

Random Signals

All useful message signals appear random to the receiver, since the receiver does not know, a priori, which of the possible message signals will be transmitted. Also, the noise superimposed to the desired signal is random. Therefore, we need an efficient description of random signals.

properties of a random variable, x :

1) The distribution function $F_x(x)$ of the random variable x is given by:

$$F_x(x) \equiv \text{Pr}[x \leq x] \quad (33)$$

This is the probability that the value taken by the R.V. x is less than or equal to a real number x .

$F_x(x)$ has the following properties:

a) $0 \leq F_x(x) \leq 1$

b) $F_x(x_1) \leq F_x(x_2)$ if $x_1 \leq x_2$

c) $F_x(-\infty) = 0$

d) $F_x(+\infty) = 1$

2) probability density function (PDF) of the random variable x ; $f_x(x)$:

The pdf and the distribution function of the R.V X are related to each other by:

$$f_x(x) = \frac{dF_x(x)}{dx} \quad (34) \quad \text{or}$$

$$F_x(x) = \int_{-\infty}^x f_x(x_1) dx_1 \quad (35)$$

Thus:

$$\begin{aligned} P[x_1 \leq X \leq x_2] &= P[X \leq x_2] - P[X \leq x_1] \\ &= F_x(x_2) - F_x(x_1) = \int_{x_1}^{x_2} f_x(x) dx \end{aligned} \quad (36)$$

Properties of $f_x(x)$

a) $f_x(x) \geq 0$

b) $\int_{-\infty}^{+\infty} f_x(x) dx = 1$

3) Ensemble Averages:

a) The mean value m_x , of a ^{continuous} random variable X , is defined by:

$$m_x \equiv E\{X\} = \int_{-\infty}^{+\infty} x f_x(x) dx \quad (37)$$

b) The m th moment:

$$E\{X^m\} \equiv \int_{-\infty}^{+\infty} x^m f_x(x) dx \quad (38)$$

c) The mean square value or the power

$$P = E\{x^2\} = \int_{-\infty}^{+\infty} x^2 f_x(x) dx \quad (39)$$

d) Variance of the R.V. x ;

$$\sigma_x^2 = \text{Var}[x] = E\{(x - m_x)^2\} = \int_{-\infty}^{+\infty} (x - m_x)^2 f_x(x) dx \quad (40)$$

The variance σ_x^2 is a measure of the ^{the} randomness of the random variable x .

e) One can verify that:

$$\sigma_x^2 = E\{x^2\} - m_x^2 \quad (41) \quad \text{where:}$$

$E\{x^2\}$ represents the total power (avg)

m_x^2 " " the DC power and

σ_x^2 " " AC power (avg)

$$\begin{aligned} E\{(x - \mu)^2\} &= E\{x^2 + \mu^2 - 2x\mu\} \\ &= E\{x^2\} + E\{\mu^2\} - 2\mu E\{x\} \\ &= E\{x^2\} + \mu^2 - 2\mu^2 \end{aligned}$$

