac{\pi}{2n}$$

so for $n=1$, $\theta = +\frac{\pi}{2}, -\frac{\pi}{2}$

$n=2$, $2\theta = \pm \frac{\pi}{2}$ or $\theta = \pm \frac{\pi}{4}$



for $n=3$, $3\theta = \pm \frac{\pi}{2}$ or $\theta = \pm \frac{\pi}{6}$



etc..

now, for changing of the m .

$$\text{from } z = J_n(K_m r) \cos n\theta \cos K_m r t$$

we want $J_n(K_m r)$ to zero.

as m increases, $K_{m,2} > K_{m,1}$ when $m_2 > m_1$

so r becomes smaller for each m increasing.

if original radius of drum is 1, then

$$r \text{ for } m=1 \Rightarrow 1$$

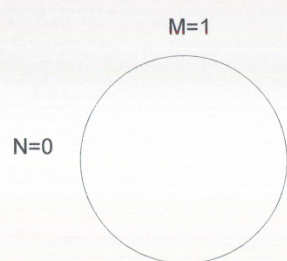
$$r \text{ for } m=2 \Rightarrow \frac{K_{10}}{K_{20}} < 1$$

$$r \text{ for } m=3 \Rightarrow \frac{K_{10}}{K_{30}} < \frac{K_{10}}{K_{20}}$$

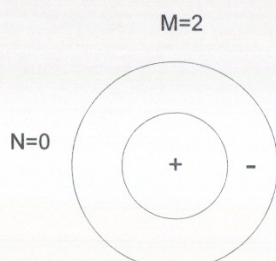
So each time m increases by 1 we add a smaller radius inside. so now I show

the complete figure for $n=0,1,2$, $m=1,2,3$.

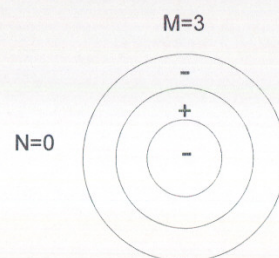
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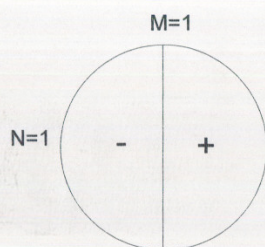
$$z = J_0(k_{10}r) \cos(k_{10}vt)$$



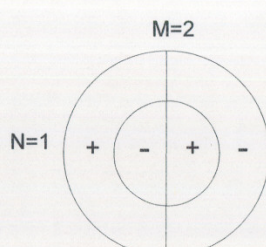
$$z = J_0(k_{20}r) \cos(k_{20}vt)$$



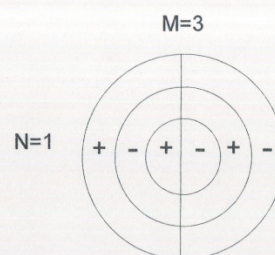
$$z = J_0(k_{30}r) \cos(k_{30}vt)$$



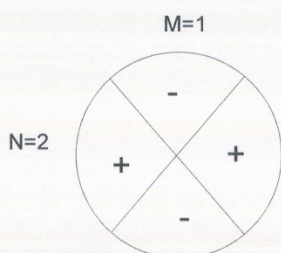
$$z = J_1(k_{11}r) \cos\theta \cos(k_{11}vt)$$



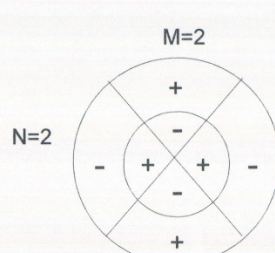
$$z = J_1(k_{21}r) \cos\theta \cos(k_{21}vt)$$



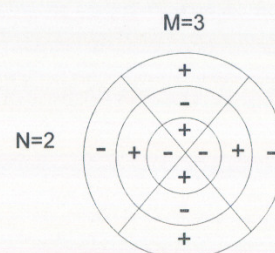
$$z = J_1(k_{31}r) \cos\theta \cos(k_{31}vt)$$



$$z = J_2(k_{12}r) \cos 2\theta \cos(k_{12}vt)$$



$$z = J_2(k_{22}r) \cos 2\theta \cos(k_{22}vt)$$



$$z = J_2(k_{32}r) \cos 2\theta \cos(k_{32}vt)$$

chapter 13, 6.2

look up first 3 zeros of K_{mn} of each Bessel function J_0, J_1, J_2, J_3 . find the first 6 frequencies of a vibrating circular membrane as multiples of fundamental frequency.

Solution

frequency is given by $\omega_{mn} = K_{mn} v$

Fundamental frequency is $\omega_{10} v$.

First zero of J_0

So ratio of frequency ω_{mn} to Fundamental is

$$\frac{\omega_{mn}}{\omega_{10}} = \frac{K_{mn}}{K_{10}}$$

First zero of J_0 .

so
$$\omega_{mn} = \omega_{10} \frac{K_{mn}}{K_{10}}$$

Using this I can find frequencies as multiple of Fundamental freq.

→

First 3 zeros of Bessel functions. using Handbook.

J_0

$$\begin{array}{l} m=1 \rightarrow \underline{\underline{2.4}} \\ m=2 \rightarrow 5.65 \\ m=3 \rightarrow 8.55 \end{array}$$

J_1

$$\begin{array}{l} m=1 \rightarrow 3.75 \\ m=2 \rightarrow 7.25 \\ m=3 \rightarrow 10.05 \end{array}$$

J_2

$$\begin{array}{l} m=1 \rightarrow 5.05 \\ m=2 \rightarrow 8.45 \\ m=3 \rightarrow 11.55 \end{array}$$

J_3

$$\begin{array}{l} m=1 \rightarrow 6.3 \\ m=2 \rightarrow 13.1 \\ m=3 \rightarrow 16.3 \end{array}$$

So now I can find the first 6 frequencies.

First = ω_{10} This is Fundamental Frequency.

$$\text{Second} = \omega_{11} = \omega_{10} \frac{K_{11}}{K_{10}} = \omega_{10} \frac{3.75}{2.4} = \boxed{1.56 \omega_0}$$

$$\text{Third} = \omega_{12} = \omega_{10} \frac{K_{12}}{K_{10}} = \omega_{10} \frac{5.05}{2.4} = \boxed{2.1 \omega_0}$$

$$\text{Fourth} = \omega_{20} = \omega_{10} \frac{K_{20}}{K_{10}} = \omega_{10} \frac{5.65}{2.4} = \boxed{2.35 \omega_0}$$

$$\text{Fifth} = \omega_{21} = \omega_{10} \frac{K_{21}}{K_{10}} = \omega_{10} \frac{7.25}{2.4} = \boxed{3.01 \omega_0}$$

$$\text{Sixth} = \omega_{22} = \omega_{10} \frac{K_{22}}{K_{10}} = \omega_{10} \frac{8.45}{2.4} = \boxed{3.5 \omega_0}$$

2 chapter 13, problem 4.1. Mary Boas, second edition

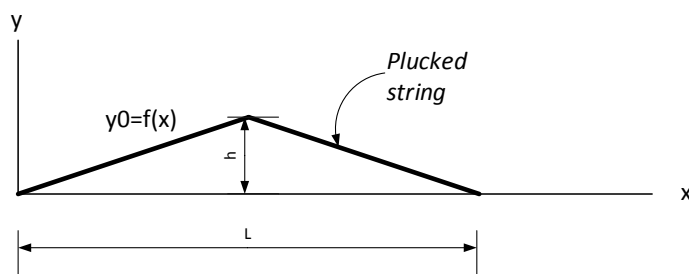
Complete the plucked string problem to get equation 4.0

Solution

Here we start with the solution given in 4.8

$$y_0 = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi x}{L}\right) = f(x) \quad (1)$$

Where $f(x)$ represents the initial position (shape) of the string.



