

HW 9

MATH 121B

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# 1 Chapter 13, problem 6.1 Mary Boas. Second edition

chapter 13

6.1

will use

$$z = J_n(k_{mn}) \cos n\theta \cos k_{mn} x t$$

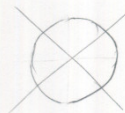
Complete Figure 6.1.

$k_{mn}$  is the  $m^{\text{th}}$  zero of  $J_n$ .

Circle is divided into as many sectors as  $2n$ . for example, when  $n=1$ , we will set



when  $n=2$ , we will set



this is because we want a solution

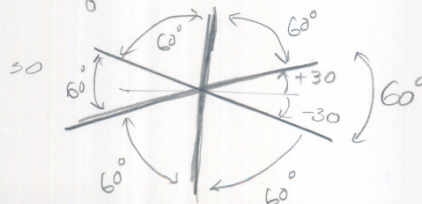
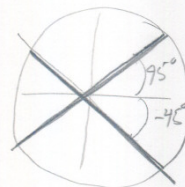
$$\cos 2\theta = \pm \frac{\pi}{2}$$

$$\text{which means } \theta = \pm \frac{\pi}{2n}$$

$$\text{so for } n=1, \theta = \pm \frac{\pi}{2}, -\frac{\pi}{2}$$

$$n=2, 2\theta = \pm \frac{\pi}{2} \text{ or } \theta = \pm \frac{\pi}{4}$$

$$\text{for } n=3, 3\theta = \pm \frac{\pi}{2} \text{ or } \theta = \pm \frac{\pi}{6}$$



etc..

now, for changing of the  $m$ .

from  $z = J_n(K_m r) \cos n\theta \cos K_m \sqrt{t}$

we want  $J_n(K_m r)$  to zero.

as  $m$  increases,  $K_{m_2} > K_{m_1}$  when  $m_2 > m_1$

so  $r$  becomes smaller for each  $m$  increasing.

if original radius of drum is 1, then

$$r \text{ for } m=1 \Rightarrow 1$$

$$r \text{ for } m=2 \Rightarrow \frac{K_{10}}{K_{20}} < 1$$

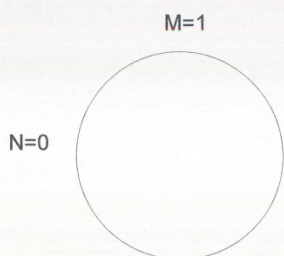
$$r \text{ for } m=3 \Rightarrow \frac{K_{10}}{K_{30}} < \frac{K_{10}}{K_{20}}$$

So each time  $m$  increases by 1 we add a smaller radius inside. so now I show

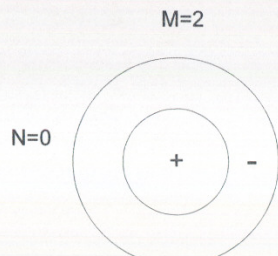
the complete figure for  $n=0, 1, 2$ ,  $m=1, 2, 3$ .

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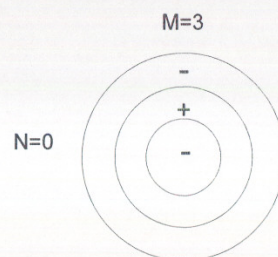




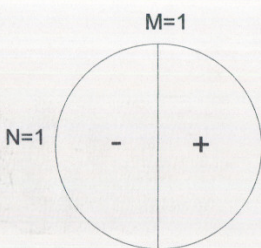
$$z = J_0(k_{10}r) \cos(k_{10}vt)$$



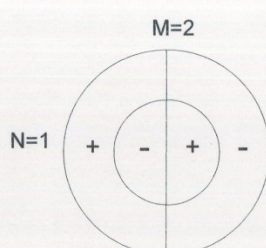
$$z = J_0(k_{20}r) \cos(k_{20}vt)$$



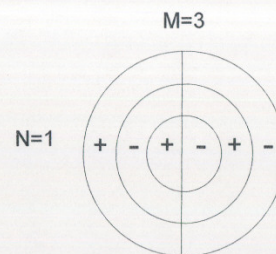
$$z = J_0(k_{30}r) \cos(k_{30}vt)$$



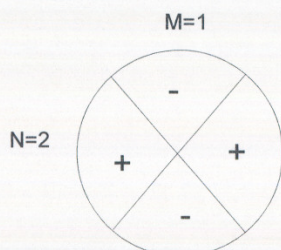
$$z = J_1(k_{11}r) \cos\theta \cos(k_{11}vt)$$



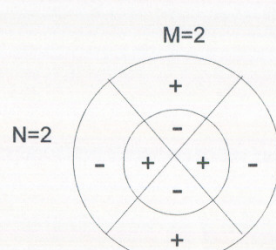
$$z = J_1(k_{21}r) \cos\theta \cos(k_{21}vt)$$



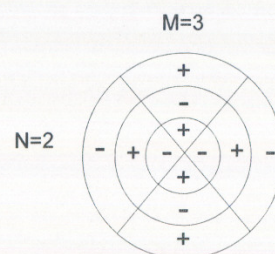
$$z = J_1(k_{31}r) \cos\theta \cos(k_{31}vt)$$



$$z = J_2(k_{12}r) \cos 2\theta \cos(k_{12}vt)$$



$$z = J_2(k_{22}r) \cos 2\theta \cos(k_{22}vt)$$



$$z = J_2(k_{32}r) \cos 2\theta \cos(k_{32}vt)$$

Chapter 13, 6.2

look up first 3 zeros of  $K_{mn}$  of each Bessel function  $J_0, J_1, J_2, J_3$ . find the first 6 frequencies of a vibrating circular membrane as multiples of fundamental frequency.

Solution

frequency is given by  $\omega_{mn} = K_{mn} v$

Fundamental frequency is  $\omega_{10} v$ .

First zero of  $J_0$

So ratio of frequency  $\omega_{mn}$  to Fundamental is

$$\frac{\omega_{mn}}{\omega_{10}} = \frac{K_{mn}}{K_{10}}$$

First zero of  $J_0$ .

So 
$$\omega_{mn} = \omega_{10} \frac{K_{mn}}{K_{10}}$$

Using this I can find frequencies as multiple of Fundamental freq.

→



First 3 Zeros of Bessel functions. using Handbook.

$J_0$

		<u>zero</u>
$m=1$	$\rightarrow$	2.4
$m=2$	$\rightarrow$	5.65
$m=3$	$\rightarrow$	8.55

$J_1$

$m=1$	$\rightarrow$	3.75
$m=2$	$\rightarrow$	7.25
$m=3$	$\rightarrow$	10.05

$J_2$

$m=1$	$\rightarrow$	5.05
$m=2$	$\rightarrow$	8.45
$m=3$	$\rightarrow$	11.55

$J_3$

$m=1$	$\rightarrow$	6.3
$m=2$	$\rightarrow$	13.1
$m=3$	$\rightarrow$	16.3

So now I can find the first 6 frequencies.

First =  $\omega_{10}$  This is Fundamental Frequency.

$$\text{Second} = \omega_{11} = \omega_{10} \frac{K_{11}}{K_{10}} = \omega_{10} \frac{3.75}{2.4} = \boxed{1.56 \omega_0}$$

$$\text{Third} = \omega_{12} = \omega_{10} \frac{K_{12}}{K_{10}} = \omega_{10} \frac{5.05}{2.4} = \boxed{2.1 \omega_0}$$

$$\text{Fourth} = \omega_{20} = \omega_{10} \frac{K_{20}}{K_{10}} = \omega_{10} \frac{5.65}{2.4} = \boxed{2.35 \omega_0}$$

$$\text{Fifth} = \omega_{21} = \omega_{10} \frac{K_{21}}{K_{10}} = \omega_{10} \frac{7.25}{2.4} = \boxed{3.01 \omega_0}$$

$$\text{Sixth} = \omega_{22} = \omega_{10} \frac{K_{22}}{K_{10}} = \omega_{10} \frac{8.45}{2.4} = \boxed{3.5 \omega_0}$$

## 2 chapter 13, problem 4.1. Mary Boas, second edition

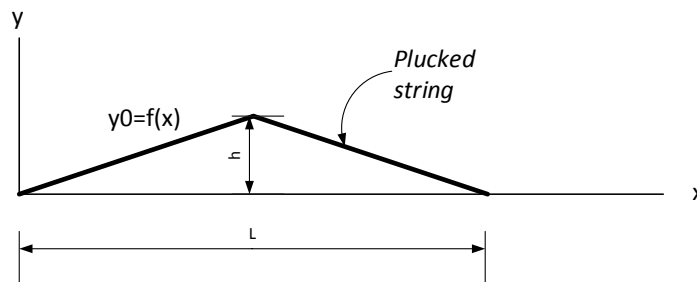
Complete the plucked string problem to get equation 4.0

### Solution

Here we start with the solution given in 4.8

$$y_0 = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi x}{L}\right) = f(x) \quad (1)$$

Where  $f(x)$  represents the initial position (shape) of the string.



