

HW # 7
Math 307
Linear Algebra, Spring 2007
CSUE

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Section 3.2 # 1, 3, 12, 18

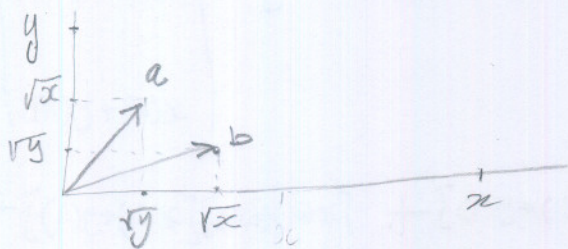
Section 3.3 # 1, 2, 3, 4, 8, 14

Section 3.2 # 1

1 (a) given any 2 positive numbers x, y , choose the vector b equal to (\sqrt{x}, \sqrt{y}) , and choose $a = (\sqrt{y}, \sqrt{x})$. Apply Schwarz inequality to compare the arithmetic mean $\frac{1}{2}(x+y)$ with the geometric mean \sqrt{xy}

(b) suppose we start with a vector from the origin to the point x and then add a vector of length $\|y\|$ connecting x to $x+y$. the third side of the triangle goes from the origin to $x+y$. the triangle inequality asserts that this distance cannot be greater than the sum of the first two $\|x+y\| \leq \|x\| + \|y\|$. reduce this to Schwarz inequality

Answer (a)



$$|\vec{a} \cdot \vec{b}| \leq \|a\| \|b\| \quad \text{Schwarz inequality.}$$

$$\text{i.e. } |(\sqrt{y}, \sqrt{x}) \cdot (\sqrt{x}, \sqrt{y})| \leq (\sqrt{(\sqrt{y})^2 + (\sqrt{x})^2}) (\sqrt{(\sqrt{x})^2 + (\sqrt{y})^2})$$

$$\text{i.e. } |\sqrt{yx} + \sqrt{xy}| \leq \sqrt{y+x} \sqrt{x+y}$$

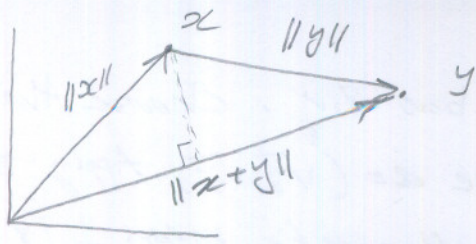
$$\text{i.e. } 2\sqrt{yx} \leq y+x$$

$$\text{i.e. } \boxed{\sqrt{yx} \leq \frac{1}{2}(y+x)}$$

→ back.



b)



$$\|x+y\| \leq \|x\| + \|y\|$$

Square both sides:

$$\|x+y\|^2 \leq (\|x\| + \|y\|)^2 = \|x\|^2 + \|y\|^2 + 2\|x\|\|y\|. \quad \text{--- (1)}$$

but $\|x+y\|^2 = |(x+y)^T(x+y)|$

but $|(x+y)^T(x+y)| = \{x^{(1)}+y^{(1)}, x^{(2)}+y^{(2)}, \dots, x^{(n)}+y^{(n)}\}^T \begin{Bmatrix} x^{(1)}+y^{(1)} \\ x^{(2)}+y^{(2)} \\ \vdots \\ x^{(n)}+y^{(n)} \end{Bmatrix}$

$$= [x^{(1)}+y^{(1)}][x^{(1)}+y^{(1)}] + [x^{(2)}+y^{(2)}][x^{(2)}+y^{(2)}] + \dots + [x^{(n)}+y^{(n)}][x^{(n)}+y^{(n)}]$$

$$= x^{(1)2} + 2x^{(1)}y^{(1)} + y^{(1)2} + x^{(2)2} + 2x^{(2)}y^{(2)} + y^{(2)2} + \dots + x^{(n)2} + 2x^{(n)}y^{(n)} + y^{(n)2}$$

$$= [x^{(1)2} + x^{(2)2} + \dots + x^{(n)2}] + [y^{(1)2} + y^{(2)2} + \dots + y^{(n)2}] + 2[x^{(1)}y^{(1)} + \dots + x^{(n)}y^{(n)}]$$

so

$$\|x+y\|^2 = \|x\|^2 + \|y\|^2 + 2x^T y \quad \text{Sub this in LHS of (1)}$$

we obtain:

$$\|x\|^2 + \|y\|^2 + 2x^T y \leq \|x\|^2 + \|y\|^2 + 2\|x\|\|y\|$$

$$2x^T y \leq 2\|x\|\|y\|$$

$$x^T y \leq \|x\|\|y\|$$

QED

Section 3.2 # 3

what multiple of $a = (1, 1, 1)$ is closest to point $b = (2, 4, 4)$?
 Find also the closest point to a on a line through b .