Now need to find b_n

First need to define $f(x)$, from diagram we see that from $x = 0$ to $x = L/2$ the slope is $\frac{h}{L/2} = \frac{2h}{L}$ hence from equation of line we get $y = \frac{2h}{L}x$

From $x = L/2$ to $x = L$, slope is $-\frac{2h}{L}$, so $y = h - \frac{2h}{L}\left(x - \frac{L}{2}\right) = h - \frac{2h}{L}x + h = 2h - \frac{2h}{L}x = 2\left(h - \frac{hx}{L}\right)$

so we have

$$f(x) = \begin{cases} \frac{2h}{L}x & 0 \leq x \leq \frac{L}{2} \\ 2\left(h - \frac{hx}{L}\right) & \frac{L}{2} < x \leq L \end{cases}$$

so from (1) we get, after applying inner product w.r.t. $\sin\left(\frac{n\pi x}{L}\right)$

$$\begin{aligned}
b_n \int_0^L \sin^2\left(\frac{n\pi x}{L}\right) dx &= \int_0^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \int_0^{\frac{L}{2}} f(x) \sin\left(\frac{n\pi x}{L}\right) dx + \int_{\frac{L}{2}}^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \int_0^{\frac{L}{2}} \frac{2h}{L} x \sin\left(\frac{n\pi x}{L}\right) dx + \int_{\frac{L}{2}}^L 2\left(h - \frac{hx}{L}\right) \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \frac{2h}{L} \int_0^{\frac{L}{2}} x \sin\left(\frac{n\pi x}{L}\right) dx + \int_{\frac{L}{2}}^L 2h \sin\left(\frac{n\pi x}{L}\right) dx - \int_{\frac{L}{2}}^L \frac{2hx}{L} \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \frac{2h}{L} \int_0^{\frac{L}{2}} x \sin\left(\frac{n\pi x}{L}\right) dx + 2h \int_{\frac{L}{2}}^L \sin\left(\frac{n\pi x}{L}\right) dx - \frac{2h}{L} \int_{\frac{L}{2}}^L x \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \frac{16 h L \cos\left(\frac{n\pi}{4}\right) \sin\left(\frac{n\pi}{4}\right)^3}{n^2 \pi^2} \\
b_n &= \frac{32 h \cos\left(\frac{n\pi}{4}\right) \sin\left(\frac{n\pi}{4}\right)^3}{n^2 \pi^2}
\end{aligned}$$

so

$$b_n = \frac{32 h L \cos\left(\frac{n\pi}{4}\right) \sin\left(\frac{n\pi}{4}\right)^3}{n^2 \pi^2}$$

Looking at few values of n to see the pattern

$$\begin{aligned}
b_n &= \frac{32 h \cos\left(\frac{\pi}{4}\right) \sin\left(\frac{\pi}{4}\right)^3}{1^2 \pi^2}, \frac{32 h \cos\left(\frac{2\pi}{4}\right) \sin\left(\frac{2\pi}{4}\right)^3}{2^2 \pi^2}, \frac{32 h \cos\left(\frac{3\pi}{4}\right) \sin\left(\frac{3\pi}{4}\right)^3}{3^2 \pi^2}, \dots \\
&= \frac{8h}{\pi^2}, 0, -\frac{8h}{9\pi^2}, 0, \frac{8h}{25\pi^2}, \dots \\
&= \frac{8h}{\pi^2} \left(1, 0, -\frac{1}{9}, 0, \frac{1}{25}, \dots\right)
\end{aligned}$$

Notice that we have terms for only odd n.

Now, substituting the above in the general solution given in equation 4.7 in book, which is

$$y = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi x}{L}\right) \cos\left(\frac{n\pi vt}{L}\right)$$

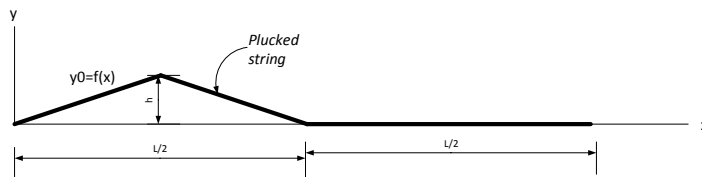
Gives

$$\begin{aligned}
y &= \frac{8h}{\pi^2} \left(\sin\left(\frac{\pi x}{L}\right) \cos\left(\frac{\pi vt}{L}\right) + 0 + -\frac{1}{9} \sin\left(\frac{3\pi x}{L}\right) \cos\left(\frac{3\pi vt}{L}\right) + 0 + \frac{1}{25} \sin\left(\frac{5\pi x}{L}\right) \cos\left(\frac{5\pi vt}{L}\right) + \dots \right) \\
y &= \frac{8h}{\pi^2} \left(\sin\left(\frac{\pi x}{L}\right) \cos\left(\frac{\pi vt}{L}\right) - \frac{1}{9} \sin\left(\frac{3\pi x}{L}\right) \cos\left(\frac{3\pi vt}{L}\right) + \frac{1}{25} \sin\left(\frac{5\pi x}{L}\right) \cos\left(\frac{5\pi vt}{L}\right) + \dots \right)
\end{aligned}$$

The above is the result we are asked to show.

3 chapter 13, problem 4.2. Mary Boas, second edition

A string of length L has zero initial velocity and a displacement $y_0(x)$ as shown. Find the displacement as a function of x and t .



Solution

The PDE that governs this problem is the wave equation $\nabla^2 y = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$

The candidate solutions are

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \\ \cos(kx) \sin(\omega t) \\ \cos(kx) \cos(\omega t) \end{cases}$$

where $\omega = kv$ and $k = \frac{2\pi}{\lambda}$ where λ is the wave length

Now we discard solutions that contains $\cos kx$ since the string is fixed at $x = 0$.

So we are left with

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \end{cases}$$

Now, $y = 0$ at $x = L$ then from $\sin kx = 0$ or $\sin kL = 0$ we need $k = \frac{n\pi}{L}$

Hence solutions become

$$y = \begin{cases} \sin\left(\frac{n\pi}{L}x\right) \sin\left(\frac{n\pi}{L}vt\right) \\ \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi}{L}vt\right) \end{cases}$$

Applying initial conditions, which says that at time $t = 0$, velocity is zero.

Hence from above, after taking $\frac{\partial y}{\partial t}$, we get

$$\frac{\partial y}{\partial t} = \begin{cases} \frac{n\pi v}{L} \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi v}{L}t\right) \\ -\frac{n\pi v}{L} \sin\left(\frac{n\pi}{L}x\right) \sin\left(\frac{n\pi v}{L}t\right) \end{cases}$$

For the above to be zero at $t = 0$ then we discard first solution above with $\cos t$ in it. Hence final general solution is now

$$y = \left\{ \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi}{L}vt\right) \right.$$

A general solution is a linear combination of the above solutions, hence

$$y = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi}{L}vt\right) \quad (1)$$

To find b_n , we apply the second initial condition, which is $y = y_0 = f(x)$

(Notice that we use two initial conditions, i.e. at time $t=0$ we are looking at speed and position, this is because we started with a PDE with $\frac{\partial^2 y}{\partial t^2}$ in it, which is a second order in t .)