Now need to find  $b_n$

First need to define  $f(x)$ , from diagram we see that from  $x = 0$  to  $x = L/2$  the slope is  $\frac{h}{L/2} = \frac{2h}{L}$  hence from equation of line we get  $y = \frac{2h}{L}x$

From  $x = L/2$  to  $x = L$ , slope is  $-\frac{2h}{L}$ , so  $y = h - \frac{2h}{L}\left(x - \frac{L}{2}\right) = h - \frac{2h}{L}x + h = 2h - \frac{2h}{L}x = 2\left(h - \frac{hx}{L}\right)$

so we have

$$f(x) = \begin{cases} \frac{2h}{L}x & 0 \leq x \leq \frac{L}{2} \\ 2\left(h - \frac{hx}{L}\right) & \frac{L}{2} < x \leq L \end{cases}$$

so from (1) we get, after applying inner product w.r.t.  $\sin\left(\frac{n\pi x}{L}\right)$



$$\begin{aligned}
b_n \int_0^L \sin^2\left(\frac{n\pi x}{L}\right) dx &= \int_0^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \int_0^{\frac{L}{2}} f(x) \sin\left(\frac{n\pi x}{L}\right) dx + \int_{\frac{L}{2}}^L f(x) \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \int_0^{\frac{L}{2}} \frac{2h}{L} x \sin\left(\frac{n\pi x}{L}\right) dx + \int_{\frac{L}{2}}^L 2\left(h - \frac{hx}{L}\right) \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \frac{2h}{L} \int_0^{\frac{L}{2}} x \sin\left(\frac{n\pi x}{L}\right) dx + \int_{\frac{L}{2}}^L 2h \sin\left(\frac{n\pi x}{L}\right) dx - \int_{\frac{L}{2}}^L \frac{2hx}{L} \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \frac{2h}{L} \int_0^{\frac{L}{2}} x \sin\left(\frac{n\pi x}{L}\right) dx + 2h \int_{\frac{L}{2}}^L \sin\left(\frac{n\pi x}{L}\right) dx - \frac{2h}{L} \int_{\frac{L}{2}}^L x \sin\left(\frac{n\pi x}{L}\right) dx \\
b_n \frac{L}{2} &= \frac{16 h L \cos\left(\frac{n\pi}{4}\right) \sin\left(\frac{n\pi}{4}\right)^3}{n^2 \pi^2} \\
b_n &= \frac{32 h \cos\left(\frac{n\pi}{4}\right) \sin\left(\frac{n\pi}{4}\right)^3}{n^2 \pi^2}
\end{aligned}$$

so

$$b_n = \frac{32 h L \cos\left(\frac{n\pi}{4}\right) \sin\left(\frac{n\pi}{4}\right)^3}{n^2 \pi^2}$$

Looking at few values of n to see the pattern

$$\begin{aligned}
b_n &= \frac{32 h \cos\left(\frac{\pi}{4}\right) \sin\left(\frac{\pi}{4}\right)^3}{1^2 \pi^2}, \frac{32 h \cos\left(\frac{2\pi}{4}\right) \sin\left(\frac{2\pi}{4}\right)^3}{2^2 \pi^2}, \frac{32 h \cos\left(\frac{3\pi}{4}\right) \sin\left(\frac{3\pi}{4}\right)^3}{3^2 \pi^2}, \dots \\
&= \frac{8h}{\pi^2}, 0, -\frac{8h}{9 \pi^2}, 0, \frac{8h}{25 \pi^2}, \dots \\
&= \frac{8h}{\pi^2} \left(1, 0, -\frac{1}{9}, 0, \frac{1}{25}, \dots\right)
\end{aligned}$$

Notice that we have terms for only odd n.

Now, substituting the above in the general solution given in equation 4.7 in book, which is

$$y = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi x}{L}\right) \cos\left(\frac{n\pi vt}{L}\right)$$

Gives

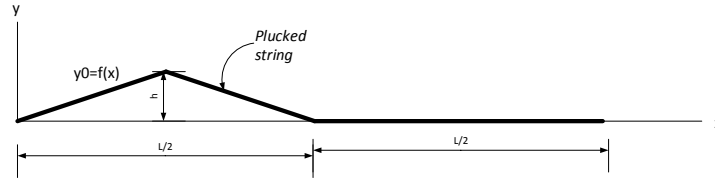
$$y = \frac{8h}{\pi^2} \left( \sin\left(\frac{\pi x}{L}\right) \cos\left(\frac{\pi vt}{L}\right) + 0 + -\frac{1}{9} \sin\left(\frac{3\pi x}{L}\right) \cos\left(\frac{3\pi vt}{L}\right) + 0 + \frac{1}{25} \sin\left(\frac{5\pi x}{L}\right) \cos\left(\frac{5\pi vt}{L}\right) + \dots \right)$$

$$y = \frac{8h}{\pi^2} \left( \sin\left(\frac{\pi x}{L}\right) \cos\left(\frac{\pi vt}{L}\right) - \frac{1}{9} \sin\left(\frac{3\pi x}{L}\right) \cos\left(\frac{3\pi vt}{L}\right) + \frac{1}{25} \sin\left(\frac{5\pi x}{L}\right) \cos\left(\frac{5\pi vt}{L}\right) + \dots \right)$$

The above is the result we are asked to show.

### 3 chapter 13, problem 4.2. Mary Boas, second edition

A string of length  $L$  has zero initial velocity and a displacement  $y_0(x)$  as shown. Find the displacement as a function of  $x$  and  $t$ .



#### Solution

The PDE that governs this problem is the wave equation  $\nabla^2 y = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$

The candidate solutions are

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \\ \cos(kx) \sin(\omega t) \\ \cos(kx) \cos(\omega t) \end{cases}$$

where  $\omega = kv$  and  $k = \frac{2\pi}{\lambda}$  where  $\lambda$  is the wave length

Now we discard solutions that contains  $\cos kx$  since the string is fixed at  $x = 0$ .

So we are left with

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \end{cases}$$

Now,  $y = 0$  at  $x = L$  then from  $\sin kx = 0$  or  $\sin kL = 0$  we need  $k = \frac{n\pi}{L}$

Hence solutions become

$$y = \begin{cases} \sin\left(\frac{n\pi}{L}x\right) \sin\left(\frac{n\pi}{L}vt\right) \\ \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi}{L}vt\right) \end{cases}$$

Applying initial conditions, which says that at time  $t = 0$ , velocity is zero.

Hence from above, after taking  $\frac{\partial y}{\partial t}$ , we get



$$\frac{\partial y}{\partial t} = \begin{cases} \frac{n\pi v}{L} \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi v}{L}t\right) \\ -\frac{n\pi v}{L} \sin\left(\frac{n\pi}{L}x\right) \sin\left(\frac{n\pi v}{L}t\right) \end{cases}$$

For the above to be zero at  $t = 0$  then we discard first solution above with  $\cos t$  in it. Hence final general solution is now

$$y = \left\{ \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi}{L}vt\right) \right.$$

A general solution is a linear combination of the above solutions, hence

$$y = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi}{L}x\right) \cos\left(\frac{n\pi}{L}vt\right) \quad (1)$$

To find  $b_n$ , we apply the second initial condition, which is  $y = y_0 = f(x)$

(Notice that we use two initial conditions, i.e. at time  $t=0$  we are looking at speed and position, this is because we started with a PDE with  $\frac{\partial^2 y}{\partial t^2}$  in it, which is a second order in  $t$ .)

