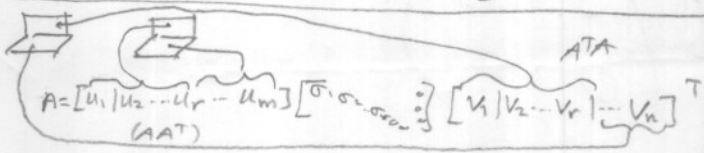


SVD:  $A=U\Sigma V^T$ ,  $A(m \times n) = U \begin{matrix} m \times m \\ m \times n \\ n \times n \end{matrix} \Sigma V^T$ . Test it,  $U \in AA^T$ ,  $V \in A^T A$ . Calculate  $AA^T$  and  $A^T A$ . Find which is smaller. find  $\sigma_1, \sigma_2$ . find  $\bar{u}_1, \bar{u}_2$ . then use  $AA^T \bar{u}_j = \sigma_j^2 \bar{u}_j$  so  $A^T AA^T \bar{u}_j = \sigma_j^2 A^T \bar{u}_j \Rightarrow \frac{A^T \bar{u}_j}{\sigma_j} = \bar{v}_j$ , find  $\bar{v}_1, \bar{v}_2$ . for  $\bar{v}_3$  solve  $(A^T A)x = 0$ . this small.

**NASSEK**

if  $A^T A$  was smaller, then  $\bar{u}_j = \frac{A \bar{v}_j}{\sigma_j}$  i.e.  $A^T A \bar{v}_j = \sigma_j^2 \bar{v}_j \Rightarrow AA^T A \bar{v}_j = \sigma_j^2 A \bar{v}_j$   
 so  $\frac{A \bar{v}_j}{\sigma_j} = \bar{u}_j$ . example:  $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} = U \begin{matrix} 2 \times 2 \\ 2 \times 2 \\ 2 \times 3 \end{matrix} \Sigma V^T$ .  $U \in AA^T = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$ ,  $V \in A^T A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$

from  $U$ , find  $\sigma_1, \sigma_2$ , find  $\bar{u}_1, \bar{u}_2$ , the eigenvectors of  $AA^T$ . so now we have  $\bar{u}$ .  
 now  $\bar{v}_1 = \frac{A^T \bar{u}_1}{\sigma_1}$ ,  $\bar{v}_2 = \frac{A^T \bar{u}_2}{\sigma_2}$ . for  $\bar{v}_3$ :  $\begin{pmatrix} 1 & -1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ . so  $V = \begin{pmatrix} 1 & -1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$ . Remind Normed, all-eigen real!



Similarity:  $T_r = M^{-1} T_w M$  Basis of  $W$  inverse  $[\bar{w}_1 | \bar{w}_2 \dots]^{-1}$   
 $\Rightarrow T_r \bar{z}_r = M^{-1} T_w M \bar{z}_r$   
 takes vectors from  $r$  space to  $W$  basis  
 applies linear mapping to vectors in  $W$  basis  
 takes vectors in  $W$  basis back to  $r$  basis

Example:  $v_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ ,  $v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$   
 $T(v_1) = 1\bar{v}_1 + 0\bar{v}_2 = 1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 0 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$   
 $T(v_2) = 0 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

Now find new Transformation Matrix under new coordinates.

Now find  $M$ :

$\begin{pmatrix} 2 \\ 1 \end{pmatrix} = a\bar{w}_1 + b\bar{w}_2 = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} \Rightarrow \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ 1 \end{pmatrix} \Rightarrow \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -1/2 \\ 3/2 \end{pmatrix}$  i.e.  $M = \begin{pmatrix} 1/2 & -1/2 \\ 1/2 & 1/2 \end{pmatrix}$ . so  $M^{-1} = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \Rightarrow T_w = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

To diagonalize Matrix  $A = S \Lambda S^{-1}$   $A^k = S \Lambda^k S^{-1}$ . if  $\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \end{pmatrix} \Rightarrow \Lambda^k = \begin{pmatrix} \lambda_1^k & & \\ & \lambda_2^k & \\ & & \ddots \end{pmatrix}$ ;  $e^{At} = \begin{pmatrix} e^{\lambda_1 t} & & \\ & e^{\lambda_2 t} & \\ & & \ddots \end{pmatrix}$