At $t=0$, (1) becomes

$$y = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi}{L}x\right) = f(x) \quad (2)$$

To find $f(x)$ from diagram, we see that for $0 \leq x \leq \frac{L}{4}$, $y = x \frac{h}{L/4} = \frac{4h}{L}x$

For $\frac{L}{4} < x \leq \frac{L}{2}$, $y = -\left(x - \frac{L}{4}\right) \frac{h}{L/4} + h = -\left(x - \frac{L}{4}\right) \frac{4h}{L} + h = -x \frac{4h}{L} + \frac{L}{4} \frac{4h}{L} + h = -x \frac{4h}{L} + 2h$

For $\frac{L}{2} < x \leq L$, $y = 0$

Hence

$$y = \begin{cases} \frac{4h}{L}x & 0 \leq x \leq \frac{L}{4} \\ 2h - x \frac{4h}{L} & \frac{L}{4} < x \leq \frac{L}{2} \\ 0 & \frac{L}{2} < x \leq L \end{cases}$$

Do the inner product on both sides of equation (2) w.r.t. $\sin \frac{n\pi}{L}x$

$$\begin{aligned} b_n \int_0^L \sin^2 \frac{n\pi}{L}x \, dx &= \int_0^L f(x) \sin \frac{n\pi}{L}x \, dx \\ b_n \frac{L}{2} &= \int_0^{\frac{L}{4}} f(x) \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} f(x) \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{2}}^L f(x) \sin \frac{n\pi}{L}x \, dx \\ &= \int_0^{\frac{L}{4}} \frac{4h}{L}x \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} \left(2h - x \frac{4h}{L}\right) \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{2}}^L 0 \sin \frac{n\pi}{L}x \, dx \\ &= \int_0^{\frac{L}{4}} \frac{4h}{L}x \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} 2h \sin\left(\frac{n\pi}{L}x\right) - x \frac{4h}{L} \sin\left(\frac{n\pi}{L}x\right) \, dx \\ &= \int_0^{\frac{L}{4}} \frac{4h}{L}x \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} 2h \sin\left(\frac{n\pi}{L}x\right) dx - \int_{\frac{L}{4}}^{\frac{L}{2}} x \frac{4h}{L} \sin\left(\frac{n\pi}{L}x\right) \, dx \\ &= \frac{4h}{L} \int_0^{\frac{L}{4}} x \sin \frac{n\pi}{L}x \, dx + 2h \int_{\frac{L}{4}}^{\frac{L}{2}} \sin\left(\frac{n\pi}{L}x\right) dx - \frac{4h}{L} \int_{\frac{L}{4}}^{\frac{L}{2}} x \sin\left(\frac{n\pi}{L}x\right) \, dx \\ b_n &= \frac{8h}{n^2\pi^2} \left(2 \sin\left(\frac{n\pi}{4}\right) - \sin \frac{n\pi}{2}\right) \end{aligned}$$

Looking at few values of b_n

$$\begin{aligned}
b_n &= \frac{8h}{1^2\pi^2} \left(2 \sin\left(\frac{\pi}{4}\right) - \sin\frac{\pi}{2} \right), \frac{8h}{2^2\pi^2} \left(2 \sin\left(\frac{2\pi}{4}\right) - \sin\frac{2\pi}{2} \right), \frac{8h}{3^2\pi^2} \left(2 \sin\left(\frac{3\pi}{4}\right) - \sin\frac{3\pi}{2} \right), \dots \\
&= \frac{8h}{\pi^2} \left[\left(2 \sin\left(\frac{\pi}{4}\right) - \sin\frac{\pi}{2} \right), \frac{1}{2^2} \left(2 \sin\frac{2\pi}{4} - \sin\frac{2\pi}{2} \right), \frac{1}{3^2} \left(2 \sin\frac{3\pi}{4} - \sin\frac{3\pi}{2} \right), \dots \right] \\
&= \frac{8h}{\pi^2} \left[\frac{1}{n^2} \left\{ \left(2 \sin\left(\frac{\pi}{4}\right) - \sin\frac{\pi}{2} \right), \left(2 \sin\frac{2\pi}{4} - \sin\frac{2\pi}{2} \right), \left(2 \sin\frac{3\pi}{4} - \sin\frac{3\pi}{2} \right), \dots \right\} \right] \\
&= \frac{8h}{\pi^2} \left[\frac{1}{n^2} \left(2 \sin\left(\frac{n\pi}{4}\right) - \sin\frac{n\pi}{2} \right) \right]
\end{aligned}$$

Hence from equation (1) above, we get

$$\begin{aligned}
y &= \sum_{n=1}^{\infty} b_n \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt \\
&= \sum_{n=1}^{\infty} \frac{8h}{\pi^2} \left[\frac{1}{n^2} \left(2 \sin\left(\frac{n\pi}{4}\right) - \sin\frac{n\pi}{2} \right) \right] \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt \\
&= \frac{8h}{\pi^2} \sum_{n=1}^{\infty} B_n \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt
\end{aligned}$$

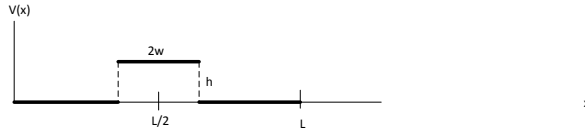
Where

$$B_n = \frac{1}{n^2} \left(2 \sin\left(\frac{n\pi}{4}\right) - \sin\frac{n\pi}{2} \right)$$

The above is the result required to show.

4 chapter 13, problem 4.6. Mary Boas, second edition

A string of length L is initially stretched straight, its ends are fixed for all time t . At time $t=0$ its points are given the velocity $V(x) = \left(\frac{\partial y}{\partial t}\right)_{t=0}$ as shown in diagram below. Determine the shape of the string at time t .



Solution

The PDE that governs this problem is the wave equation $\nabla^2 y = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$

The candidate solutions are

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \\ \cos(kx) \sin(\omega t) \\ \cos(kx) \cos(\omega t) \end{cases}$$

Where $\omega = kv$ and $k = \frac{2\pi}{\lambda}$ where λ is the wave length

Now we discard solutions that contains $\cos kx$ since the string is fixed at $x = 0$.

So we are left with

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \end{cases}$$

Now, $y = 0$ at $x = L$ then from $\sin kx = 0$ or $\sin kL = 0$ we need $k = \frac{n\pi}{L}$

Hence solutions become

$$y = \begin{cases} \sin \frac{n\pi}{L} x \sin \frac{n\pi}{L} vt \\ \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt \end{cases}$$

Applying initial conditions, which says that at time $t = 0$, velocity is given by $V(x)$

Hence from above, after taking $\frac{\partial y}{\partial t}$, we get

$$\frac{\partial y}{\partial t} = \begin{cases} \frac{n\pi v}{L} \sin \frac{n\pi}{L} x \cos \frac{n\pi v}{L} t \\ -\frac{n\pi v}{L} \sin \frac{n\pi}{L} x \sin \frac{n\pi v}{L} t \end{cases}$$

For the above we discard velocity solution above with $\sin t$ in it since that will give zero velocity at time $t=0$, which is not the case here. Hence we discard y solution with $\cos t$ in it, then the final general solution for y is now

$$y = \sin \frac{n\pi}{L} x \sin \frac{n\pi}{L} vt$$

A general solution is a linear combination of the above solutions, hence

$$y = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{L} \sin \frac{n\pi vt}{L} \quad (1)$$

To find b_n , we apply the velocity initial condition. Hence differentiate equation (1) and set $t=0$, we have

$$\frac{\partial y}{\partial t} = \sum_{n=1}^{\infty} b_n \frac{n\pi v}{L} \sin \frac{n\pi x}{L} \cos \frac{n\pi vt}{L}$$

Setting $t=0$

$$\frac{\partial y}{\partial t} = \sum_{n=1}^{\infty} b_n \frac{n\pi v}{L} \sin \frac{n\pi x}{L} = V_{t=0} \quad (2)$$

Now to find $V_{t=0}$. From diagram, we see that for $0 \leq x \leq \frac{L}{2} - w$, $V_{t=0} = 0$

For $\frac{L}{2} - w < x \leq \frac{L}{2} + w$, $V_{t=0} = h$

For $\frac{L}{2} + w < x \leq L$, $V_{t=0} = 0$

Hence

$$V_{t=0} = \begin{cases} 0 & 0 \leq x \leq \frac{L}{2} - w \\ h & \frac{L}{2} - w < x \leq \frac{L}{2} + w \\ 0 & \frac{L}{2} + w < x \leq L \end{cases}$$