At  $t=0$ , (1) becomes

$$y = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi}{L}x\right) = f(x) \quad (2)$$

To find  $f(x)$  from diagram, we see that for  $0 \leq x \leq \frac{L}{4}$ ,  $y = x \frac{h}{L/4} = \frac{4h}{L}x$

For  $\frac{L}{4} < x \leq \frac{L}{2}$ ,  $y = -\left(x - \frac{L}{4}\right) \frac{h}{L/4} + h = -\left(x - \frac{L}{4}\right) \frac{4h}{L} + h = -x \frac{4h}{L} + \frac{L}{4} \frac{4h}{L} + h = -x \frac{4h}{L} + 2h$

For  $\frac{L}{2} < x \leq L$ ,  $y = 0$

Hence

$$y = \begin{cases} \frac{4h}{L}x & 0 \leq x \leq \frac{L}{4} \\ 2h - x \frac{4h}{L} & \frac{L}{4} < x \leq \frac{L}{2} \\ 0 & \frac{L}{2} < x \leq L \end{cases}$$

Do the inner product on both sides of equation (2) w.r.t.  $\sin \frac{n\pi}{L}x$

$$\begin{aligned}
b_n \int_0^L \sin^2 \frac{n\pi}{L} x \, dx &= \int_0^L f(x) \sin \frac{n\pi}{L} x \, dx \\
b_n \frac{L}{2} &= \int_0^{\frac{L}{4}} f(x) \sin \frac{n\pi}{L} x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} f(x) \sin \frac{n\pi}{L} x \, dx + \int_{\frac{L}{2}}^L f(x) \sin \frac{n\pi}{L} x \, dx \\
&= \int_0^{\frac{L}{4}} \frac{4h}{L} x \sin \frac{n\pi}{L} x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} \left(2h - x \frac{4h}{L}\right) \sin \frac{n\pi}{L} x \, dx + \int_{\frac{L}{2}}^L 0 \sin \frac{n\pi}{L} x \, dx \\
&= \int_0^{\frac{L}{4}} \frac{4h}{L} x \sin \frac{n\pi}{L} x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} 2h \sin\left(\frac{n\pi}{L} x\right) - x \frac{4h}{L} \sin\left(\frac{n\pi}{L} x\right) \, dx \\
&= \int_0^{\frac{L}{4}} \frac{4h}{L} x \sin \frac{n\pi}{L} x \, dx + \int_{\frac{L}{4}}^{\frac{L}{2}} 2h \sin\left(\frac{n\pi}{L} x\right) dx - \int_{\frac{L}{4}}^{\frac{L}{2}} x \frac{4h}{L} \sin\left(\frac{n\pi}{L} x\right) \, dx \\
&= \frac{4h}{L} \int_0^{\frac{L}{4}} x \sin \frac{n\pi}{L} x \, dx + 2h \int_{\frac{L}{4}}^{\frac{L}{2}} \sin\left(\frac{n\pi}{L} x\right) dx - \frac{4h}{L} \int_{\frac{L}{4}}^{\frac{L}{2}} x \sin\left(\frac{n\pi}{L} x\right) \, dx \\
b_n &= \frac{8h}{n^2 \pi^2} \left(2 \sin\left(\frac{n\pi}{4}\right) - \sin \frac{n\pi}{2}\right)
\end{aligned}$$

Looking at few values of  $b_n$

$$\begin{aligned}
b_n &= \frac{8h}{1^2 \pi^2} \left(2 \sin\left(\frac{\pi}{4}\right) - \sin \frac{\pi}{2}\right), \frac{8h}{2^2 \pi^2} \left(2 \sin\left(\frac{2\pi}{4}\right) - \sin \frac{2\pi}{2}\right), \frac{8h}{3^2 \pi^2} \left(2 \sin\left(\frac{3\pi}{4}\right) - \sin \frac{3\pi}{2}\right), \dots \\
&= \frac{8h}{\pi^2} \left[ \left(2 \sin\left(\frac{\pi}{4}\right) - \sin \frac{\pi}{2}\right), \frac{1}{2^2} \left(2 \sin \frac{2\pi}{4} - \sin \frac{2\pi}{2}\right), \frac{1}{3^2} \left(2 \sin \frac{3\pi}{4} - \sin \frac{3\pi}{2}\right), \dots \right] \\
&= \frac{8h}{\pi^2} \left[ \frac{1}{n^2} \left\{ \left(2 \sin\left(\frac{\pi}{4}\right) - \sin \frac{\pi}{2}\right), \left(2 \sin \frac{2\pi}{4} - \sin \frac{2\pi}{2}\right), \left(2 \sin \frac{3\pi}{4} - \sin \frac{3\pi}{2}\right), \dots \right\} \right] \\
&= \frac{8h}{\pi^2} \left[ \frac{1}{n^2} \left(2 \sin\left(\frac{n\pi}{4}\right) - \sin \frac{n\pi}{2}\right) \right]
\end{aligned}$$

Hence from equation (1) above, we get

$$\begin{aligned}
y &= \sum_{n=1}^{\infty} b_n \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt \\
&= \sum_{n=1}^{\infty} \frac{8h}{\pi^2} \left[ \frac{1}{n^2} \left(2 \sin\left(\frac{n\pi}{4}\right) - \sin \frac{n\pi}{2}\right) \right] \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt \\
&= \frac{8h}{\pi^2} \sum_{n=1}^{\infty} B_n \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt
\end{aligned}$$

Where

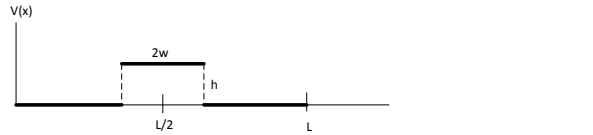
$$B_n = \frac{1}{n^2} \left( 2 \sin\left(\frac{n\pi}{4}\right) - \sin\frac{n\pi}{2} \right)$$

The above is the result required to show.



## 4 chapter 13, problem 4.6. Mary Boas, second edition

A string of length  $L$  is initially stretched straight, its ends are fixed for all time  $t$ . At time  $t=0$  its points are given the velocity  $V(x) = \left(\frac{\partial y}{\partial t}\right)_{t=0}$  as shown in diagram below. Determine the shape of the string at time  $t$ .



### Solution

The PDE that governs this problem is the wave equation  $\nabla^2 y = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$

The candidate solutions are

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \\ \cos(kx) \sin(\omega t) \\ \cos(kx) \cos(\omega t) \end{cases}$$

Where  $\omega = kv$  and  $k = \frac{2\pi}{\lambda}$  where  $\lambda$  is the wave length

Now we discard solutions that contains  $\cos kx$  since the string is fixed at  $x = 0$ .

So we are left with

$$y = \begin{cases} \sin(kx) \sin(\omega t) \\ \sin(kx) \cos(\omega t) \end{cases}$$

Now,  $y = 0$  at  $x = L$  then from  $\sin kx = 0$  or  $\sin kL = 0$  we need  $k = \frac{n\pi}{L}$

Hence solutions become

$$y = \begin{cases} \sin \frac{n\pi}{L} x \sin \frac{n\pi}{L} vt \\ \sin \frac{n\pi}{L} x \cos \frac{n\pi}{L} vt \end{cases}$$

Applying initial conditions, which says that at time  $t = 0$ , velocity is given by  $V(x)$

Hence from above, after taking  $\frac{\partial y}{\partial t}$ , we get

$$\frac{\partial y}{\partial t} = \begin{cases} \frac{n\pi v}{L} \sin \frac{n\pi}{L} x \cos \frac{n\pi v}{L} t \\ -\frac{n\pi v}{L} \sin \frac{n\pi}{L} x \sin \frac{n\pi v}{L} t \end{cases}$$

For the above we discard velocity solution above with  $\sin t$  in it since that will give zero velocity at time  $t=0$ , which is not the case here. Hence we discard  $y$  solution with  $\cos t$  in it, then the final general solution for  $y$  is now

$$y = \sin \frac{n\pi}{L} x \sin \frac{n\pi}{L} vt$$

A general solution is a linear combination of the above solutions, hence

$$y = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{L} \sin \frac{n\pi vt}{L} \quad (1)$$

To find  $b_n$ , we apply the velocity initial condition. Hence differentiate equation (1) and set  $t=0$ , we have

$$\frac{\partial y}{\partial t} = \sum_{n=1}^{\infty} b_n \frac{n\pi v}{L} \sin \frac{n\pi x}{L} \cos \frac{n\pi vt}{L}$$