$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$   $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$

Similarity  $A \xrightarrow{M^{-1} A M} B$

Inversivity Jordan:  $A = \begin{pmatrix} 2 & 0 \\ 4 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & 0 & | & 1 & 0 \\ 4 & 2 & | & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & 0 & | & 2 & 0 \\ 0 & 2 & | & -2 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & | & 1 & 0 \\ 0 & 1 & | & -1 & 1/2 \end{pmatrix}$

Matrix Property:  $A$  need  $P$  symmetric  $\Rightarrow \lambda$  real.  
 if  $A$  symm.  $\Rightarrow$  spectral decomposition:  $A = Q \Lambda Q^{-1}$   
 if  $A^T A = I \rightarrow A$  unitary.  
 if  $A$  is NORMAL  $\rightarrow$  diagonalizable. Normal  $AA^H = A^H A$

Row View  $\begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix} (c_1) \rightarrow \begin{pmatrix} r_1 c_1 \\ r_2 c_1 \\ r_3 c_1 \end{pmatrix} = \begin{pmatrix} r_1 A \\ r_2 A \\ r_3 A \end{pmatrix}$   
 Col View  $\begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} (c_1) \rightarrow \begin{pmatrix} c_1 | r_1 \\ c_2 | r_2 \\ c_3 | r_3 \end{pmatrix} = \begin{pmatrix} c_1 | r_1 A \\ c_2 | r_2 A \\ c_3 | r_3 A \end{pmatrix}$

Proof different  $\lambda$  and  $A$  symm  $\rightarrow \bar{x}$  are unique:  
 $(\lambda_1 x)^H y = (\lambda_2 x)^H y = x^H A^H y = x^H A y = x^H \lambda_2 y$   
 so  $\lambda_1 x^H y = \lambda_2 x^H y$ . but  $\lambda_1 \neq \lambda_2 \Rightarrow x^H y = 0$   
 i.e.  $\bar{x} \perp y$   
 $(A^{-1})^H A^H = I^H = I$   
 $(A^{-1})^H A^H = I \rightarrow (A^{-1})^H = A^H$   
 $|A^T| = |A|$

GE: Subtract from second row multiple of first row

Projections:  $\vec{b}$  projected onto line  $P$  defined by  $\vec{a}$ .  
 $\langle \vec{b}, \vec{a} \rangle = \|\vec{b}\| \|\vec{a}\| \cos \theta$   
 $\vec{p} = \frac{\langle \vec{b}, \vec{a} \rangle}{\|\vec{a}\|^2} \vec{a} = \frac{\vec{b}^T \vec{a}}{\vec{a}^T \vec{a}} \vec{a}$   
 $= \vec{a} \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}} = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}} \vec{b}$   
 $= [P] \vec{b}$   
 projection matrix line a line.

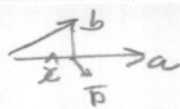
proof that  $A = A^H \rightarrow \lambda$  real:  $Ax = \lambda x \rightarrow x^H Ax = \lambda \|x\|^2$   
 $\rightarrow \lambda$  real since  $x^H Ax$  real  
 Gram schmidt:  $A = [v_1 | v_2 | v_3]$   
 $q_1 = \frac{v_1}{\|v_1\|}$   
 $q_2 = \frac{v_2 - \langle v_2, q_1 \rangle q_1}{\|v_2 - \langle v_2, q_1 \rangle q_1\|}$   
 $q_3 = \frac{v_3 - \langle v_3, q_1 \rangle q_1 - \langle v_3, q_2 \rangle q_2}{\|v_3 - \langle v_3, q_1 \rangle q_1 - \langle v_3, q_2 \rangle q_2\|}$   
 Schur:  $\langle \vec{a}, \vec{b} \rangle \leq \|\vec{a}\| \|\vec{b}\|$   
 Triangle  $\|x+y\| \leq \|x\| + \|y\|$   
 $A = LLT$ :  $A$  SPD  
 $A = QR$ :  $A$  indep. cols  
 if  $A$  square then  $Q^{-1} = Q^T$   
 $A = S \Lambda S^{-1}$ :  $A$  has n L.I.  
 $Q^T Q = I$   $A = Q \Lambda Q^T$ :  $A$  symm.  
 $A = M J M^{-1}$ :  $A$  square  
 $A = U \Sigma V^T$ :  $A$  any  $A^H / A = U U^H = I$ :  $A$  Normal