Do the inner product on both sides of equation (2) w.r.t. $\sin \frac{n\pi}{L}x$

$$\begin{aligned} b_n \frac{n\pi v}{L} \int_0^L \sin^2 \frac{n\pi}{L}x \, dx &= \int_0^L V(x) \sin \frac{n\pi}{L}x \, dx \\ b_n \frac{n\pi v}{2} &= \int_0^{\frac{L}{2}-w} 0 \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{2}-w}^{\frac{L}{2}+w} h \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{2}+w}^L 0 \sin \frac{n\pi}{L}x \, dx \\ b_n \frac{n\pi v}{2} &= \int_{\frac{L}{2}-w}^{\frac{L}{2}+w} h \sin \frac{n\pi}{L}x \, dx \\ b_n \frac{n\pi v}{2} &= -h \frac{L}{n\pi} \left[\cos \frac{n\pi x}{L} \right]_{\frac{L}{2}-w}^{\frac{L}{2}+w} \\ b_n \frac{n\pi v}{2} &= -h \frac{L}{n\pi} \left[\cos \frac{n\pi \left(\frac{L}{2} + w \right)}{L} - \cos \frac{n\pi \left(\frac{L}{2} - w \right)}{L} \right] \\ b_n \frac{n\pi v}{2} &= -h \frac{L}{n\pi} \left[\cos \left(\frac{n\pi}{2} + \frac{n\pi w}{L} \right) - \cos \left(\frac{n\pi}{2} - \frac{n\pi w}{L} \right) \right] \\ b_n &= -\frac{2hL}{n^2\pi^2v} \left[\cos \left(\frac{n\pi}{2} + \frac{n\pi w}{L} \right) - \cos \left(\frac{n\pi}{2} - \frac{n\pi w}{L} \right) \right] \end{aligned}$$

But $\cos(a + b) = \cos(a)\cos(b) - \sin(a)\sin(b)$

and $\cos(a - b) = \cos(a)\cos(b) + \sin(a)\sin(b)$

Let $a = \frac{n\pi}{2}$, $b = \frac{n\pi w}{L}$

Hence b_n becomes

$$\begin{aligned}
b_n &= -\frac{2hL}{n^2\pi^2v} [\cos(a+b) - \cos(a-b)] \\
&= -\frac{2hL}{n^2\pi^2v} [\cos(a)\cos(b) - \sin(a)\sin(b) - \{\cos(a)\cos(b) + \sin(a)\sin(b)\}] \\
&= -\frac{2hL}{n^2\pi^2v} [\cos(a)\cos(b) - \sin(a)\sin(b) - \cos(a)\cos(b) - \sin(a)\sin(b)] \\
&= -\frac{2hL}{n^2\pi^2v} [-\sin(a)\sin(b) - \sin(a)\sin(b)] \\
&= \frac{4hL}{n^2\pi^2v} \sin(a)\sin(b) \\
&= \frac{4hL}{n^2\pi^2v} \sin\left(\frac{n\pi}{2}\right) \sin\left(\frac{n\pi w}{L}\right)
\end{aligned}$$

For even n , the term $\sin\left(\frac{n\pi}{2}\right)$ is zero. For n odd $\sin\left(\frac{n\pi}{2}\right) = 1$ when $n = 1, 5, 9, \dots$ and $\sin\left(\frac{n\pi}{2}\right) = -1$ when $n = 3, 7, 11, \dots$ Hence

$$b_n = A(n) \frac{4hL}{n^2\pi^2v} \sin\left(\frac{n\pi w}{L}\right) \quad n = 1, 3, 5, 7, \dots$$

And $A(n)$ is a function which returns 1 when $n = 1, 5, 9, \dots$ and returns -1 when $n = 3, 7, 11, \dots$

Hence now we have b_n we can substitute in (1)

$$\begin{aligned}
y &= \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{L} \sin \frac{n\pi vt}{L} \\
y &= \sum_{n \text{ odd}}^{\infty} A(n) \frac{4hL}{n^2\pi^2v} \sin\left(\frac{n\pi w}{L}\right) \left[\sin \frac{n\pi x}{L} \sin \frac{n\pi vt}{L} \right] \\
y &= \frac{4hL}{\pi^2v} \sum_{n \text{ odd}}^{\infty} A(n) \frac{1}{n^2} \sin\left(\frac{n\pi w}{L}\right) \left[\sin \frac{n\pi x}{L} \sin \frac{n\pi vt}{L} \right]
\end{aligned}$$

Which is the general solution. Looking at few expanded terms in the series we get

$$y = \frac{4hL}{\pi^2v} \left\{ \sin\left(\frac{\pi w}{L}\right) \sin \frac{\pi x}{L} \sin \frac{\pi vt}{L} - \frac{1}{9} \sin\left(\frac{3\pi w}{L}\right) \sin \frac{3\pi x}{L} \sin \frac{3\pi vt}{L} + \frac{1}{25} \sin\left(\frac{5\pi w}{L}\right) \sin \frac{5\pi x}{L} \sin \frac{5\pi vt}{L} \right\}$$

Which is the result required.

5 chapter 13, problem 5.1. Mary Boas, second edition

Compute numerically the coefficients $c_m = \frac{200}{k_m J_1(k_m)}$ for the first 3 terms of the series $u = \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-k_m z}$ for the steady state temp. in a solid semi-infinite cylinder when $u = 0$ at $r = 1$ and $u = 100$ at $z = 0$. find u at $r = 1/2, z = 1$

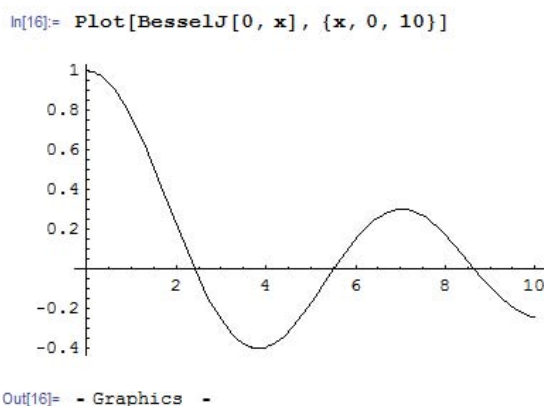
Solution

Here, we are looking at the solution for temp. inside a semi-infinite cylinder. This solution is for the case of a uniform temp. distribution on the boundary $z = 0$ is given by u equation shown above. Note that in the expression $c_m = \frac{200}{k_m J_1(k_m)}$, the k_m are the zeros of J_0 not J_1 .

Need to find c_1, c_2, c_3 where $c_1 = \frac{200}{k_1 J_1(k_1)}$

To find k_1 and $J_1(k_1)$ I used mathematica.

I plotted $J_0(x)$ to see where the zeros are located first



So I see there is a zero near 2,5, and 9. I use mathematica to find these:

```
In[20]:= k1 = FindRoot[BesselJ[0, x] == 0, {x, 2}]
Out[20]= {x -> 2.40483 }

In[21]:= k2 = FindRoot[BesselJ[0, x] == 0, {x, 5}]
Out[21]= {x -> 5.52008 }

In[22]:= k3 = FindRoot[BesselJ[0, x] == 0, {x, 9}]
Out[22]= {x -> 8.65373 }
```

Now I need to find $J_1(k_m)$. This is the result for 3 terms:

```
In[37]:= BesselJ[1, k1[[1, 2]]]
Out[37]= 0.519147

In[38]:= BesselJ[1, k2[[1, 2]]]
Out[38]= -0.340265

In[39]:= BesselJ[1, k3[[1, 2]]]
Out[39]= 0.271452
```