Setting  $t=0$

$$\frac{\partial y}{\partial t} = \sum_{n=1}^{\infty} b_n \frac{n\pi v}{L} \sin \frac{n\pi x}{L} = V_{t=0} \quad (2)$$

Now to find  $V_{t=0}$ . From diagram, we see that for  $0 \leq x \leq \frac{L}{2} - w$ ,  $V_{t=0} = 0$

For  $\frac{L}{2} - w < x \leq \frac{L}{2} + w$ ,  $V_{t=0} = h$

For  $\frac{L}{2} + w < x \leq L$ ,  $V_{t=0} = 0$

Hence

$$V_{t=0} = \begin{cases} 0 & 0 \leq x \leq \frac{L}{2} - w \\ h & \frac{L}{2} - w < x \leq \frac{L}{2} + w \\ 0 & \frac{L}{2} + w < x \leq L \end{cases}$$

Do the inner product on both sides of equation (2) w.r.t.  $\sin \frac{n\pi}{L}x$

$$\begin{aligned}
b_n \frac{n\pi v}{L} \int_0^L \sin^2 \frac{n\pi}{L}x \, dx &= \int_0^L V(x) \sin \frac{n\pi x}{L} \, dx \\
b_n \frac{n\pi v}{2} &= \int_0^{\frac{L}{2}-w} 0 \sin \frac{n\pi}{L}x \, dx + \int_{\frac{L}{2}-w}^{\frac{L}{2}+w} h \sin \frac{n\pi x}{L} \, dx + \int_{\frac{L}{2}+w}^L 0 \sin \frac{n\pi}{L}x \, dx \\
b_n \frac{n\pi v}{2} &= \int_{\frac{L}{2}-w}^{\frac{L}{2}+w} h \sin \frac{n\pi x}{L} \, dx \\
b_n \frac{n\pi v}{2} &= -h \frac{L}{n\pi} \left[ \cos \frac{n\pi x}{L} \right]_{\frac{L}{2}-w}^{\frac{L}{2}+w} \\
b_n \frac{n\pi v}{2} &= -h \frac{L}{n\pi} \left[ \cos \frac{n\pi \left( \frac{L}{2} + w \right)}{L} - \cos \frac{n\pi \left( \frac{L}{2} - w \right)}{L} \right] \\
b_n \frac{n\pi v}{2} &= -h \frac{L}{n\pi} \left[ \cos \left( \frac{n\pi}{2} + \frac{n\pi w}{L} \right) - \cos \left( \frac{n\pi}{2} - \frac{n\pi w}{L} \right) \right] \\
b_n &= -\frac{2hL}{n^2\pi^2v} \left[ \cos \left( \frac{n\pi}{2} + \frac{n\pi w}{L} \right) - \cos \left( \frac{n\pi}{2} - \frac{n\pi w}{L} \right) \right]
\end{aligned}$$

But  $\cos(a + b) = \cos(a) \cos(b) - \sin(a) \sin(b)$

and  $\cos(a - b) = \cos(a) \cos(b) + \sin(a) \sin(b)$

Let  $a = \frac{n\pi}{2}, b = \frac{n\pi w}{L}$

Hence  $b_n$  becomes

$$\begin{aligned}
b_n &= -\frac{2hL}{n^2\pi^2v} [\cos(a + b) - \cos(a - b)] \\
&= -\frac{2hL}{n^2\pi^2v} [\cos(a) \cos(b) - \sin(a) \sin(b) - \{\cos(a) \cos(b) + \sin(a) \sin(b)\}] \\
&= -\frac{2hL}{n^2\pi^2v} [\cos(a) \cos(b) - \sin(a) \sin(b) - \cos(a) \cos(b) - \sin(a) \sin(b)] \\
&= -\frac{2hL}{n^2\pi^2v} [-\sin(a) \sin(b) - \sin(a) \sin(b)] \\
&= \frac{4hL}{n^2\pi^2v} \sin(a) \sin(b) \\
&= \frac{4hL}{n^2\pi^2v} \sin\left(\frac{n\pi}{2}\right) \sin\left(\frac{n\pi w}{L}\right)
\end{aligned}$$



For even  $n$ , the term  $\sin\left(\frac{n\pi}{2}\right)$  is zero. For  $n$  odd  $\sin\left(\frac{n\pi}{2}\right) = 1$  when  $n = 1, 5, 9, \dots$  and  $\sin\left(\frac{n\pi}{2}\right) = -1$  when  $n = 3, 7, 11, \dots$  Hence

$$b_n = A(n) \frac{4hL}{n^2 \pi^2 v} \sin\left(\frac{n\pi w}{L}\right) \quad n = 1, 3, 5, 7, \dots$$

And  $A(n)$  is a function which returns 1 when  $n = 1, 5, 9, \dots$  and returns  $-1$  when  $n = 3, 7, 11, \dots$

Hence now we have  $b_n$  we can substitute in (1)

$$\begin{aligned} y &= \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{L} \sin \frac{n\pi v t}{L} \\ y &= \sum_{n \text{ odd}}^{\infty} A(n) \frac{4hL}{n^2 \pi^2 v} \sin\left(\frac{n\pi w}{L}\right) \left[ \sin \frac{n\pi x}{L} \sin \frac{n\pi v t}{L} \right] \\ y &= \frac{4hL}{\pi^2 v} \sum_{n \text{ odd}}^{\infty} A(n) \frac{1}{n^2} \sin\left(\frac{n\pi w}{L}\right) \left[ \sin \frac{n\pi x}{L} \sin \frac{n\pi v t}{L} \right] \end{aligned}$$

Which is the general solution. Looking at few expanded terms in the series we get

$$y = \frac{4hL}{\pi^2 v} \left\{ \sin\left(\frac{\pi w}{L}\right) \sin \frac{\pi x}{L} \sin \frac{\pi v t}{L} - \frac{1}{9} \sin\left(\frac{3\pi w}{L}\right) \sin \frac{3\pi x}{L} \sin \frac{3\pi v t}{L} + \frac{1}{25} \sin\left(\frac{5\pi w}{L}\right) \sin \frac{5\pi x}{L} \sin \frac{5\pi v t}{L} \right\}$$

Which is the result required.

## 5 chapter 13, problem 5.1. Mary Boas, second edition

Compute numerically the coefficients  $c_m = \frac{200}{k_m J_1(k_m)}$  for the first 3 terms of the series  $u = \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-k_m z}$  for the steady state temp. in a solid semi-infinite cylinder when  $u = 0$  at  $r = 1$  and  $u = 100$  at  $z = 0$ . find  $u$  at  $r = 1/2, z = 1$

### Solution

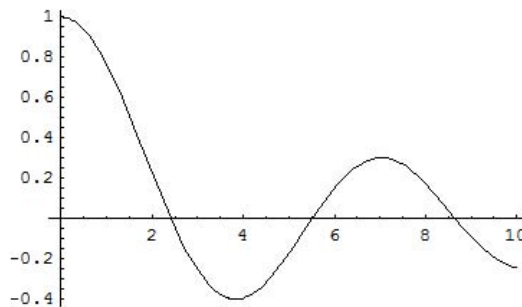
Here, we are looking at the solution for temp. inside a semi-infinite cylinder. This solution is for the case of a uniform temp. distribution on the boundary  $z = 0$  is given by  $u$  equation shown above. Note that in the expression  $c_m = \frac{200}{k_m J_1(k_m)}$ , the  $k_m$  are the zeros of  $J_0$  not  $J_1$ .

Need to find  $c_1, c_2, c_3$  where  $c_1 = \frac{200}{k_1 J_1(k_1)}$

To find  $k_1$  and  $J_1(k_1)$  I used mathematica.