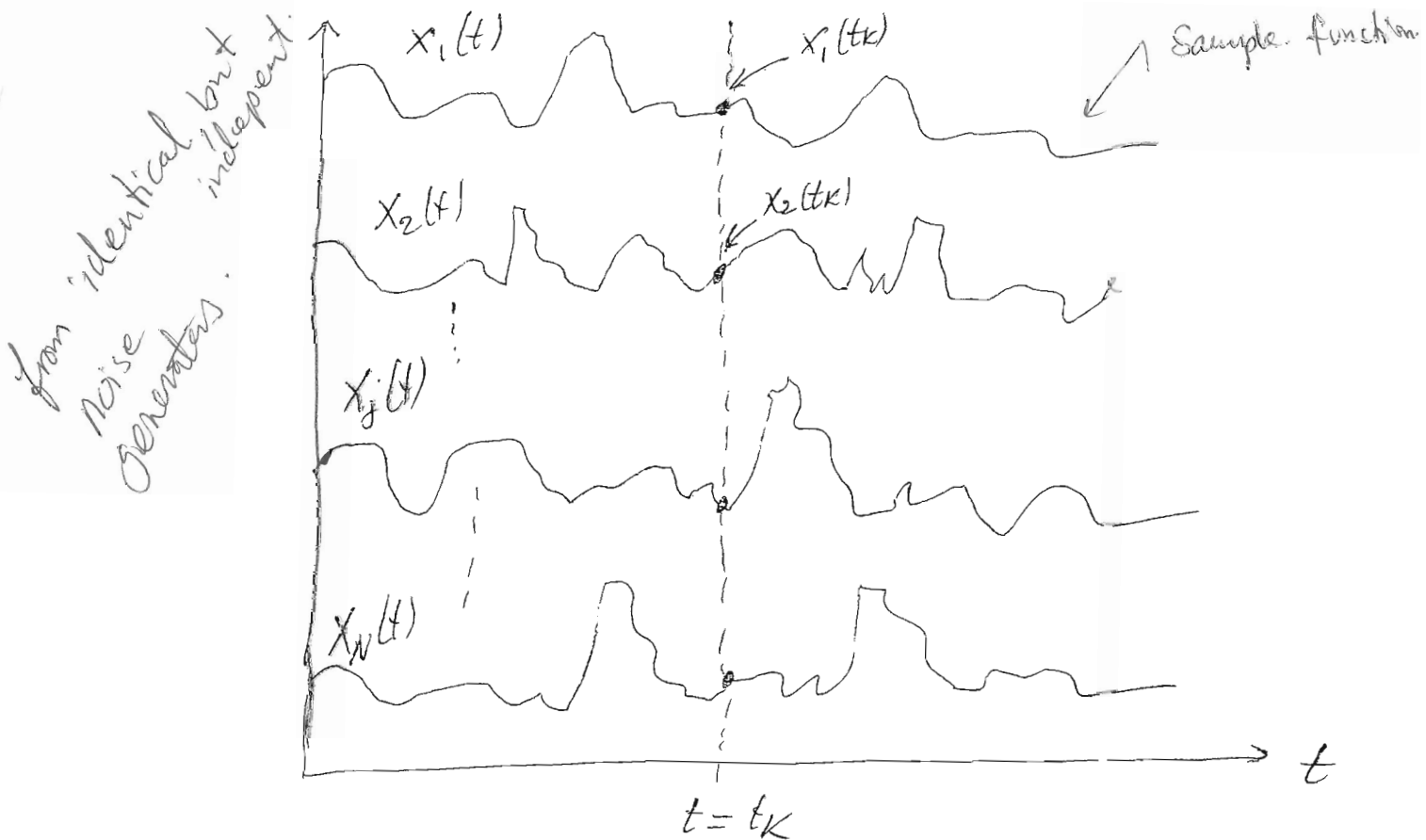
4) Random Processes (R.P.)

A random process $X(A, t)$ is a function of two variables: a random event A and time. The

following figure shows a R.P., which consist of N sample functions of time, $\{x_j(t)\}$. Each of the sample function can be viewed as the output of a different noise generator (that is distinct but identical noise generators).

- For a specific event A_j , that is when the event A_j is known, we have a single function of time (sample function) $x(A_j, t) \equiv x_j(t)$. The totality of all sample functions is called an ensemble or R.P.
- For a specific time t_k , $x(A, t_k)$ is a random variable $x(t_k)$ whose value depends on the event.
- For a specific event $A = A_j$ and a specific time $t = t_k$, $x(A_j, t_k)$ is a number.

From now on we will use $x(t)$ to describe the R.P. $x(A, t)$.



Random Noise Process

next time

statistical Averages of a Random Process:

Because the value of a R.P. at any future time is unknown, a R.P. whose distribution function are continuous can be described statistically with a prob. density function (pdf). In general the form of the pdf of a R.P. will be different at different times. In most cases it is not possible to determine empirically the probability distribution function of a R.P. However, a partial description consisting of its mean and its autocorrelation function are sufficient for the needs of communication systems.

we define the mean of the R.P. $x(t)$ as:

$$m_x(t_k) = E \{ x(t_k) \} = \int_{-\infty}^{+\infty} \omega e f_{x_k}(\omega e) d\omega e. \quad (42)$$

where $x(t_k)$ is the Random Variable obtained by observing the R.P. at time $t = t_k$ and $f_{x_k}(\omega e)$ is the pdf over the ensemble of events at $t = t_k$.

b) Autocorrelation function of the R.P. $x(t)$:

$$R_x(t_1, t_2) = E \{ x(t_1) x(t_2) \} \quad (43)$$

where $x(t_1)$ and $x(t_2)$ are R. Variables obtained by observing the R.P. $x(t)$ at time t_1 and t_2 .

$R_x(t_1, t_2)$ is a measure of similarity of the two samples $x(t_1)$ and $x(t_2)$ of the same R.P.

Stationarity:

(Time Invariant?)

a) A R.P. $x(t)$ is said to be stationary in strict sense (SSS) if none of its statistics are affected by a shift in the time origin.

b) A R.P. $x(t)$ is said to be stationary in wide sense (WSS) if its mean and its autocorrelation function do not change with a shift in the time origin. That is:

$$E\{x(t)\} = m_x = \text{constant}$$

$$R_x(t_1, t_2) = R_x(t_2 - t_1) \triangleq R_x(\tau)$$

Note that: (SSS) $\xrightarrow{\text{if}}$ WSS

The autocorrelation of WSS is defined as:

$$R_x(\tau) \triangleq E\{x(t)x^*(t+\tau)\} \quad \text{or}$$

$$R_x(\tau) \triangleq E\{x(t)x^*(t-\tau)\} \quad (44)$$

Properties of $R_x(\tau)$ for WSS:

1) $R_x(\tau) = R_x(-\tau)$: If the R.P. $x(t)$ is real, then $R_x(\tau)$ is real and even.