Hence, now the c_m terms can be found:

$$c_1 = \frac{200}{k_1 J_1(k_1)} = \frac{200}{(2.404)(0.519)} = 160.30$$

$$c_2 = \frac{200}{k_2 J_1(k_2)} = \frac{200}{(5.52)(-0.34)} = -106.56$$

$$c_3 = \frac{200}{k_3 J_1(k_3)} = \frac{200}{(8.65)(0.27)} = 85.635$$

Evaluating $u = \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-k_m z}$ for the first 3 terms when $r = 1/2, z = 1$

$$\begin{aligned}
 u &= c_1 J_0(k_1 r) e^{-k_1 z} + c_2 J_0(k_2 r) e^{-k_2 z} + c_3 J_0(k_3 r) e^{-k_3 z} \\
 &= c_1 J_0\left(k_1 \frac{1}{2}\right) e^{-k_1} + c_2 J_0\left(k_2 \frac{1}{2}\right) e^{-k_2} + c_3 J_0\left(k_3 \frac{1}{2}\right) e^{-k_3} \\
 &= (160.30) J_0\left(2.404 \frac{1}{2}\right) e^{-2.404} - (106.56) J_0\left(5.52 \frac{1}{2}\right) e^{-5.52} + (85.635) J_0\left(8.65 \frac{1}{2}\right) e^{-8.65} \\
 &= (160.30) J_0(1.202) e^{-2.404} - (106.56) J_0(2.76) e^{-5.52} + (85.635) J_0(4.325) e^{-8.65}
 \end{aligned}$$

Mathematica was used to evaluate J_0 values above.

```

In[40]:= BesselJ[0, 1.202]
Out[40]:= 0.670136

In[41]:= BesselJ[0, 2.76]
Out[41]:= -0.168385

In[42]:= BesselJ[0, 4.325]
Out[42]:= -0.356614

```

Hence

$$\begin{aligned}
 u &= (160.30)(0.67) e^{-2.404} - (106.56)(-0.168) e^{-5.52} + (85.635)(-0.356) e^{-8.65} \\
 u &= 9.7043 + 7.1713 \times 10^{-2} - 5.3389 \times 10^{-3} \\
 u &= 9.7707 \text{ degrees}
 \end{aligned}$$

6 chapter 13, problem 5.2. Mary Boas, second edition

Find the solution for the steady state temp. distribution in a solid semi-infinite cylinder if the boundary temp. are $u = 0$ at $r = 1$ and $u = y = r \sin \theta$ at $z = 0$.

Solution

The candidate solutions are given by the solution to the Laplace equation in cylindrical coordinates which are

$$u = \begin{cases} J_n(k r) \sin(n\theta) e^{-k z} & (1) \\ J_n(k r) \cos(n\theta) e^{-k z} & (2) \end{cases}$$

Where k is a zero of J_n (This is because we have used the B.C. of $u = 0$ at $r = 1$ to determine that the k 's have to be the zeros of J_n) when deriving the above solutions. See book page 560.

From boundary conditions we want $u = r \sin \theta$ when $z = 0$, hence we need to keep the solution (1) above, with $n = 1$. Hence a solution is

$$u = J_1(k r) \sin(\theta) e^{-k z} \quad (3)$$

A general solution is a linear series combinations (eigenfunctions) of (3), each eigenfunction for each of the zeros of J_1 . Call these zeros k_m

$$u = \sum_{m=1}^{\infty} c_m J_1(k_m r) \sin(\theta) e^{-k_m z} \quad (4)$$

We now apply B.C. at $z = 0$ to find c_m . From (4) when $z = 0$

$$r \sin \theta = \sum_{m=1}^{\infty} c_m J_1(k_m r) \sin(\theta) \quad (5)$$

We use (5) to find c_m and then substitute into (4) to obtain the final solution.

To find c_m from (5), take the inner product of each side with respect to $r J_1(k_u r)$ from $r = 0$ to $r = 1$

$$\begin{aligned} \int_0^1 r \sin \theta [r J_1(k_u r)] dr &= \sum_{m=1}^{\infty} c_m \left(\int_0^1 J_1(k_m r) \sin(\theta) [r J_1(k_u r)] dr \right) \\ \sin \theta \int_0^1 r^2 J_1(k_u r) dr &= \sum_{m=1}^{\infty} c_m \sin(\theta) \left(\int_0^1 J_1(k_m r) [r J_1(k_u r)] dr \right) \end{aligned}$$

Dividing each side by $\sin \theta$

$$\int_0^1 r^2 J_1(k_u r) dr = \sum_{m=1}^{\infty} c_m \left(\int_0^1 J_1(k_m r) [r J_1(k_u r)] dr \right)$$

From orthogonality of Bessel function, we know that

$$\int_0^1 J_p(k_m r) r J_p(k_u r) dr = 0$$

If $m \neq u$. Hence in above equation all terms on the right drop except for one when $u = m$. We get

$$\int_0^1 r^2 J_1(k_m r) dr = c_m \int_0^1 r J_1(k_m r) J_1(k_m r) dr$$

Or

$$c_m = \frac{\int_0^1 r^2 J_1(k_m r) dr}{\int_0^1 r J_1(k_m r) J_1(k_m r) dr} \quad (6)$$

The integral in the denominator above is found from equation 19.10 in text on page 523 which gives

$$\int_0^1 r J_1(k_m r) J_1(k_m r) dr = \frac{1}{2} [J_2(k_m)]^2 \quad (7)$$

Now, we need to find the integral of the numerator in equation (6).

Using equation 15.1 in text, page 514, which says

$$\frac{d}{dx} [x^p J_p(x)] = x^p J_{p-1}(x)$$

Putting $p = 2$ above, and letting $x = k_m r$ gives

$$\begin{aligned} \frac{1}{k_m} \frac{d}{dr} [(k_m r)^2 J_2(k_m r)] &= (k_m r)^2 J_1(k_m r) \\ \frac{1}{k_m} \frac{d}{dr} [k_m^2 r^2 J_2(k_m r)] &= k_m^2 r^2 J_1(k_m r) \\ \frac{1}{k_m} \frac{d}{dr} [r^2 J_2(k_m r)] &= r^2 J_1(k_m r) \end{aligned}$$

Integrating each side w.r.t r from 0 ... 1

$$\begin{aligned} \frac{1}{k_m} \int_0^1 \frac{d}{dr} [r^2 J_2(k_m r)] dr &= \int_0^1 r^2 J_1(k_m r) dr \\ \frac{1}{k_m} [r^2 J_2(k_m r)]_0^1 &= \int_0^1 r^2 J_1(k_m r) dr \\ \frac{1}{k_m} [J_2(k_m) - 0] &= \int_0^1 r^2 J_1(k_m r) dr \\ \frac{1}{k_m} J_2(k_m) &= \int_0^1 r^2 J_1(k_m r) dr \quad (8) \end{aligned}$$

Substituting (7) and (8) into (6)

$$\begin{aligned} c_m &= \frac{\int_0^1 r^2 J_1(k_m r) dr}{\int_0^1 r J_1(k_m r) J_1(k_m r) dr} \\ &= \frac{\frac{1}{k_m} J_2(k_m)}{\frac{1}{2} [J_2(k_m)]^2} \\ &= \frac{2}{k_m J_2(k_m)} \end{aligned}$$

Substituting this into (4) above, we get

$$u = \sum_{m=1}^{\infty} c_m J_1(k_m r) \sin(\theta) e^{-k_m z}$$
$$u = \sum_{m=1}^{\infty} \frac{2}{k_m J_2(k_m)} J_1(k_m r) \sin(\theta) e^{-k_m z}$$

where k_m are zeros of J_1

The above is the result we are asked to show.