Invertibility of Matrix depends on Non zero  $\lambda$   
 diagonalizability depends on enough eigenvectors

$\vec{f}_{\text{eigen}} = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$   $\lambda_1 = \frac{1+\sqrt{5}}{2}$ ,  $A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$

Solution to  $U_{k+1} = A U_k$  is  $U_k = A^k U_0 \Rightarrow U_k = (C_1 \lambda_1^k \bar{x}_1 + C_2 \lambda_2^k \bar{x}_2 + \dots) U_0$   
 initial condition at  $k=0$ . Note  $\lambda < 1$  for stability

Sheet Nasser



$\langle b, a \rangle = \|b\| \|a\| \cos \theta$ .  $\bar{P} = \frac{b^T a}{a^T a} \bar{a}$ ,  $\bar{P} = \bar{a} \frac{a^T b}{a^T a} = [P] \bar{b}$

$\frac{a a^T}{a^T a}$  projects onto line.

Projection Matrix for line or plane is  $\underbrace{A(A^T A)^{-1} A^T}_{[P]}$  s.  $[P] \bar{b} = \bar{P}$

if  $Q$  other projection  $[P]$  is simplified,  $Q(Q^T Q)^{-1} Q^T \Rightarrow Q Q^T$   
 so  $[P] = Q Q^T$  where  $Q = [q_1 | q_2 | \dots]$

if basis are orthonormal, then Projection of Vector on Plane = Sum of Projection of Vector on each Basis.

Note  $Q^T Q = I$ . Least squares: minimum  $\|E\|^2 = \|Ax - b\|^2 \Rightarrow (ax_1 - b_1)^2 + (ax_2 - b_2)^2 + \dots$

or using matrix, L.S. is  $\hat{x} = (A^T A)^{-1} A^T b$ . error  $\bar{P} + \bar{e} = \bar{b} \Rightarrow \bar{e} = \bar{b} - \bar{P}$

Schwarz inequality:  $\langle a, b \rangle \leq \|a\| \|b\|$  or  $a^T b \leq \|a\| \|b\|$   
 Triangle Inequality:  $\|x+y\| \leq \|x\| + \|y\|$ ,  $\langle v, v \rangle = \|v\|^2$   
 $\bar{e} \perp \bar{P}$

$(x+y)^T (x+y) = x^T x + y^T y + 2x^T y$  Q-S: given  $A = [a_1 | a_2 | \dots]$ , let  $\bar{q}_i = \bar{a}_i$

Then  $\bar{q}_2 = \bar{a}_2 - \left( \frac{\bar{a}_2^T \bar{q}_1}{\bar{q}_1^T \bar{q}_1} \bar{q}_1 \right)$ ;  $\bar{q}_3 = \bar{a}_3 - \left( \frac{\bar{a}_3^T \bar{q}_1}{\bar{q}_1^T \bar{q}_1} \bar{q}_1 + \frac{\bar{a}_3^T \bar{q}_2}{\bar{q}_2^T \bar{q}_2} \bar{q}_2 \right)$  etc...  
 Then Normalize  $\bar{q}_i$ .  $A = QR \Rightarrow R = Q^T A$ .

Prop of det: ①  $\det I = 1$ , ② row exchange: sign change, ③ Linear on first Row.

i.e  $\begin{vmatrix} a+1 & b+1 \\ c & d \end{vmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} + \begin{vmatrix} 1 & 1 \\ c & d \end{vmatrix}$ ;  $\begin{vmatrix} 3a & 3b \\ c & d \end{vmatrix} = 3 \begin{vmatrix} a & b \\ c & d \end{vmatrix}$

if  $A$  diagonal or triangular,  $|A| =$  Product of diagonal elements. to prove, use property ③ repeatedly.

$\det(2A) = 2^n \det(A)$ .  $PA = LDU$ .  $\det P = \pm 1$ .