I plotted  $J_0(x)$  to see where the zeros are located first

```
In[16]:= Plot[BesselJ[0, x], {x, 0, 10}]
```



```
Out[16]= - Graphics -
```

So I see there is a zero near 2,5, and 9. I use mathematica to find these:

```
In[20]:= k1 = FindRoot[BesselJ[0, x] == 0, {x, 2}]
```

```
Out[20]= {x -> 2.40483 }
```

```
In[21]:= k2 = FindRoot[BesselJ[0, x] == 0, {x, 5}]
```

```
Out[21]= {x -> 5.52008 }
```

```
In[22]:= k3 = FindRoot[BesselJ[0, x] == 0, {x, 9}]
```

```
Out[22]= {x -> 8.65373 }
```

Now I need to find  $J_1(k_m)$ . This is the result for 3 terms:

```

In[37]:= BesselJ[1, k1[[1, 2]]]
Out[37]= 0.519147

In[38]:= BesselJ[1, k2[[1, 2]]]
Out[38]= -0.340265

In[39]:= BesselJ[1, k3[[1, 2]]]
Out[39]= 0.271452

```

Hence, now the  $c_m$  terms can be found:

$$\begin{aligned}
 c_1 &= \frac{200}{k_1 J_1(k_1)} = \frac{200}{(2.404)(0.519)} = 160.30 \\
 c_2 &= \frac{200}{k_2 J_1(k_2)} = \frac{200}{(5.52)(-0.34)} = -106.56 \\
 c_3 &= \frac{200}{k_3 J_1(k_3)} = \frac{200}{(8.65)(0.27)} = 85.635
 \end{aligned}$$

Evaluating  $u = \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-k_m z}$  for the first 3 terms when  $r = 1/2, z = 1$

$$\begin{aligned}
 u &= c_1 J_0(k_1 r) e^{-k_1 z} + c_2 J_0(k_2 r) e^{-k_2 z} + c_3 J_0(k_3 r) e^{-k_3 z} \\
 &= c_1 J_0\left(k_1 \frac{1}{2}\right) e^{-k_1} + c_2 J_0\left(k_2 \frac{1}{2}\right) e^{-k_2} + c_3 J_0\left(k_3 \frac{1}{2}\right) e^{-k_3} \\
 &= (160.30) J_0\left(2.404 \frac{1}{2}\right) e^{-2.404} - (106.56) J_0\left(5.52 \frac{1}{2}\right) e^{-5.52} + (85.635) J_0\left(8.65 \frac{1}{2}\right) e^{-8.65} \\
 &= (160.30) J_0(1.202) e^{-2.404} - (106.56) J_0(2.76) e^{-5.52} + (85.635) J_0(4.325) e^{-8.65}
 \end{aligned}$$

Mathematica was used to evaluate  $J_0$  values above.

```

In[40]:= BesselJ[0, 1.202]
Out[40]= 0.670136

In[41]:= BesselJ[0, 2.76]
Out[41]= -0.168385

In[42]:= BesselJ[0, 4.325]
Out[42]= -0.356614

```

Hence

$$u = (160.30)(0.67)e^{-2.404} - (106.56)(-0.168)e^{-5.52} + (85.635)(-0.356)e^{-8.65}$$

$$u = 9.7043 + 7.1713 \times 10^{-2} - 5.3389 \times 10^{-3}$$

$$u = 9.7707 \text{ degrees}$$

## 6 chapter 13, problem 5.2. Mary Boas, second edition

Find the solution for the steady state temp. distribution in a solid semi-infinite cylinder if the boundary temp. are  $u = 0$  at  $r = 1$  and  $u = y = r \sin \theta$  at  $z = 0$ .

### Solution

The candidate solutions are given by the solution to the Laplace equation in cylindrical coordinates which are

$$u = \begin{cases} J_n(k r) \sin(n\theta) e^{-k z} & (1) \\ J_n(k r) \cos(n\theta) e^{-k z} & (2) \end{cases}$$

Where  $k$  is a zero of  $J_n$  (This is because we have used the B.C. of  $u = 0$  at  $r = 1$  to determine that the  $k$ 's have to be the zeros of  $J_n$ ) when deriving the above solutions. See book page 560.

From boundary conditions we want  $u = r \sin \theta$  when  $z = 0$ , hence we need to keep the solution (1) above, with  $n = 1$ . Hence a solution is

$$u = J_1(k r) \sin(\theta) e^{-k z} \quad (3)$$

A general solution is a linear series combinations (eigenfunctions) of (3), each eigenfunction for each of the zeros of  $J_1$ . Call these zeros  $k_m$

$$u = \sum_{m=1}^{\infty} c_m J_1(k_m r) \sin(\theta) e^{-k_m z} \quad (4)$$

We now apply B.C. at  $z = 0$  to find  $c_m$ . From (4) when  $z = 0$

$$r \sin \theta = \sum_{m=1}^{\infty} c_m J_1(k_m r) \sin(\theta) \quad (5)$$

We use (5) to find  $c_m$  and then substitute into (4) to obtain the final solution.

To find  $c_m$  from (5), take the inner product of each side with respect to  $r J_1(k_u r)$  from  $r = 0$  to  $r = 1$

$$\begin{aligned} \int_0^1 r \sin \theta [r J_1(k_u r)] dr &= \sum_{m=1}^{\infty} c_m \left( \int_0^1 J_1(k_m r) \sin(\theta) [r J_1(k_u r)] dr \right) \\ \sin \theta \int_0^1 r^2 J_1(k_u r) dr &= \sum_{m=1}^{\infty} c_m \sin(\theta) \left( \int_0^1 J_1(k_m r) [r J_1(k_u r)] dr \right) \end{aligned}$$

Dividing each side by  $\sin \theta$

$$\int_0^1 r^2 J_1(k_u r) dr = \sum_{m=1}^{\infty} c_m \left( \int_0^1 J_1(k_m r) [r J_1(k_u r)] dr \right)$$

From orthogonality of Bessel function, we know that

$$\int_0^1 J_p(k_m r) r J_p(k_u r) dr = 0$$

If  $m \neq u$ . Hence in above equation all terms on the right drop except for one when  $u = m$ . We get

$$\int_0^1 r^2 J_1(k_m r) dr = c_m \int_0^1 r J_1(k_m r) J_1(k_m r) dr$$

Or

$$c_m = \frac{\int_0^1 r^2 J_1(k_m r) dr}{\int_0^1 r J_1(k_m r) J_1(k_m r) dr} \quad (6)$$

The integral in the denominator above is found from equation 19.10 in text on page 523 which gives

$$\int_0^1 r J_1(k_m r) J_1(k_m r) dr = \frac{1}{2} [J_2(k_m)]^2 \quad (7)$$

Now, we need to find the integral of the numerator in equation (6).

Using equation 15.1 in text, page 514, which says

$$\frac{d}{dx} [x^p J_p(x)] = x^p J_{p-1}(x)$$

Putting  $p = 2$  above, and letting  $x = k_m r$  gives

$$\begin{aligned} \frac{1}{k_m} \frac{d}{dr} [(k_m r)^2 J_2(k_m r)] &= (k_m r)^2 J_1(k_m r) \\ \frac{1}{k_m} \frac{d}{dr} [k_m^2 r^2 J_2(k_m r)] &= k_m^2 r^2 J_1(k_m r) \\ \frac{1}{k_m} \frac{d}{dr} [r^2 J_2(k_m r)] &= r^2 J_1(k_m r) \end{aligned}$$

Integrating each side w.r.t  $r$  from 0 ... 1

$$\begin{aligned}
 \frac{1}{k_m} \int_0^1 \frac{d}{dr} [r^2 J_2(k_m r)] dr &= \int_0^1 r^2 J_1(k_m r) dr \\
 \frac{1}{k_m} [r^2 J_2(k_m r)]_0^1 &= \int_0^1 r^2 J_1(k_m r) dr \\
 \frac{1}{k_m} [J_2(k_m) - 0] &= \int_0^1 r^2 J_1(k_m r) dr \\
 \frac{1}{k_m} J_2(k_m) &= \int_0^1 r^2 J_1(k_m r) dr \quad (8)
 \end{aligned}$$

Substituting (7) and (8) into (6)

$$\begin{aligned}
 c_m &= \frac{\int_0^1 r^2 J_1(k_m r) dr}{\int_0^1 r J_1(k_m r) J_1(k_m r) dr} \\
 &= \frac{\frac{1}{k_m} J_2(k_m)}{\frac{1}{2} [J_2(k_m)]^2} \\
 &= \frac{2}{k_m J_2(k_m)}
 \end{aligned}$$

Substituting this into (4) above, we get

$$\begin{aligned}
 u &= \sum_{m=1}^{\infty} c_m J_1(k_m r) \sin(\theta) e^{-k_m z} \\
 u &= \sum_{m=1}^{\infty} \frac{2}{k_m J_2(k_m)} J_1(k_m r) \sin(\theta) e^{-k_m z}
 \end{aligned}$$

where  $k_m$  are zeros of  $J_1$

The above is the result we are asked to show.