7 chapter 13, problem 5.4. Mary Boass, second edition

A flat circular plate of radius 1 is initially at temp. 100^0 . From $t = 0$ on, the circumference of the plate is held at 0^0 . Find the time-dependent temp distribution $u(r, \theta, t)$

Solution

First convert heat equation from Cartesian coordinates to polar.

heat equation in 2D Cartesian is

$$\nabla^2 u = \frac{\partial^2}{\partial x^2} u + \frac{\partial^2}{\partial y^2} u = \frac{1}{\alpha^2} \frac{\partial}{\partial t} u$$

First need to express Laplacian operator ∇^2 in polar coordinates:

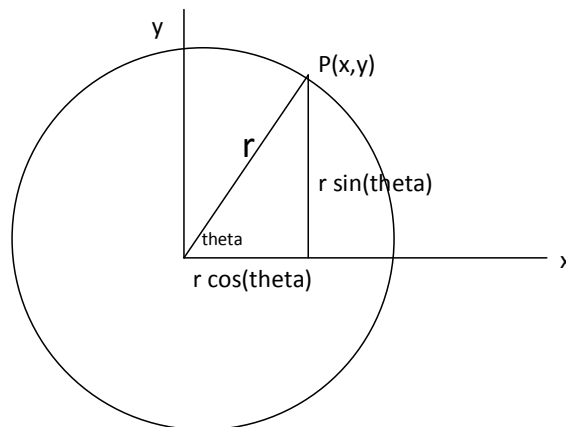
$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$

Hence

$$\begin{aligned} \frac{\partial x}{\partial r} &= \cos \theta \\ \frac{\partial y}{\partial r} &= \sin \theta \end{aligned} \tag{A}$$

And

$$\begin{aligned} \frac{\partial x}{\partial \theta} &= -r \sin \theta \\ \frac{\partial y}{\partial \theta} &= r \cos \theta \end{aligned} \tag{B}$$



From geometry, we also know that

$$\begin{aligned} r &= \sqrt{x^2 + y^2} \\ \theta &= \arctan \frac{y}{x} \end{aligned}$$

The above 2 relations imply

$$\frac{\partial}{\partial r} = \frac{\partial x}{\partial r} \frac{\partial}{\partial x} + \frac{\partial y}{\partial r} \frac{\partial}{\partial y} \quad \text{and} \quad \frac{\partial}{\partial \theta} = \frac{\partial x}{\partial \theta} \frac{\partial}{\partial x} + \frac{\partial y}{\partial \theta} \frac{\partial}{\partial y}$$

Hence we can express the above, using equations (A) and (B) as follows:

$$\begin{aligned}\frac{\partial}{\partial r} &= \frac{\partial x}{\partial r} \frac{\partial}{\partial x} + \frac{\partial y}{\partial r} \frac{\partial}{\partial y} \\ &= \cos \theta \frac{\partial}{\partial x} + \sin \theta \frac{\partial}{\partial y}\end{aligned}$$

Multiply each side by r

$$\begin{aligned}r \frac{\partial}{\partial r} &= r \cos \theta \frac{\partial}{\partial x} + r \sin \theta \frac{\partial}{\partial y} \\ &= x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}\end{aligned}\tag{1}$$

Squaring each sides of (1) gives

$$\begin{aligned}r \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) &= \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)^2 \\ r \left(r \frac{\partial^2}{\partial r^2} + \frac{\partial}{\partial r} \right) &= x \frac{\partial}{\partial x} x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} y \frac{\partial}{\partial y} + 2x \frac{\partial}{\partial x} y \frac{\partial}{\partial y} \\ r^2 \frac{\partial^2}{\partial r^2} + r \frac{\partial}{\partial r} &= x \frac{\partial}{\partial x} \left(x \frac{\partial}{\partial x} \right) + y \frac{\partial}{\partial y} \left(y \frac{\partial}{\partial y} \right) + 2x \frac{\partial}{\partial x} \left(y \frac{\partial}{\partial y} \right) \\ &= x \left(x \frac{\partial^2}{\partial x^2} + \overset{=1}{\frac{\partial}{\partial x}} x \frac{\partial}{\partial x} \right) + y \left(y \frac{\partial^2}{\partial y^2} + \overset{=1}{\frac{\partial}{\partial y}} y \frac{\partial}{\partial y} \right) + 2x \left(y \frac{\partial^2}{\partial x \partial y} + \overset{=0}{\frac{\partial}{\partial x}} y \frac{\partial}{\partial y} \right) \\ &= x^2 \frac{\partial^2}{\partial x^2} + x \frac{\partial}{\partial x} + y^2 \frac{\partial^2}{\partial y^2} + y \frac{\partial}{\partial y} + 2xy \frac{\partial^2}{\partial x \partial y}\end{aligned}\tag{2}$$

Notice that when manipulating of differential operators, $x \frac{\partial}{\partial x} \neq \frac{\partial}{\partial x} x$. Similarly

$$\begin{aligned}\frac{\partial}{\partial \theta} &= \frac{\partial x}{\partial \theta} \frac{\partial}{\partial x} + \frac{\partial y}{\partial \theta} \frac{\partial}{\partial y} \\ &= -r \sin \theta \frac{\partial}{\partial x} + r \cos \theta \frac{\partial}{\partial y} \\ &= -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}\end{aligned}\tag{3}$$

Squaring each side of (3) gives

$$\begin{aligned}
\left(\frac{\partial}{\partial\theta}\right)^2 &= \left(-y\frac{\partial}{\partial x} + x\frac{\partial}{\partial y}\right)^2 \\
\frac{\partial}{\partial\theta}\frac{\partial}{\partial\theta} &= -y\frac{\partial}{\partial x}\left(-y\frac{\partial}{\partial x}\right) + x\frac{\partial}{\partial y}\left(x\frac{\partial}{\partial y}\right) - y\frac{\partial}{\partial x}\left(x\frac{\partial}{\partial y}\right) + x\frac{\partial}{\partial y}\left(-y\frac{\partial}{\partial x}\right) \\
\frac{\partial^2}{\partial\theta^2} &= -y\left(-y\frac{\partial^2}{\partial x^2} + \overbrace{\frac{\partial}{\partial x}(-y)}^{=0}\frac{\partial}{\partial x}\right) + x\left(x\frac{\partial^2}{\partial y^2} + \overbrace{\frac{\partial}{\partial y}(x)}^{=0}\frac{\partial}{\partial y}\right) \\
&\quad - y\left(x\frac{\partial^2}{\partial y\partial x} + \overbrace{\frac{\partial}{\partial x}x}^{=1}\frac{\partial}{\partial y}\right) + x\left(-y\frac{\partial^2}{\partial x\partial y} + \overbrace{\frac{\partial}{\partial y}y}^{=1}\frac{\partial}{\partial x}\right) \\
&= y^2\frac{\partial^2}{\partial x^2} + x^2\frac{\partial^2}{\partial y^2} - yx\frac{\partial^2}{\partial y\partial x} - y\frac{\partial}{\partial y} - xy\frac{\partial^2}{\partial x\partial y} - x\frac{\partial}{\partial x} \\
&= y^2\frac{\partial^2}{\partial x^2} + x^2\frac{\partial^2}{\partial y^2} - 2yx\frac{\partial^2}{\partial y\partial x} - y\frac{\partial}{\partial y} - x\frac{\partial}{\partial x} \tag{4}
\end{aligned}$$

Adding equation (2) and (4) and carry cancellations

$$\begin{aligned}
r^2\frac{\partial^2}{\partial r^2} + r\frac{\partial}{\partial r} + \frac{\partial^2}{\partial\theta^2} &= \left(x^2\frac{\partial^2}{\partial x^2} + x\frac{\partial}{\partial x} + y^2\frac{\partial^2}{\partial y^2} + y\frac{\partial}{\partial y} + 2xy\frac{\partial^2}{\partial x\partial y}\right) + \left(y^2\frac{\partial^2}{\partial x^2} + x^2\frac{\partial^2}{\partial y^2} - 2yx\frac{\partial^2}{\partial y\partial x} - y\frac{\partial}{\partial y} - x\frac{\partial}{\partial x}\right) \\
r^2\frac{\partial^2}{\partial r^2} + r\frac{\partial}{\partial r} + \frac{\partial^2}{\partial\theta^2} &= \left(x^2\frac{\partial^2}{\partial x^2} + y^2\frac{\partial^2}{\partial y^2}\right) + \left(y^2\frac{\partial^2}{\partial x^2} + x^2\frac{\partial^2}{\partial y^2}\right)
\end{aligned}$$

Hence we get

$$\begin{aligned}
r^2\frac{\partial^2}{\partial r^2} + r\frac{\partial}{\partial r} + \frac{\partial^2}{\partial\theta^2} &= x^2\frac{\partial^2}{\partial x^2} + y^2\frac{\partial^2}{\partial y^2} + y^2\frac{\partial^2}{\partial x^2} + x^2\frac{\partial^2}{\partial y^2} \\
&= (x^2 + y^2)\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right)
\end{aligned}$$