$Qx = b$   
 $Q^T Q \hat{x} = Q^T b$   
 $\hat{x} = (Q^T Q)^{-1} Q^T b = Q^T b$   
 $\bar{P} = Q \hat{x}$   
 $[P] = Q Q^T b$

if  $\bar{b} \perp$  to each column of  $V$ , then  $\bar{b} \perp$  span  $V$ .  
 if every  $\bar{v} \in W \perp$  every  $\bar{u} \in U$ ,  $\Rightarrow W$  is orthogonal complement of  $U$ .  
 Row space  $\perp$  Null space: proof:  $\bar{x} \in N(A)$ ,  $Ax = 0$ .  
 $Ax = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \bar{x} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow$  each Row of  $A \perp \bar{x}$  since dot product = 0.  
 so every vector in Row space is  $\perp$  every vector in  $N(A)$ .

similarly,  $y^T A = 0$  i.e.  $[y_1, y_2, \dots] \begin{bmatrix} 0 & 0 & \dots & 0 \end{bmatrix} = [0 \ 0 \ 0 \ \dots] \Rightarrow$  every  $y$  is  $\perp$  every column of  $A$ .  
 so every vector in Left Null is  $\perp$   $C(A)$ .

to find transformation matrix, apply  $T$  to each Basis. Then  $A =$  columns just found.

Proof that different  $\lambda$ , and  $A$  symm  $\Rightarrow$  eigenvectors are unig:  $(\lambda_1, x)^T y = (Ax)^T y = x^T A^T y = x^T A y = x^T \lambda_2 y$ .  
 so  $\lambda_1 x^T y = \lambda_2 x^T y$ , but  $\lambda_1 \neq \lambda_2 \Rightarrow x^T y = 0$  i.e.  $\bar{x} \perp \bar{y}$ .

Proof that if  $A=A^T \rightarrow x^T A x$  must be real:  $(x^T A x)^T = x^T A^T x = x^T A x$  i.e.  $\bar{z} = z \Rightarrow z$  is real. i.e.  $x^T A x$  is real.

Proof that if  $A=A^T \rightarrow \lambda$  are real:  $Ax = \lambda x \rightarrow x^T A x = \lambda \|x\|^2$ . but  $x^T A x$  is real,  $\rightarrow \lambda$  is real

Prop: A real symmetric Matrix can be factored into  $A = Q \Lambda Q^T$ .  $Q$  is matrix of orthonormal eigenvectors

$A = \lambda_1 \bar{x}_1 \bar{x}_1^T + \lambda_2 \bar{x}_2 \bar{x}_2^T + \dots + \lambda_n \bar{x}_n \bar{x}_n^T$   
 Spectral theorem: Matrix is uniquely determined by its  $\lambda_i$  and  $\bar{v}_i$ .

eigenvalues of  $Q$ , matrix of orthonormal eigenvectors is  $|\lambda| = 1$   
 $A = S \Lambda S^{-1}$

Proof inverse of Hermitian is Hermitian:  $A = A^H$ .  
 $AA^{-1} = I \rightarrow (AA^{-1})^H = I^H \rightarrow (A^{-1})^H A^H = I^H \rightarrow (A^{-1})^H A = I \rightarrow (A^{-1})^H = A^{-1}$   
 $\rightarrow A^{-1}$  is Hermitian

determinant properties:  $|A^T| = |A|$

invertibility of Matrix depends on non zero eigenvalues  
 but diagonalizability depends on eigenvectors (indep).

Solution to difference equation  $u_{k+1} = Au_k$  is  $u_k = A^k u_0 \rightarrow$  solution  $u_k = c_1 \lambda_1^k \bar{x}_1 + c_2 \lambda_2^k \bar{x}_2 + \dots$

Fibonacci equation  $F_{k+2} = F_{k+1} + F_k$ .  
 To find  $F_{1000}$  do  $\frac{1}{\sqrt{5}} \lambda_1^{1000}$  where  $\lambda_1$  is the bigger of  $\lambda_i$ .

in  $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$   
 $\lambda_1 = \frac{1+\sqrt{5}}{2}$ . so  $F_{1000} = \frac{1}{\sqrt{5}} \left(\frac{1+\sqrt{5}}{2}\right)^{1000}$ , then round down.

