

Solution key HW #8

Section 3.4: # 1, 2, 8, 13, 16, 18

Section 4.2: # 1, 7, 14

Section 4.3: # 3, In class problems.

Section 3.4

#1 Solution in book.

#2.  $\vec{b} = (0, 3, 0)$      $\vec{a}_1 = (\frac{2}{3}, \frac{2}{3}, -\frac{1}{3})$      $\vec{a}_2 = (-\frac{1}{3}, \frac{2}{3}, \frac{2}{3})$

Since  $\vec{a}_1$  and  $\vec{a}_2$  are orthonormal, then the projection onto the plane spanned by  $\vec{a}_1$  and  $\vec{a}_2$  is the sum of the projection to each individual vector.

$\vec{b}^T \vec{a}_1 \cdot \vec{a}_1 = 2 \vec{a}_1 = \begin{bmatrix} 4/3 \\ 4/3 \\ -2/3 \end{bmatrix}$     Projection of  $\vec{b}$  onto  $\vec{a}_1$ .

$\vec{b}^T \vec{a}_2 \cdot \vec{a}_2 = 2 \vec{a}_2 = \begin{bmatrix} -2/3 \\ 4/3 \\ 4/3 \end{bmatrix}$     Projection of  $\vec{b}$  onto  $\vec{a}_2$ .

Projection onto plane =  $\begin{bmatrix} 4/3 \\ 4/3 \\ -2/3 \end{bmatrix} + \begin{bmatrix} -2/3 \\ 4/3 \\ 4/3 \end{bmatrix} = \begin{bmatrix} 2/3 \\ 8/3 \\ 2/3 \end{bmatrix}$ .

We check by computing the projection onto the plane as the projection onto the column space of  $Q$

$Q = \begin{bmatrix} 2/3 & -1/3 \\ 2/3 & 2/3 \\ -1/3 & 2/3 \end{bmatrix}$

Since  $Q$  is orthogonal, the projection

is  $p = QQ^T \vec{b}$

$= \begin{bmatrix} 2/3 & -1/3 \\ 2/3 & 2/3 \\ -1/3 & 2/3 \end{bmatrix} \begin{bmatrix} 2/3 & 2/3 & -1/3 \\ -1/3 & 2/3 & 2/3 \end{bmatrix} \begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix}$

$= \begin{bmatrix} 2/3 & -1/3 \\ 2/3 & 2/3 \\ -1/3 & 2/3 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2/3 \\ 8/3 \\ 2/3 \end{bmatrix} \quad \checkmark$

#8  $\vec{b}$  projected onto  $\vec{a}_1 = \frac{\vec{b}^T \vec{a}_1}{\|\vec{a}_1\|^2} \vec{a}_1 = \frac{1}{1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

(2)

$\vec{b}$  projected onto  $\vec{a}_2 = \frac{3}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3/2 \\ 3/2 \end{bmatrix}$   
 $\vec{a}_2 = (1, 1)$

see that  $\begin{bmatrix} 3/2 \\ 3/2 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 5/2 \\ 3/2 \end{bmatrix} \neq \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

#13

$\vec{v}_1 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{1} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

I usually don't normalize until the end but in this case they are already normalized.

$A = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad Q = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad A = QR$

We find  $R$  in two ways. First slow + fundamental. one column of  $A$  at a time.

$\vec{a}_1 = 1 \vec{v}_1$   
 $\vec{a}_2 = 1 \vec{v}_1 + 1 \vec{v}_2 \Rightarrow R = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$   
 $\vec{a}_3 = 1 \vec{v}_1 + 1 \vec{v}_2 + 1 \vec{v}_3$

or we could do the computational way  $R = Q^T A$

$Q^T = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad Q^T A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = R$

#16

③

$$\begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 1/3 & 0 \\ 2/3 & 1/\sqrt{2} \\ 2/3 & 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 3 & 3 \\ 0 & \sqrt{2} \end{bmatrix}$$

A

Q

R

using same procedure as in #13 &amp; note.

If we have  $n$  vectors with  $m$  components  $A_{m \times n} = Q_{m \times n} R_{n \times n}$

note that  $(Q^T)_{n \times m} A_{m \times n} = R_{n \times n}$  as it should be.

#18

Q has the same column space as A, so

$$P = Q(Q^T Q)^{-1} Q^T = Q Q^T.$$

or you could have used  $A = QR$

$$\begin{aligned} P &= (QR) ((QR)^T (QR))^{-1} (QR)^T \\ &= (QR) (R^T Q^T Q R)^{-1} R^T Q^T \\ &= (QR) (R^T R)^{-1} R^T Q^T \\ &= Q R R^{-1} (R^T)^{-1} R^T Q^T \\ &= Q Q^T \end{aligned}$$

## Section 4.2

4

#1, #7 solutions in the book.

#14

a) False;  $\det \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \neq 2 \det \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$  Linearity holds for the entire first row, not just one element

b) False;  $\det \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} = -1$  with pivots  $\begin{matrix} 1 & 1 \\ 1 & 1 \end{matrix}$  [Row exchanges make this statement not true.]

c) False;  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$   
 invertible      singular      singular

d) True;  $\det(AB) = \det A \cdot \det B = \det A \cdot 0 = 0$

e) False;  $\det(AB - BA) \neq \det(AB) - \det(BA)$

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \quad AB = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \quad BA = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

$$AB - BA = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\det(AB - BA) = -1!$$

And the assigned problems.

$$A = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} \quad \det(A) = 5 \cdot 2 - 3 \cdot 4 = -2$$

$$B = \begin{bmatrix} 1 & 2 & 3 \\ 5 & 6 & 7 \\ 4 & 8 & 12 \end{bmatrix} \quad \det(B) = 1 \begin{vmatrix} 6 & 7 \\ 8 & 12 \end{vmatrix} - 2 \begin{vmatrix} 5 & 7 \\ 4 & 12 \end{vmatrix} + 3 \begin{vmatrix} 5 & 6 \\ 4 & 8 \end{vmatrix}$$

$$= 16 - 64 + 48 = 0$$

Note that I used the cofactor expansion method but you can use other methods if you like.

$$C = \begin{bmatrix} 2-\lambda & 3 \\ 4 & 5-\lambda \end{bmatrix} \quad \det(C) = (\lambda-2)(5-\lambda) - 12$$

$$= \lambda^2 - 7\lambda - 2$$

$$D = \begin{bmatrix} 1-\lambda & 2 & 3 \\ 5 & 6-\lambda & 7 \\ 4 & 8 & 12-\lambda \end{bmatrix} \quad \det(D) = (1-\lambda) \begin{vmatrix} 6-\lambda & 7 \\ 8 & 12-\lambda \end{vmatrix} - 2 \begin{vmatrix} 5 & 7 \\ 4 & 12-\lambda \end{vmatrix} + 3 \begin{vmatrix} 5 & 6-\lambda \\ 4 & 8 \end{vmatrix}$$

$$= -\lambda^3 + 19\lambda^2 - 12\lambda$$