Dividing by r^2

$$\frac{\partial^2}{\partial r^2} + \frac{1}{r}\frac{\partial}{\partial r} + \frac{1}{r^2}\frac{\partial^2}{\partial\theta^2} = \frac{(x^2 + y^2)}{r^2}\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right)$$

But $r^2 = x^2 + y^2$ hence

$$\frac{\partial^2}{\partial r^2} + \frac{1}{r}\frac{\partial}{\partial r} + \frac{1}{r^2}\frac{\partial^2}{\partial\theta^2} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) = \nabla^2$$

Now that we have the Laplacian in polar coordinates, we can solve the problem by applying separation of variables on the heat PDE expressed in polar coordinates.

$$\frac{\partial^2}{\partial r^2}u + \frac{1}{r}\frac{\partial}{\partial r}u + \frac{1}{r^2}\frac{\partial^2}{\partial\theta^2}u = \frac{1}{\alpha^2}\frac{\partial}{\partial t}u \tag{5}$$

Let solution $u(r, \theta, t)$ be a linear combination of functions each depends on only r, θ , or t

$$u(r, \theta, t) = R(r)\Theta(\theta)T(t) \tag{6}$$

Substitute (6) in (5). First evaluate the various derivatives:

$$\frac{\partial}{\partial r}u = \Theta(\theta)T(t)\frac{\partial}{\partial r}R(r)$$

$$\frac{\partial^2}{\partial r^2}u = \Theta(\theta)T(t)\frac{\partial^2}{\partial r^2}R(r)$$

$$\frac{\partial}{\partial \theta}u = R(r)T(t)\frac{\partial}{\partial \theta}\Theta(\theta)$$

$$\frac{\partial^2}{\partial \theta^2}u = R(r)T(t)\frac{\partial^2}{\partial \theta^2}\Theta(\theta)$$

$$\frac{\partial}{\partial t}u = R(r)\Theta(\theta)\frac{\partial}{\partial t}T(t)$$

Hence equation (5) becomes

$$\begin{aligned} \frac{\partial^2}{\partial r^2}u + \frac{1}{r}\frac{\partial}{\partial r}u + \frac{1}{r^2}\frac{\partial^2}{\partial \theta^2}u &= \frac{1}{\alpha^2}\frac{\partial}{\partial t}u \\ \Theta(\theta)T(t)\frac{d^2}{dr^2}R(r) + \frac{1}{r}\Theta(\theta)T(t)\frac{d}{dr}R(r) + \frac{1}{r^2}R(r)T(t)\frac{d^2}{d\theta^2}\Theta(\theta) &= \frac{1}{\alpha^2}R(r)\Theta(\theta)\frac{d}{dt}T(t) \end{aligned}$$

Divide by $R(r)\Theta(\theta)T(t)$

$$\begin{aligned} \frac{1}{R(r)}\frac{d^2}{dr^2}R(r) + \frac{1}{r}\frac{1}{R(r)}\frac{d}{dr}R(r) + \frac{1}{r^2}\frac{1}{\Theta(\theta)}\frac{d^2}{d\theta^2}\Theta(\theta) &= \frac{1}{\alpha^2}\frac{1}{T(t)}\frac{d}{dt}T(t) \\ \frac{1}{R(r)}\left[\frac{d^2}{dr^2}R(r) + \frac{1}{r}\frac{d}{dr}R(r)\right] + \frac{1}{r^2}\frac{1}{\Theta(\theta)}\frac{d^2}{d\theta^2}\Theta(\theta) &= \frac{1}{\alpha^2}\frac{1}{T(t)}\frac{d}{dt}T(t) \end{aligned}$$

We notice that the RHS depends only on t and the LHS depends only on r, θ and they equal to each others, hence they both must be constant. Let this constant be $-k^2$

Hence

$$\frac{1}{\alpha^2}\frac{1}{T(t)}\frac{d}{dt}T(t) = -k^2 \quad (7)$$

$$\frac{1}{R(r)}\left[\frac{d^2}{dr^2}R(r) + \frac{1}{r}\frac{d}{dr}R(r)\right] + \frac{1}{r^2}\frac{1}{\Theta(\theta)}\frac{d^2}{d\theta^2}\Theta(\theta) = -k^2 \quad (8)$$

equation (7) is a linear first order ODE with constant coeff. $\frac{d}{dt}T(t) = -\alpha^2T(t)k^2$ or $\frac{dT(t)}{T(t)} = -\alpha^2k^2dt$

Integrating to solve gives

$$\begin{aligned} \int \frac{dT(t)}{T(t)} &= \int -\alpha^2k^2dt \\ \ln T(t) &= -\alpha^2k^2t \end{aligned}$$

or

$$T(t) = e^{-\alpha^2k^2t} \quad (9)$$

Looking at equation (8). Multiply each sides by r^2 we get

$$\begin{aligned} \frac{r^2}{R(r)} \left[\frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= -r^2 k^2 \\ \frac{r^2}{R(r)} \left[\frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + r^2 k + \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= 0 \\ r^2 \left(\frac{1}{R(r)} \left[\frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + k^2 \right) + \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= 0 \end{aligned} \quad (10)$$

The second term depends only on θ and the first term depends only on r and they are equal, hence they must be both constant. Let this constant be $-n^2$ hence

$$\begin{aligned} \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= -n^2 \\ \frac{d^2}{d\theta^2} \Theta(\theta) &= -n^2 \Theta(\theta) \end{aligned}$$

This is a second order linear ODE with constant coeff. Solution is

$$\Theta(\theta) = \begin{cases} \sin n\theta \\ \cos n\theta \end{cases} \quad (11)$$

From (10) we now have

$$\begin{aligned} r^2 \left(\frac{1}{R(r)} \left[\frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + k^2 \right) - n^2 &= 0 \\ \frac{r^2}{R(r)} \left[\frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + r^2 k^2 - n^2 &= 0 \\ r^2 \left[\frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + (r^2 k^2 - n^2) R(r) &= 0 \\ r^2 \frac{d^2}{dr^2} R(r) + r \frac{d}{dr} R(r) + (r^2 k^2 - n^2) R(r) &= 0 \end{aligned} \quad (12)$$

Equation (12) is the Bessel D.E., its solutions are $J_n(kr)$ and $N_n(kr)$. As described on book on page 560, we can not use the $N_n(kr)$ solution since plate contains the origin and $N_n(0)$ is not defined. So we use solution $R(r) = J_n(kr)$. From boundary conditions, we want solution to be zero at $r = 1$, hence we want $J_n(k) = 0$, hence the k 's are the zeros of J_n

Putting these solutions together, we get from (6)

$$\begin{aligned} u(r, \theta, t) &= R(r)\Theta(\theta)T(t) \\ &= \begin{cases} J_n(kr) \sin n\theta e^{-\alpha^2 k^2 t} \\ J_n(kr) \cos n\theta e^{-\alpha^2 k^2 t} \end{cases} \end{aligned}$$

From symmetry of plate, the solution can not depend on the angle θ , hence let $n = 0$ and so as not to get $u = 0$, we must pick the solution with $\cos n\theta$ term. Hence our solution now is

$$u(r, t) = J_0(kr) e^{-\alpha^2 k^2 t}$$

Where k is a zero of J_0

The general solution is a linear combination of this eigenfunction for all zeros of J_0 , hence

$$u(r, t) = \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-\alpha^2 k_m^2 t} \quad (13)$$

We find c_m by using initial condition. When $t = 0$, temp. was 100^0 hence

$$100 = \sum_{m=1}^{\infty} c_m J_0(k_m r)$$

Applying inner product w.r.t. $rJ_0(k_u r)$ from 0 ... 1

$$\begin{aligned} \int_0^1 100 rJ_0(k_u r) dr &= \int_0^1 \left(\sum_{m=1}^{\infty} c_m J_0(k_m r) \right) rJ_0(k_u r) dr \\ 100 \int_0^1 rJ_0(k_u r) dr &= \sum_{m=1}^{\infty} c_m \int_0^1 J_0(k_m r) rJ_0(k_u r) dr \end{aligned}$$