## 7 chapter 13, problem 5.4. Mary Boass, second edition

A flat circular plate of radius 1 is initially at temp.  $100^0$ . From  $t = 0$  on, the circumference of the plate is held at  $0^0$ . Find the time-dependent temp distribution  $u(r, \theta, t)$

Solution

First convert heat equation from Cartesian coordinates to polar.

heat equation in 2D Cartesian is

$$\nabla^2 u = \frac{\partial^2}{\partial x^2} u + \frac{\partial^2}{\partial y^2} u = \frac{1}{\alpha^2} \frac{\partial}{\partial t} u$$

First need to express Laplacian operator  $\nabla^2$  in polar coordinates:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

Hence

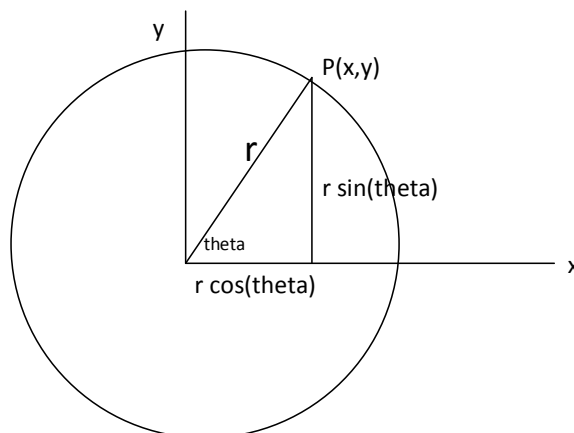
$$\frac{\partial x}{\partial r} = \cos \theta \tag{A}$$

$$\frac{\partial y}{\partial r} = \sin \theta$$

And

$$\frac{\partial x}{\partial \theta} = -r \sin \theta \tag{B}$$

$$\frac{\partial y}{\partial \theta} = r \cos \theta$$



From geometry, we also know that

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \arctan \frac{y}{x}$$

The above 2 relations imply

$$\frac{\partial}{\partial r} = \frac{\partial x}{\partial r} \frac{\partial}{\partial x} + \frac{\partial y}{\partial r} \frac{\partial}{\partial y} \quad \text{and} \quad \frac{\partial}{\partial \theta} = \frac{\partial x}{\partial \theta} \frac{\partial}{\partial x} + \frac{\partial y}{\partial \theta} \frac{\partial}{\partial y}$$

Hence we can express the above, using equations (A) and (B) as follows:

$$\begin{aligned} \frac{\partial}{\partial r} &= \frac{\partial x}{\partial r} \frac{\partial}{\partial x} + \frac{\partial y}{\partial r} \frac{\partial}{\partial y} \\ &= \cos \theta \frac{\partial}{\partial x} + \sin \theta \frac{\partial}{\partial y} \end{aligned}$$

Multiply each side by  $r$

$$\begin{aligned} r \frac{\partial}{\partial r} &= r \cos \theta \frac{\partial}{\partial x} + r \sin \theta \frac{\partial}{\partial y} \\ &= x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \end{aligned} \tag{1}$$

Squaring each sides of (1) gives

$$\begin{aligned} r \frac{\partial}{\partial r} \left( r \frac{\partial}{\partial r} \right) &= \left( x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)^2 \\ r \left( r \frac{\partial^2}{\partial r^2} + \frac{\partial}{\partial r} \right) &= x \frac{\partial}{\partial x} x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} y \frac{\partial}{\partial y} + 2x \frac{\partial}{\partial x} y \frac{\partial}{\partial y} \\ r^2 \frac{\partial^2}{\partial r^2} + r \frac{\partial}{\partial r} &= x \frac{\partial}{\partial x} \left( x \frac{\partial}{\partial x} \right) + y \frac{\partial}{\partial y} \left( y \frac{\partial}{\partial y} \right) + 2x \frac{\partial}{\partial x} \left( y \frac{\partial}{\partial y} \right) \\ &= x \left( x \frac{\partial^2}{\partial x^2} + \overset{=1}{\frac{\partial}{\partial x}} x \frac{\partial}{\partial x} \right) + y \left( y \frac{\partial^2}{\partial y^2} + \overset{=1}{\frac{\partial}{\partial y}} y \frac{\partial}{\partial y} \right) + 2x \left( y \frac{\partial^2}{\partial x \partial y} + \overset{=0}{\frac{\partial}{\partial x}} y \frac{\partial}{\partial y} \right) \\ &= x^2 \frac{\partial^2}{\partial x^2} + x \frac{\partial}{\partial x} + y^2 \frac{\partial^2}{\partial y^2} + y \frac{\partial}{\partial y} + 2xy \frac{\partial^2}{\partial x \partial y} \end{aligned} \tag{2}$$

Notice that when manipulating of differential operators,  $x \frac{\partial}{\partial x} \neq \frac{\partial}{\partial x} x$ . Similarly

$$\begin{aligned} \frac{\partial}{\partial \theta} &= \frac{\partial x}{\partial \theta} \frac{\partial}{\partial x} + \frac{\partial y}{\partial \theta} \frac{\partial}{\partial y} \\ &= -r \sin \theta \frac{\partial}{\partial x} + r \cos \theta \frac{\partial}{\partial y} \\ &= -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \end{aligned} \quad (3)$$

Squaring each side of (3) gives

$$\begin{aligned} \left( \frac{\partial}{\partial \theta} \right)^2 &= \left( -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right)^2 \\ \frac{\partial}{\partial \theta} \frac{\partial}{\partial \theta} &= -y \frac{\partial}{\partial x} \left( -y \frac{\partial}{\partial x} \right) + x \frac{\partial}{\partial y} \left( x \frac{\partial}{\partial y} \right) - y \frac{\partial}{\partial x} \left( x \frac{\partial}{\partial y} \right) + x \frac{\partial}{\partial y} \left( -y \frac{\partial}{\partial x} \right) \\ \frac{\partial^2}{\partial \theta^2} &= -y \left( -y \frac{\partial^2}{\partial x^2} + \overbrace{\frac{\partial}{\partial x} (-y)}^{=0} \frac{\partial}{\partial x} \right) + x \left( x \frac{\partial^2}{\partial y^2} + \overbrace{\frac{\partial}{\partial y} (x)}^{=0} \frac{\partial}{\partial y} \right) \\ &\quad - y \left( x \frac{\partial^2}{\partial y \partial x} + \overbrace{\frac{\partial}{\partial x} x}^{=1} \frac{\partial}{\partial y} \right) + x \left( -y \frac{\partial^2}{\partial x \partial y} + \overbrace{\frac{\partial}{\partial y} y}^{=1} \frac{\partial}{\partial x} \right) \\ &= y^2 \frac{\partial^2}{\partial x^2} + x^2 \frac{\partial^2}{\partial y^2} - yx \frac{\partial^2}{\partial y \partial x} - y \frac{\partial}{\partial y} - xy \frac{\partial^2}{\partial x \partial y} - x \frac{\partial}{\partial x} \\ &= y^2 \frac{\partial^2}{\partial x^2} + x^2 \frac{\partial^2}{\partial y^2} - 2yx \frac{\partial^2}{\partial y \partial x} - y \frac{\partial}{\partial y} - x \frac{\partial}{\partial x} \end{aligned} \quad (4)$$

Adding equation (2) and (4) and carry cancellations

$$\begin{aligned} r^2 \frac{\partial^2}{\partial r^2} + r \frac{\partial}{\partial r} + \frac{\partial^2}{\partial \theta^2} &= \left( x^2 \frac{\partial^2}{\partial x^2} + x \frac{\partial}{\partial x} + y^2 \frac{\partial^2}{\partial y^2} + y \frac{\partial}{\partial y} + 2xy \frac{\partial^2}{\partial x \partial y} \right) + \left( y^2 \frac{\partial^2}{\partial x^2} + x^2 \frac{\partial^2}{\partial y^2} - 2yx \frac{\partial^2}{\partial y \partial x} - y \frac{\partial}{\partial y} - x \frac{\partial}{\partial x} \right) \\ r^2 \frac{\partial^2}{\partial r^2} + r \frac{\partial}{\partial r} + \frac{\partial^2}{\partial \theta^2} &= \left( x^2 \frac{\partial^2}{\partial x^2} + y^2 \frac{\partial^2}{\partial y^2} \right) + \left( y^2 \frac{\partial^2}{\partial x^2} + x^2 \frac{\partial^2}{\partial y^2} \right) \end{aligned}$$