2) $R_x(\tau) \leq R_x(0)$

3) $R_x(\tau) \xleftrightarrow{\text{F.T.}} S_x(f)$ P.S.D

4) $R_x(0) = E\{x^2(t)\} \triangleq P_{av}$

Time Averaging and Ergodicity:

To find m_x and $R_x(\tau)$ by ensemble averaging, we ^{have} to average over all sample functions of the R.P. This would require the knowledge of I^0 and I^2 order joint probability density functions, which are not generally available.

We will consider a particular class of R.P. known as ergodic process, where its time averages equal its ensemble averages, and its statistical properties can be obtained by time averaging a single sample function of the process. Note for a R.P. to be ergodic it must be SSS.

a) we say a R.P. $x(t)$ is ergodic in mean if and only if:

$$m_x = E\{x(t)\} = \langle x(t) \rangle \quad (45) \quad \text{where}$$

$$E\{x(t)\} = \int_{-\infty}^{+\infty} \rho_x(x) f(x) dx \quad (46) \quad \text{ensemble average}$$

$$\langle x(t) \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt \quad (47) \quad \text{time average}$$

b) we say a R.P. $x(t)$ is ergodic in autocorrelation iff:

$$E\{x(t)x(t+\tau)\} = \langle x(t)x(t+\tau) \rangle \quad (48)$$

where:

$$R_x(\tau) = E\{x(t)x(t+\tau)\} = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \rho_{xy}(x,y) f(x,y) dx dy \quad (49)$$

$$R_x(\tau) = \langle x(t)x(t+\tau) \rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t)x(t+\tau) dt$$

For an ergodic process, fundamental electrical engineering parameters, such as dc value, rms value, and average power can be related to the moments of an ergodic process:

- $m_x = E\{x(t)\}$ is the dc level of the signal
- m_x^2 is the normalized power in the dc component
- $E\{x^2(t)\}$ is the total average normalized power
- $\sqrt{E\{x^2(t)\}}$ is the root mean square (RMS) value
- σ_x^2 is the variance or the average normalized power in the ac component. where $\sigma_x^2 = E\{x^2(t)\} - m_x^2$.

Properties of the P.S.D of a R.P. $x(t)$

If the process $x(t)$ is real then:

- $S_x(f) \geq 0$ and is always real valued.
- $S_x(f) = S_x(-f)$
- $S_x(f) \xleftrightarrow{FT} R_x(\tau)$
- $P_x = \int_{-\infty}^{+\infty} S(f) df = R_x(0)$

Example: consider the sample function $x(t) = A \cos(\omega_0 t + \theta)$ where A and ω_0 are constant and θ is a random variable uniformly distributed over $(0, 2\pi)$, that is:

$$f_p(\alpha) = \begin{cases} \frac{1}{2\pi} & 0 \leq \alpha \leq 2\pi \\ 0 & \text{otherwise} \end{cases}$$

a) verify that $x(t)$ is ergodic in mean.

b) " " " " " " autocorrelation.

$$\begin{aligned} a) \quad m_x &= E\{x(t)\} = \int_{-\infty}^{+\infty} A \cos(\omega t + \alpha) f_p(\alpha) d\alpha \\ &= \frac{A}{2\pi} \int_{-\infty}^{+\infty} \cos(\omega t + \alpha) d\alpha = 0 \end{aligned}$$

$$\begin{aligned} \langle x(t) \rangle &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} A \cos(\omega t + \theta) dt \\ &= \lim_{T \rightarrow \infty} \frac{A}{T} \cdot \frac{1}{2\pi f_0} \left[\text{Sin}(2\pi f_0 t + \theta) \right]_{-T/2}^{T/2} \\ &= \lim_{T \rightarrow \infty} \frac{A}{T} \cdot \frac{1}{2\pi f_0} \underbrace{\left\{ \text{Sin}(\pi f_0 T + \theta) - \text{Sin}(-\pi f_0 T + \theta) \right\}}_{\leq 2} = 0 \end{aligned}$$

Thus $E\{x(t)\} = \langle x(t) \rangle \Rightarrow$ Ergodic in mean.

b)

$$\begin{aligned} R_x(\tau) &= E\{x(t)x(t+\tau)\} \\ &= E\{A^2 \cos(2\pi f_0 t + \theta) \cos(2\pi f_0 t + 2\pi f_0 \tau + \theta)\} \end{aligned}$$