From orthogonality of $J_0(k_m r)$ and $J_0(k_u r)$, all terms drop except when $m = u$

$$100 \int_0^1 rJ_0(k_u r) dr = c_u \int_0^1 r[J_0(k_u r)]^2 dr$$

From here we can follow the book on page 561 to get

$$c_m = \frac{200}{k_m J_1(k_m)}$$

Substitute this in equation 13

$$\begin{aligned} u(r, t) &= \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-\alpha^2 k_m^2 t} \\ &= \sum_{m=1}^{\infty} \frac{200}{k_m J_1(k_m)} J_0(k_m r) e^{-\alpha^2 k_m^2 t} \\ &= 200 \sum_{m=1}^{\infty} \frac{1}{k_m J_1(k_m)} J_0(k_m r) e^{-\alpha^2 k_m^2 t} \end{aligned}$$

Where k_m are zeros of J_0

Notice that final solution does not depend on θ

8 chapter 13, problem 5.11. Mary Boas, second edition

Solve

$$r \frac{d}{dr} \left(r \frac{dR}{dr} \right) = n^2 R$$

$$\frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = l(l+1)R$$

Solution

First equation, use power series method.

$$r \frac{d}{dr} \left(r \frac{dR}{dr} \right) = n^2 R$$

$$r \left(r \frac{d^2 R}{dr^2} + \frac{dR}{dr} \right) - n^2 R = 0$$

$$r^2 \frac{d^2 R}{dr^2} + r \frac{dR}{dr} - n^2 R = 0$$

Let $R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$ then

$$R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$$

$$-n^2 R = -n^2 a_0 r^s - n^2 a_1 r^{s+1} - n^2 a_2 r^{s+2} - n^2 a_3 r^{s+3} - n^2 a_4 r^{s+4} - \dots$$

$$\frac{dR}{dr} = s a_0 r^{s-1} + (s+1) a_1 r^s + (s+2) a_2 r^{s+1} + (s+3) a_3 r^{s+2} + \dots$$

$$r \frac{dR}{dr} = s a_0 r^s + (s+1) a_1 r^{s+1} + (s+2) a_2 r^{s+2} + (s+3) a_3 r^{s+3} + \dots$$

$$\frac{d^2 R}{dr^2} = (s-1)s a_0 r^{s-2} + s(s+1) a_1 r^{s-1} + (s+1)(s+2) a_2 r^s + (s+2)(s+3) a_3 r^{s+1} + \dots$$

$$r^2 \frac{d^2 R}{dr^2} = (s-1)s a_0 r^s + s(s+1) a_1 r^{s+1} + (s+1)(s+2) a_2 r^{s+2} + (s+2)(s+3) a_3 r^{s+3} + \dots$$

Table is

	r^s	r^{s+1}	r^{s+2}	r^{s+m}
$-n^2 R$	$-n^2 a_0$	$-n^2 a_1$	$-n^2 a_2$	$-n^2 a_m$
$r \frac{dR}{dr}$	$s a_0$	$(s+1) a_1$	$(s+2) a_2$	$(s+m) a_m$
$r^2 \frac{d^2 R}{dr^2}$	$(s-1)s a_0$	$s(s+1) a_1$	$(s+1)(s+2) a_2$	$(s+m-1)(s+m) a_m$

Hence, from first column we see , and since $a_0 \neq 0$ we solve for s

$$-n^2 a_0 + s a_0 + (s-1)s a_0 = 0$$

$$a_0 (-n^2 + s + (s-1)s) = 0$$

$$-n^2 + s + (s-1)s = 0$$

$$-n^2 + s^2 = 0$$

$$s = \pm n$$

We see from second column, $a_1 (-n^2 + (s+1) + s^2 + s) = 0$ or $a_1 (-s^2 + 2s + 1 + s^2) = 0$, hence $a_1(2s+1) = 0$

For $a_1 \neq 0$ then $s = -\frac{1}{2}$, this means n is not an integer since $s = \pm n$. hence a_1 must be zero.

The same applies to all $a_m, m > 0$ Hence solution contains only a_0

$$R = a_0 r^{\pm n}$$

$$R = \begin{cases} a_0 r^{-n} \\ a_0 r^{+n} \end{cases}$$

For some constant a_0 . This solution is when $n \neq 0$

If $n = 0$, table is

	r^s	r^{s+1}	r^{s+2}	r^{s+m}
$-n^2 R$	0	0	0	0
$r \frac{dR}{dr}$	$s a_0$	$(s+1) a_1$	$(s+2) a_2$	$(s+m) a_m$
$r^2 \frac{d^2 R}{dr^2}$	$(s-1)s a_0$	$s(s+1) a_1$	$(s+1)(s+2) a_2$	$(s+m-1)(s+m) a_m$

From first column:

$$s a_0 + s^2 a_0 - s a_0 = 0$$

$$a_0 (s + s^2 - s) = 0$$

$$s^2 = 0$$

$$s = 0$$

And all other a 's are zero. Hence $R = a_0$ or R is constant.

Now for the second ODE

$$\frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = l(l+1)R$$

$$r^2 \frac{d^2 R}{dr^2} + 2r \frac{dR}{dr} - l(l+1)R = 0$$

Let $R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$ then

$$R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$$

$$-l(l+1)R = -l(l+1)a_0 r^s - l(l+1)a_1 r^{s+1} - l(l+1)a_2 r^{s+2} - l(l+1)a_3 r^{s+3} - l(l+1)a_4 r^{s+4} - \dots$$

$$\frac{dR}{dr} = s a_0 r^{s-1} + (s+1) a_1 r^s + (s+2) a_2 r^{s+1} + (s+3) a_3 r^{s+2} + \dots$$

$$2r \frac{dR}{dr} = 2s a_0 r^s + 2(s+1) a_1 r^{s+1} + 2(s+2) a_2 r^{s+2} + 2(s+3) a_3 r^{s+3} + \dots$$

$$\frac{d^2 R}{dr^2} = (s-1)s a_0 r^{s-2} + s(s+1) a_1 r^{s-1} + (s+1)(s+2) a_2 r^s + (s+2)(s+3) a_3 r^{s+1} + \dots$$

$$r^2 \frac{d^2 R}{dr^2} = (s-1)s a_0 r^s + s(s+1) a_1 r^{s+1} + (s+1)(s+2) a_2 r^{s+2} + (s+2)(s+3) a_3 r^{s+3} + \dots$$

Table is

	r^s	r^{s+1}	r^{s+2}	r^{s+m}
$-r^2 R$	$-l(l+1)a_0$	$-l(l+1)a_1$	$-l(l+1)a_2$	$-l(l+1)a_m$
$2r \frac{dR}{dr}$	$2s a_0$	$2(s+1)a_1$	$2(s+2)a_2$	$2(s+m)a_m$
$r^2 \frac{d^2R}{dr^2}$	$(s-1)s a_0$	$s(s+1)a_1$	$(s+1)(s+2)a_2$	$(s+m-1)(s+m)a_m$

From first column:

$$\begin{aligned}
 -l(l+1)a_0 + 2s a_0 + (s-1)s a_0 &= 0 \\
 a_0(-l(l+1) + 2s + (s-1)s) &= 0 \\
 -l(l+1) + 2s + (s-1)s &= 0 \\
 -l(l+1) + s + s^2 &= 0 \\
 (s-l)(s-(-l-1)) &= 0
 \end{aligned}$$

Hence $s = l$ or $s = -l - 1$.

We also see that all other a' s will be zero, since recursive formula has only a_m in it and no other a . Hence

$$R = a_0 r^s$$

$$R = \begin{cases} a_0 r^l \\ a_0 r^{-l-1} \end{cases}$$

For some constant a_0