Hence we get

$$\begin{aligned} r^2 \frac{\partial^2}{\partial r^2} + r \frac{\partial}{\partial r} + \frac{\partial^2}{\partial \theta^2} &= x^2 \frac{\partial^2}{\partial x^2} + y^2 \frac{\partial^2}{\partial y^2} + y^2 \frac{\partial^2}{\partial x^2} + x^2 \frac{\partial^2}{\partial y^2} \\ &= (x^2 + y^2) \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \end{aligned}$$

Dividing by  $r^2$

$$\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} = \frac{(x^2 + y^2)}{r^2} \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)$$

But  $r^2 = x^2 + y^2$  hence

$$\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} = \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) = \nabla^2$$

Now that we have the Laplacian in polar coordinates, we can solve the problem by applying separation of variables on the heat PDE expressed in polar coordinates.

$$\frac{\partial^2}{\partial r^2} u + \frac{1}{r} \frac{\partial}{\partial r} u + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} u = \frac{1}{\alpha^2} \frac{\partial}{\partial t} u \quad (5)$$

Let solution  $u(r, \theta, t)$  be a linear combination of functions each depends on only  $r$ ,  $\theta$ , or  $t$

$$u(r, \theta, t) = R(r)\Theta(\theta)T(t) \quad (6)$$

Substitute (6) in (5). First evaluate the various derivatives:

$$\frac{\partial}{\partial r} u = \Theta(\theta)T(t) \frac{\partial}{\partial r} R(r)$$

$$\frac{\partial^2}{\partial r^2} u = \Theta(\theta)T(t) \frac{\partial^2}{\partial r^2} R(r)$$

$$\frac{\partial}{\partial \theta} u = R(r)T(t) \frac{\partial}{\partial \theta} \Theta(\theta)$$

$$\frac{\partial^2}{\partial \theta^2} u = R(r)T(t) \frac{\partial^2}{\partial \theta^2} \Theta(\theta)$$

$$\frac{\partial}{\partial t}u = R(r)\Theta(\theta)\frac{\partial}{\partial t}T(t)$$

Hence equation (5) becomes

$$\frac{\partial^2}{\partial r^2}u + \frac{1}{r}\frac{\partial}{\partial r}u + \frac{1}{r^2}\frac{\partial^2}{\partial \theta^2}u = \frac{1}{\alpha^2}\frac{\partial}{\partial t}u$$

$$\Theta(\theta)T(t)\frac{d^2}{dr^2}R(r) + \frac{1}{r}\Theta(\theta)T(t)\frac{d}{dr}R(r) + \frac{1}{r^2}R(r)T(t)\frac{d^2}{d\theta^2}\Theta(\theta) = \frac{1}{\alpha^2}R(r)\Theta(\theta)\frac{d}{dt}T(t)$$

Divide by  $R(r)\Theta(\theta)T(t)$

$$\frac{1}{R(r)}\frac{d^2}{dr^2}R(r) + \frac{1}{r}\frac{1}{R(r)}\frac{d}{dr}R(r) + \frac{1}{r^2}\frac{1}{\Theta(\theta)}\frac{d^2}{d\theta^2}\Theta(\theta) = \frac{1}{\alpha^2}\frac{1}{T(t)}\frac{d}{dt}T(t)$$

$$\frac{1}{R(r)}\left[\frac{d^2}{dr^2}R(r) + \frac{1}{r}\frac{d}{dr}R(r)\right] + \frac{1}{r^2}\frac{1}{\Theta(\theta)}\frac{d^2}{d\theta^2}\Theta(\theta) = \frac{1}{\alpha^2}\frac{1}{T(t)}\frac{d}{dt}T(t)$$

We notice that the RHS depends only on  $t$  and the LHS depends only on  $r, \theta$  and they equal to each others, hence they both must be constant. Let this constant be  $-k^2$

Hence

$$\frac{1}{\alpha^2}\frac{1}{T(t)}\frac{d}{dt}T(t) = -k^2 \quad (7)$$

$$\frac{1}{R(r)}\left[\frac{d^2}{dr^2}R(r) + \frac{1}{r}\frac{d}{dr}R(r)\right] + \frac{1}{r^2}\frac{1}{\Theta(\theta)}\frac{d^2}{d\theta^2}\Theta(\theta) = -k^2 \quad (8)$$

equation (7) is a linear first order ODE with constant coeff.  $\frac{d}{dt}T(t) = -\alpha^2T(t)k^2$  or  $\frac{dT(t)}{T(t)} = -\alpha^2k^2dt$

Integrating to solve gives

$$\int \frac{dT(t)}{T(t)} = \int -\alpha^2k^2dt$$

$$\ln T(t) = -\alpha^2k^2t$$

or

$$T(t) = e^{-\alpha^2k^2t} \quad (9)$$

Looking at equation (8). Multiply each sides by  $r^2$  we get

$$\begin{aligned} \frac{r^2}{R(r)} \left[ \frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= -r^2 k^2 \\ \frac{r^2}{R(r)} \left[ \frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + r^2 k + \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= 0 \\ r^2 \left( \frac{1}{R(r)} \left[ \frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + k^2 \right) + \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= 0 \end{aligned} \quad (10)$$

The second term depends only on  $\theta$  and the first term depends only on  $r$  and they are equal, hence they must be both constant. Let this constant be  $-n^2$  hence

$$\begin{aligned} \frac{1}{\Theta(\theta)} \frac{d^2}{d\theta^2} \Theta(\theta) &= -n^2 \\ \frac{d^2}{d\theta^2} \Theta(\theta) &= -n^2 \Theta(\theta) \end{aligned}$$

This is a second order linear ODE with constant coeff. Solution is

$$\Theta(\theta) = \begin{cases} \sin n\theta \\ \cos n\theta \end{cases} \quad (11)$$

From (10) we now have

$$\begin{aligned} r^2 \left( \frac{1}{R(r)} \left[ \frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + k^2 \right) - n^2 &= 0 \\ \frac{r^2}{R(r)} \left[ \frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + r^2 k^2 - n^2 &= 0 \\ r^2 \left[ \frac{d^2}{dr^2} R(r) + \frac{1}{r} \frac{d}{dr} R(r) \right] + (r^2 k^2 - n^2) R(r) &= 0 \\ r^2 \frac{d^2}{dr^2} R(r) + r \frac{d}{dr} R(r) + (r^2 k^2 - n^2) R(r) &= 0 \end{aligned} \quad (12)$$

Equation (12) is the Bessel D.E., its solutions are  $J_n(kr)$  and  $N_n(kr)$ . As described on book on page 560, we can not use the  $N_n(kr)$  solution since plate contains the origin and  $N_n(0)$  is not defined. So we use solution  $R(r) = J_n(kr)$ . From boundary conditions, we want solution to be zero at  $r = 1$ , hence we want  $J_n(k) = 0$ , hence the  $k$ 's are the zeros of  $J_n$

Putting these solutions together, we get from (6)

$$u(r, \theta, t) = R(r)\Theta(\theta)T(t) = \begin{cases} J_n(kr) \sin n\theta e^{-\alpha^2 k^2 t} \\ J_n(kr) \cos n\theta e^{-\alpha^2 k^2 t} \end{cases}$$

From symmetry of plate, the solution can not depend on the angle  $\theta$ , hence let  $n = 0$  and so as not to get  $u = 0$ , we must pick the solution with  $\cos n\theta$  term. Hence our solution now is

$$u(r, t) = J_0(kr) e^{-\alpha^2 k^2 t}$$

Where  $k$  is a zero of  $J_0$

The general solution is a linear combination of this eigenfunction for all zeros of  $J_0$ , hence

$$u(r, t) = \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-\alpha^2 k_m^2 t} \quad (13)$$

We find  $c_m$  by using initial condition. When  $t = 0$ , temp. was  $100^0$  hence

$$100 = \sum_{m=1}^{\infty} c_m J_0(k_m r)$$

Applying inner product w.r.t.  $rJ_0(k_u r)$  from 0 ... 1

$$\begin{aligned} \int_0^1 100 rJ_0(k_u r) dr &= \int_0^1 \left( \sum_{m=1}^{\infty} c_m J_0(k_m r) \right) rJ_0(k_u r) dr \\ 100 \int_0^1 rJ_0(k_u r) dr &= \sum_{m=1}^{\infty} c_m \int_0^1 J_0(k_m r) rJ_0(k_u r) dr \end{aligned}$$