For stability of difference equations,  $\lambda_i < 1$ .  $\lambda = 1$  neutral.  
 for stable diff. eqns, stable if  $\lambda < 0$ .

projections: vector on vector  $\bar{b}$  on  $\bar{a} \Rightarrow \frac{\langle \bar{b}, \bar{a} \rangle}{\langle \bar{a}, \bar{a} \rangle} \bar{a}$

vectors on plane: if vectors span plane,  $a_1, a_2$ , and we are asked to find projection of  $\bar{b}$  on plane, then find projection of  $\bar{b}$  onto  $a_1$ , and onto  $a_2$ , and add.

OR make  $Q$  matrix from  $a_1, a_2$  and write  $\bar{P} = QQ^T \bar{b}$

Least square  $Ax = b \Rightarrow A^T A x = A^T b \Rightarrow x = (A^T A)^{-1} A^T b$

Gram schmid.  $\bar{v}_1, \bar{v}_2, \bar{v}_3 \rightarrow A = \begin{bmatrix} | & | & | \\ v_1 & v_2 & v_3 \\ | & | & | \end{bmatrix}$   
 $\bar{q}_1 = \bar{v}_1$   
 $\bar{q}_2 = \bar{v}_2 - \left( \frac{\langle \bar{v}_2, \bar{q}_1 \rangle}{\|\bar{q}_1\|^2} \bar{q}_1 \right)$

$\bar{q}_3 = \bar{v}_3 - \left( \frac{\langle \bar{v}_3, \bar{q}_1 \rangle}{\|\bar{q}_1\|^2} \bar{q}_1 + \frac{\langle \bar{v}_3, \bar{q}_2 \rangle}{\|\bar{q}_2\|^2} \bar{q}_2 \right)$   
 $A = LU$ .  
 Note  $R(A) = R(U)$   
 $N(A) = N(U)$

Now normalize all  $q$ 's.  
 Linear independence:  $c_1 \bar{v}_1 + c_2 \bar{v}_2 + \dots = \bar{0} \Rightarrow$  all  $c$ 's = 0

Given  $\frac{du}{dt} = Au$ , the general sol.  
 $\bar{u} = c_1 \bar{v}_1 e^{\lambda_1 t} + c_2 \bar{v}_2 e^{\lambda_2 t}$   
 where  $c_1, c_2$  are B.C.  
 Particular solns are  $\left\{ \begin{matrix} c_1 e^{\lambda_1 t} \\ c_2 e^{\lambda_2 t} \end{matrix} \right\}$

$A = R^T R$   
 if  $A$  is any symmetric

$Q^T Q = I$  but Not  $Q^T Q$ !

$AB$ : row indep  $\Rightarrow$  ( ) ( )

if we know  $Q$ , the projection matrix  $[P] = QQ^T$

Idential conditions at  $k=0$   
 $\hat{x} = (A^T A)^{-1} A^T \bar{b}$   
 so projection of  $\hat{x}$  onto  $C(A)$  is nearest point to  $A \hat{x}$

$A \hat{x} = A (A^T A)^{-1} A^T \bar{b}$   
 so  $[P]$  projection matrix.

$P^2 = P$   
 $P^T = P$   
 any symm matrix with  $P^2 = P$  is projective

$\bar{b} = \bar{P} + \bar{e}$   
 $\bar{P} + \bar{e} = \bar{b} \Rightarrow \bar{e} = \bar{b} - \bar{P}$

Schwarz inequality:  $\langle a, b \rangle \leq \|a\| \|b\|$   
 Triangle inequality:  $\|x+y\| \leq \|x\| + \|y\|$

Prop of det: ① det  $\neq 0$ , ② row exchange = sign chge.

③ Line on first row.  
 $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} + \begin{vmatrix} 1 & 1 \\ c & d \end{vmatrix} = \begin{vmatrix} 3a & 3b \\ c & d \end{vmatrix} = 3 \begin{vmatrix} a & b \\ c & d \end{vmatrix}$

$\det(2A) = 2^n \det(A)$  when  $A = n \times n$ .  
 For Linear Transform  $T(av) = aT(v)$   
 $T(v+x) = T(v) + T(x)$

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