

```

ClearAll[x1, x2, θ1, θ2, t]
T1 =  $\frac{1}{2} m1 (x1'[t]^2 + ((L + x1[t]) \theta1'[t])^2);$ 
v1 = -m1 g (L + x1[t]) Cos[θ1[t]] + 1/2 k1 x1[t]^2;
T2 =
 $\frac{1}{2} m2 ((x2'[t] + x1'[t] \text{Cos}[\theta1[t] - \theta2[t]])^2 + (x1'[t] \text{Sin}[\theta1[t] - \theta2[t]])^2) +$ 
 $\frac{1}{2} m2 (((L + x2[t]) \theta2'[t] + ((L + x1[t]) \theta1'[t] \text{Cos}[\theta1[t] - \theta2[t]]))^2 +$ 
 $((L + x1[t]) \theta1'[t] \text{Sin}[\theta1[t] - \theta2[t]])^2);$ 
v2 = -m2 g ((L + x1[t]) Cos[θ1[t]] + (L + x2[t]) Cos[θ2[t]]) + 1/2 k2 x2[t]^2;

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(\*Lagrangian\*)

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In[71]:= (lag = (T1 + T2) - (v1 + v2)) // Simplify
Out[71]=  $\frac{1}{2} (-k1 x1[t]^2 + 2 g m1 \text{Cos}[\theta1[t]] (L + x1[t]) - k2 x2[t]^2 +$ 
 $2 g m2 (\text{Cos}[\theta1[t]] (L + x1[t]) + \text{Cos}[\theta2[t]] (L + x2[t])) +$ 
 $m2 (x1'[t]^2 + 2 \text{Cos}[\theta1[t] - \theta2[t]] x1'[t] x2'[t] + x2'[t]^2) +$ 
 $m1 (x1'[t]^2 + (L + x1[t])^2 \theta1'[t]^2) + m2 (\text{Sin}[\theta1[t] - \theta2[t]]^2 (L + x1[t])^2 \theta1'[t]^2 +$ 
 $(\text{Cos}[\theta1[t] - \theta2[t]] (L + x1[t]) \theta1'[t] + (L + x2[t]) \theta2'[t])^2)$ 

```

(\*x1 \*)

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In[72]:= (eq1 = D[D[lag, x1'[t]], t] - D[lag, x1[t]] == 0) // Simplify
```

(\*x2\*)

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In[73]:= (eq2 = D[D[lag, x2'[t]], t] - D[lag, x2[t]] == 0) // Simplify
```

(\*theta 1\*)

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In[75]:= (eq3 = D[D[lag, θ1'[t]], t] - D[lag, θ1[t]] == 0) // Simplify
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In[76]:= (eq4 = D[D[lag, θ2'[t]], t] - D[lag, θ2[t]] == 0) // Simplify
```

(\*Numerically solve the equations of motion\*)

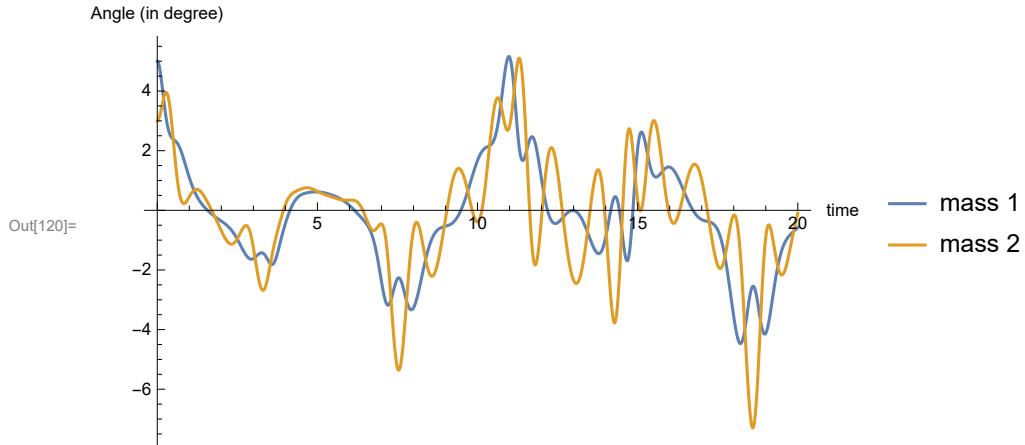
```

pars = {L → 1, m1 → 1, m2 → 2, g → 9.8, k1 → 10, k2 → 30};
ic = {θ1[0] == 5 Degree, θ1'[0] == 0, θ2[0] == 3 Degree,
      θ2'[0] == 0, x1[0] == 0, x1'[0] == 0, x2[0] == 0, x2'[0] == 0};
eqs = Flatten[{eq1, eq2, eq3, eq4}] /. pars

```

```
In[122]:= numericalSolution = First@NDSolve[{eqs, ic}, {x1, x2, θ1, θ2}, {t, 0, 20}];
```

```
In[120]:= Plot[Evaluate[({θ1[t], θ2[t]} /. numericalSolution) * 180/Pi],
{t, 0, 20}, PlotRange → All, AxesLabel → {"time", "Angle (in degree)" },
ImageSize → 400, PlotLegends → {"mass 1", "mass 2"}]
```



```
In[121]:= Plot[Evaluate[{x1[t], x2[t]} /. numericalSolution], {t, 0, 20},
PlotRange → All, AxesLabel → {"time", "spring extensions in meters" },
ImageSize → 400, PlotLegends → {"mass 1", "mass 2"}]
```