From orthogonality of  $J_0(k_m r)$  and  $J_0(k_u r)$ , all terms drop expect when  $m = u$

$$100 \int_0^1 rJ_0(k_u r) dr = c_u \int_0^1 r[J_0(k_u r)]^2 dr$$



From here we can follow the book on page 561 to get

$$c_m = \frac{200}{k_m J_1(k_m)}$$

Substitute this in equation 13

$$\begin{aligned} u(r, t) &= \sum_{m=1}^{\infty} c_m J_0(k_m r) e^{-\alpha^2 k_m^2 t} \\ &= \sum_{m=1}^{\infty} \frac{200}{k_m J_1(k_m)} J_0(k_m r) e^{-\alpha^2 k_m^2 t} \\ &= 200 \sum_{m=1}^{\infty} \frac{1}{k_m J_1(k_m)} J_0(k_m r) e^{-\alpha^2 k_m^2 t} \end{aligned}$$

Where  $k_m$  are zeros of  $J_0$

Notice that final solution does not depend on  $\theta$

## 8 chapter 13, problem 5.11. Mary Boas, second edition

Solve

$$r \frac{d}{dr} \left( r \frac{dR}{dr} \right) = n^2 R$$

$$\frac{d}{dr} \left( r^2 \frac{dR}{dr} \right) = l(l+1)R$$

Solution

First equation, use power series method.

$$r \frac{d}{dr} \left( r \frac{dR}{dr} \right) = n^2 R$$

$$r \left( r \frac{d^2 R}{dr^2} + \frac{dR}{dr} \right) - n^2 R = 0$$

$$r^2 \frac{d^2 R}{dr^2} + r \frac{dR}{dr} - n^2 R = 0$$

Let  $R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$  then

$$R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$$

$$-n^2 R = -n^2 a_0 r^s - n^2 a_1 r^{s+1} - n^2 a_2 r^{s+2} - n^2 a_3 r^{s+3} - n^2 a_4 r^{s+4} - \dots$$

$$\frac{dR}{dr} = s a_0 r^{s-1} + (s+1) a_1 r^s + (s+2) a_2 r^{s+1} + (s+3) a_3 r^{s+2} + \dots$$

$$r \frac{dR}{dr} = s a_0 r^s + (s+1) a_1 r^{s+1} + (s+2) a_2 r^{s+2} + (s+3) a_3 r^{s+3} + \dots$$

$$\frac{d^2 R}{dr^2} = (s-1)s a_0 r^{s-2} + s(s+1) a_1 r^{s-1} + (s+1)(s+2) a_2 r^s + (s+2)(s+3) a_3 r^{s+1} + \dots$$

$$r^2 \frac{d^2 R}{dr^2} = (s-1)s a_0 r^s + s(s+1) a_1 r^{s+1} + (s+1)(s+2) a_2 r^{s+2} + (s+2)(s+3) a_3 r^{s+3} + \dots$$

Table is

	$r^s$	$r^{s+1}$	$r^{s+2}$	$r^{s+m}$
$-n^2 R$	$-n^2 a_0$	$-n^2 a_1$	$-n^2 a_2$	$-n^2 a_m$
$r \frac{dR}{dr}$	$s a_0$	$(s+1) a_1$	$(s+2) a_2$	$(s+m) a_m$
$r^2 \frac{d^2 R}{dr^2}$	$(s-1)s a_0$	$s(s+1) a_1$	$(s+1)(s+2) a_2$	$(s+m-1)(s+m) a_m$

Hence, from first column we see , and since  $a_0 \neq 0$  we solve for  $s$

$$\begin{aligned} -n^2 a_0 + s a_0 + (s-1)s a_0 &= 0 \\ a_0(-n^2 + s + (s-1)s) &= 0 \\ -n^2 + s + (s-1)s &= 0 \\ -n^2 + s^2 &= 0 \\ s &= \pm n \end{aligned}$$

We see from second column,  $a_1(-n^2 + (s+1) + s^2 + s) = 0$  or  $a_1(-s^2 + 2s + 1 + s^2) = 0$ , hence  $a_1(2s + 1) = 0$

For  $a_1 \neq 0$  then  $s = -\frac{1}{2}$ , this means  $n$  is not an integer since  $s = \pm n$ . hence  $a_1$  must be zero.

The same applies to all  $a_m, m > 0$  Hence solution contains only  $a_0$

$$R = a_0 r^{\pm n}$$

$$R = \begin{cases} a_0 r^{-n} \\ a_0 r^{+n} \end{cases}$$

For some constant  $a_0$ . This solution is when  $n \neq 0$

If  $n = 0$ , table is

	$r^s$	$r^{s+1}$	$r^{s+2}$	$r^{s+m}$
$-n^2 R$	0	0	0	0
$r \frac{dR}{dr}$	$s a_0$	$(s+1) a_1$	$(s+2) a_2$	$(s+m) a_m$
$r^2 \frac{d^2 R}{dr^2}$	$(s-1)s a_0$	$s(s+1) a_1$	$(s+1)(s+2) a_2$	$(s+m-1)(s+m) a_m$

From first column:

$$\begin{aligned} s a_0 + s^2 a_0 - s a_0 &= 0 \\ a_0(s + s^2 - s) &= 0 \\ s^2 &= 0 \\ s &= 0 \end{aligned}$$

And all other  $a$ 's are zero. Hence  $R = a_0$  or  $R$  is constant.

Now for the second ODE

$$\frac{d}{dr} \left( r^2 \frac{dR}{dr} \right) = l(l+1)R$$

$$r^2 \frac{d^2 R}{dr^2} + 2r \frac{dR}{dr} - l(l+1)R = 0$$

Let  $R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$  then

$$R = a_0 r^s + a_1 r^{s+1} + a_2 r^{s+2} + a_3 r^{s+3} + a_4 r^{s+4} + \dots$$

$$-l(l+1)R = -l(l+1)a_0 r^s - l(l+1)a_1 r^{s+1} - l(l+1)a_2 r^{s+2} - l(l+1)a_3 r^{s+3} - l(l+1)a_4 r^{s+4} - \dots$$

$$\frac{dR}{dr} = s a_0 r^{s-1} + (s+1) a_1 r^s + (s+2) a_2 r^{s+1} + (s+3) a_3 r^{s+2} + \dots$$

$$2r \frac{dR}{dr} = 2s a_0 r^s + 2(s+1) a_1 r^{s+1} + 2(s+2) a_2 r^{s+2} + 2(s+3) a_3 r^{s+3} + \dots$$

$$\frac{d^2 R}{dr^2} = (s-1)s a_0 r^{s-2} + s(s+1) a_1 r^{s-1} + (s+1)(s+2) a_2 r^s + (s+2)(s+3) a_3 r^{s+1} + \dots$$

$$r^2 \frac{d^2 R}{dr^2} = (s-1)s a_0 r^s + s(s+1) a_1 r^{s+1} + (s+1)(s+2) a_2 r^{s+2} + (s+2)(s+3) a_3 r^{s+3} + \dots$$

Table is

	$r^s$	$r^{s+1}$	$r^{s+2}$	$r^{s+m}$
$-l(l+1)R$	$-l(l+1)a_0$	$-l(l+1)a_1$	$-l(l+1)a_2$	$-l(l+1)a_m$
$2r \frac{dR}{dr}$	$2s a_0$	$2(s+1) a_1$	$2(s+2) a_2$	$2(s+m)a_m$
$r^2 \frac{d^2 R}{dr^2}$	$(s-1)s a_0$	$s(s+1) a_1$	$(s+1)(s+2) a_2$	$(s+m-1)(s+m) a_m$

From first column:

$$-l(l+1)a_0 + 2s a_0 + (s-1)s a_0 = 0$$

$$a_0(-l(l+1) + 2s + (s-1)s) = 0$$

$$-l(l+1) + 2s + (s-1)s = 0$$

$$-l(l+1) + s + s^2 = 0$$

$$(s-l)(s-(-l-1)) = 0$$

Hence  $s = l$  or  $s = -l - 1$ .

We also see that all other  $a$ 's will be zero, since recursive formula has only  $a_m$  in it and no other  $a$ . Hence

$$R = a_0 r^s$$
$$R = \begin{cases} a_0 r^l \\ a_0 r^{-l-1} \end{cases}$$

For some constant  $a_0$