HW 1 Mathematics 503, Mathematical Modeling, CSUF June 2 2007

Nasser M. Abbasi

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1 Problem 1 (section 1.1,#3, page 7)

problem:

In the blast wave problem take $C = 1$ (a v $3.$ and use $\rho = 1.25 \text{ kg/m}^3$. Some of the radiu data for the Trinity explosion is given in the

> t 0.10 0.52 1.08 1.5 1.93 11.1 28.2 38.9 44.4 48.7 r

Using these data, estimate the yield of the T kiloton equals $4.186(10)^{12}$ joules). Compare y of approximately 21 kilotons.

solution:

The blast equation is given by

$$
r = C \left(\frac{Et^2}{\rho}\right)^{\frac{1}{5}}
$$

Where *r* is radius of blast in meters, *t* is time since explosion in seconds, *E* energy of explosion in Joules, ρ is air density in Kg/m^{γ 3}

We are given $\rho = 1.25 \frac{kg}{m^3}$ and $C = 1$, hence the above can be rewritten as

 $r^5 = 0.8Et^2$

Let $x = E$, $A = 0.8t^2$, $b = r^5$, then we have

 $b = Ax$

And now *x* is found by least squares solution. Once *x* is found, then *E* is found since $E = x$. The code is shown on the next page. The least squares solutions shows that

 $E = 16.6175$ kilotons

Problem 1 (#3, section 1.1, page 7) Code implementation by Nasser Abb Modeling. CSUF Summer 2007. Use LeastSquare to fit data to find Energ

```
Remove['Global.*"];
eq = r = C \left( \frac{\text{energy} \cdot t^2}{2} \right)^{\frac{1}{5}}
```
Formulate the data points

```
timePtsInMs = \{0.1, 0.52, 1.08, 1.5, 1.93, 4.07, 15.0, 34.0\};timePtsInSec = timePtsInMs * 0.001;A = 0.8 * timePtsInSec<sup>2</sup>;
```

```
rPtsInMeter = \{11.1, 28.2, 38.9, 44.4, 48.7, 64.3, 106.5, 145\};b = rPtsInMeter<sup>5</sup>;
```
Now we have $b = Ax$, where $x = energy$. Solve for x using LeastSquares

```
x = Flatten [LeastSquares [Map [List, A], Map [List, b]]];
energyInJoules = x;
energyInKTon = energyInJoules / (4.186 * 10<sup>12</sup>)
```
 ${16.6175}$

Now plot the original data

pts = Table[{timePtsInMs[i]], rPtsInMeter[i]]}, {i, 1, Length[tin]

Display data in table format

Grid[{Join[{"t"}, timePtsInMs], Join[{"r"}, rPtsInMeter] }, Fr $(\texttt{*TableForm}{\small [pts, TableDirections \rightarrow Column, TableHeadings \rightarrow {None,}$

 \pm 0.1 0.52 1.08 1.5 1.93 4.07 1.5 34.

pts = Table $[\{A[[i]], b[[i]]\}, \{i, 1, Length[timePtsInMs]\}]\}$ p1 = ListPlot[pts, PlotStyle → PointSize[.015], PlotRange → All $p2 = Plot[energyInJoules*t, {t, 0, Last[A] }];$ Show $[$ {p1, p2}, PlotRange \rightarrow All, $PlotLabel \rightarrow "Fitting data using least squares, Energy=16.617$ **AxesLabel** → $\{ "0.8 t²", "r⁵" \}]$

2 Problem 2 (section 1.1, #11, page 18)

problem:

The problem is to determine the power P ship of length l moving at a constant speed reasonable, that P depends on the density to gravity g, and the viscosity of water ν well as l and V , then show that

$$
\frac{P}{\rho l^2 V^3} = f(\text{Fr},
$$

where Fr is the Froude number and Re is t

$$
\mathbf{F} \equiv \frac{V}{\sqrt{lg}}, \quad \text{Re}
$$

solution:

First make a list of all the physical variables and the corresponding dimensions.

Hence we seek a physical law of the form

$$
f(P, l, V, \rho, v, g) = 0
$$

The function f is a combination of all the physical variables. Hence we write

$$
1 = [\pi] = [P^a l^b V^c \rho^d v^e g^f]
$$

= $\left(\frac{ML^2}{T^3}\right)^a (L)^b \left(\frac{L}{T}\right)^c \left(\frac{M}{L^3}\right)^d \left(\frac{L^2}{T}\right)^e \left(\frac{L}{T^2}\right)^f$
= $(M^a L^{2a} T^{-3a}) (L^b) (L^c T^{-c}) (M^d L^{-3d}) (L^{2e} T^{-e}) (L^f T^{-2f})$
= $(M^{a+d}) (L^{2a+b+c-3d+2e+f}) (T^{-3a-c-e-2f})$

For the above combination to be dimensionless, we must have each exponent term equal to zero. Hence we obtain the following 3 equations

$$
a+d = 0
$$

2a+b+c-3d+2e+f=0
-3a-c-e-2f=0

Writing the above in matrix form

$$
\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \ 2 & 1 & 1 & -3 & 2 & 1 \ -3 & 0 & -1 & 0 & -1 & -2 \ \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ e \\ f \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}
$$

We see that the dimension matrix 3×6 , hence its row space has dimension 6 and its column space has dimension 3. We need now to find the basis for the Null Space of the dimension matrix. Now reduce *A* to its reduce row echelon form \mathbf{r} $\overline{1}$ \mathbf{r}

$$
\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \ 2 & 1 & 1 & -3 & 2 & 1 \ -3 & 0 & -1 & 0 & -1 & -2 \ \end{bmatrix} \xrightarrow{l_{21}=2} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \ 0 & 1 & 1 & -5 & 2 & 1 \ -3 & 0 & -1 & 0 & -1 & -2 \ \end{bmatrix} \xrightarrow{l_{31}=-3} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \ 0 & 1 & 1 & -5 & 2 & 1 \ 0 & 0 & -1 & 3 & -1 & -2 \ \end{bmatrix}
$$

Now multiply last row by $-1 \rightarrow$ $\sqrt{ }$ 1 0 0 1 0 0 0 1 1 −5 2 1 0 0 1 −3 1 2 1 $\begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \\ \begin{array}{c} \end{array} \end{array} \end{array}$, and now subtract last row from second r 1 0 0 1 0 0 $\overline{1}$

row

$$
\rightarrow \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -2 & 1 & -1 \\ 0 & 0 & 1 & -3 & 1 & 2 \end{bmatrix}
$$
 and this is the final reduce row echelon form

we have rank=3 (the first 3 columns are Linearly independent). Therefor, we use the first 3 variables as the pivot variables, which are *a*,*b*, *c* and use as the free variables those which correspond to the last 3 columns, which are *d*, *e*, *f*

Now since

$$
\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \ 0 & 1 & 0 & -2 & 1 & -1 \ 0 & 0 & 1 & -3 & 1 & 2 \ \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ e \\ f \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ f \end{bmatrix}
$$

By back substitution, from the 3rd row we obtain $c-3d+e+2f=0$, or $c=3d-e-2f$ and from the second row we obtain $b-2d+e-f=0$, or $|b=-e+f+2d|$, and from the first row we obtain $a + d = 0$ or $a = -d$

Hence the solution now can be written in terms of the free variables as

$$
x_{null} = \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix} = \begin{bmatrix} -d \\ -e+f+2d \\ 3d-e-2f \\ d \\ e \\ e \\ f \end{bmatrix}
$$

= $-d \begin{bmatrix} 1 \\ -2 \\ -3 \\ -1 \\ -1 \\ 0 \end{bmatrix} - e \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \\ -1 \\ 0 \end{bmatrix} - f \begin{bmatrix} 0 \\ -1 \\ 2 \\ 0 \\ 0 \\ -1 \end{bmatrix}$

Therefor the basis for the null space of *A* are

$$
\left\{\begin{bmatrix}1\\1\\-2\\-3\\-1\\0\end{bmatrix}, \begin{bmatrix}0\\1\\1\\0\\-1\\0\end{bmatrix}, \begin{bmatrix}0\\-1\\2\\0\\0\\-1\end{bmatrix}\right\}
$$

Hence

$$
\pi_1 = P^1 l^{-2} V^{-3} \rho^{-1} v^0 g^0 = \frac{P}{l^2 V^3 \rho}
$$

$$
\pi_2 = P^0 l^1 V^1 \rho^0 v^{-1} g^0 = \frac{V l}{V}
$$

$$
\pi_3 = P^0 l^{-1} V^2 \rho^0 v^0 g^{-1} = \frac{V^2}{l g}
$$

Hence the complete set is

$$
\left\{\pi_1=\frac{P}{l^2V^3\rho}, \pi_2=\frac{Vl}{V}, \pi_3=\frac{V^2}{l\ g}\right\}
$$

Hence the general solution is $\pi = \pi_1^{\alpha} \pi_2^{\beta}$ $\frac{\beta}{2}\pi_3^{\gamma}$ 3

The Pi theorem says that there is a physical law expressed in terms of the dimensionless quantities called $F(\pi_1, \pi_2, \pi_3) = 0$ corresponding to the physical law $f(P, l, V, \rho, v, g) = 0$

Now, we need to solve for *P*, hence we write

$$
\pi_1 = g(\pi_2, \pi_3)
$$

$$
\frac{P}{l^2 V^3 \rho} = g\left(\frac{Vl}{V}, \frac{V^2}{l g}\right)
$$

Hence if we let $g\left(\frac{Vl}{V}\right)$ $\left(\frac{Vl}{V},\frac{V^2}{l\ g}\right) = \pi_2\times\sqrt{2}$ $\overline{\pi_3}$, then we see that

$$
\frac{P}{l^2V^3\rho}=g(F_r,R_e)
$$

where

$$
F_r = \frac{VI}{V}, R_e = \frac{V}{\sqrt{I \ g}}
$$

Let k be some constant, then the power needed is given by

$$
P = kl^2V^3 \rho \frac{Vl}{v} \frac{V}{\sqrt{lg}}
$$

$$
= k \frac{l^3V^5 \rho}{v\sqrt{lg}}
$$