Answer

assume we have this geometry:



The point is closest to \bar{b} along direction of \bar{a} .

so closest point along the direction of a is the point when projection of b onto a is 90° .

but $\bar{b} \cdot \bar{a} = \|b\| \|a\| \cos \theta$

so $\boxed{\|b\| \cos \theta = \frac{\bar{b} \cdot \bar{a}}{\|a\|}}$

so to find multiples of \bar{a} , we write

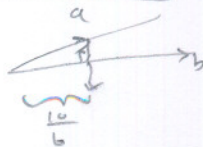
$$\begin{aligned} \text{multiples of } a &= \frac{\|b\| \cos \theta}{\|a\|} = \frac{\bar{b} \cdot \bar{a}}{\|a\|^2} = \frac{[2, 4, 4] \cdot [1, 1, 1]}{(\sqrt{1^2+1^2+1^2})^2} = \frac{2+4+4}{3} \\ &= \frac{10}{3} = 3 \frac{1}{3} \end{aligned}$$

so $\boxed{3 \frac{1}{3}}$ multiples of $\|a\|$ will get to closest point to b

i.e. the point along direction of a closest to b is $\boxed{(3 \frac{1}{3}, 3 \frac{1}{3}, 3 \frac{1}{3})}$

Now, to find point closest to \bar{a} onto \bar{b} :

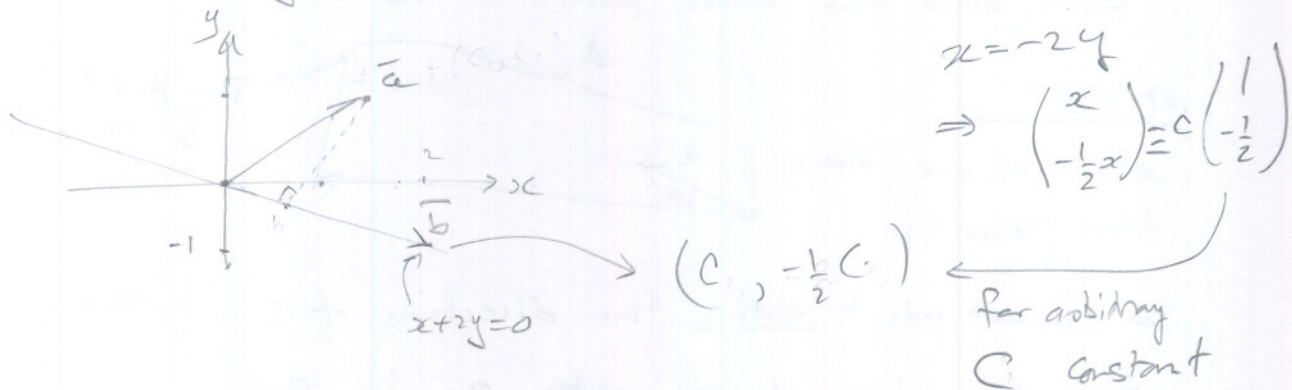
$$\|a\| \cos \theta = \frac{\bar{b} \cdot \bar{a}}{\|b\|} = \frac{10}{\sqrt{2^2+4^2+4^2}} = \frac{10}{\sqrt{36}} = \frac{10}{6}$$



so point along b is $\left(\frac{\bar{b}}{\|b\|} \right) (\|a\| \cos \theta) = \frac{\bar{b}}{\|b\|} \left(\frac{\bar{b} \cdot \bar{a}}{\|b\|} \right) = \frac{(2, 4, 4)}{\sqrt{36}} \left(\frac{10}{6} \right) = \left(\frac{1}{3}, \frac{2}{3}, \frac{2}{3} \right) \left(\frac{5}{3} \right) = \boxed{\left(\frac{5}{9}, \frac{10}{9}, \frac{10}{9} \right)}$

section 3.2 # 12

Find the matrix that projects every point in the plane onto the line $x+2y=0$



Then $\bar{b} \cdot \bar{a} = \|\bar{a}\| \|\bar{b}\| \cos \theta$

so $\frac{\bar{b} \cdot \bar{a}}{\|\bar{b}\|} = \|\bar{a}\| \cos \theta$

so The projection of \bar{a} onto the line $x+2y=0$ is

$$\frac{\bar{b} \cdot \bar{a}}{\|\bar{b}\|} \frac{\bar{b}}{\|\bar{b}\|} = \frac{\bar{b}^T \bar{a}}{\|\bar{b}\|^2} \bar{b} = \underbrace{\bar{b} \frac{\bar{b}^T \bar{a}}{\|\bar{b}\|^2}}_{\Rightarrow} \underbrace{\frac{\bar{b} \bar{b}^T}{\|\bar{b}\|^2}}_{\text{Projection Matrix}}$$

so Projection Matrix $P = \frac{\begin{pmatrix} C \\ -\frac{C}{2} \end{pmatrix} \begin{pmatrix} C & -\frac{C}{2} \end{pmatrix}}{C^2 + \frac{1}{4}C^2} = \begin{bmatrix} C^2 & -\frac{C^2}{2} \\ -\frac{C^2}{2} & \frac{C^2}{4} \end{bmatrix} \frac{1}{C^2(1+\frac{1}{4})}$

$$P = \frac{4}{5} \frac{1}{C^2} \begin{bmatrix} C^2 & -\frac{C^2}{2} \\ -\frac{C^2}{2} & \frac{C^2}{4} \end{bmatrix} = \frac{4}{5} \begin{bmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{4} \end{bmatrix}$$

$$\begin{bmatrix} \frac{4}{5} & -\frac{2}{5} \\ -\frac{2}{5} & \frac{1}{5} \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 4 & -2 \\ -2 & 1 \end{bmatrix}$$

Note: symmetric and $P^2 = P$

Section 3.2 # 18

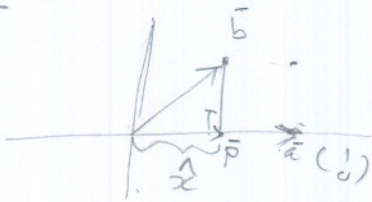
Draw the projection of b onto a and also compute it from $\bar{p} = \hat{x} a$

(a) $b = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$ and $a = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

(b) $b = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $a = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$.

Solution

(a)



$$\bar{b} \cdot \bar{a} = \|\bar{b}\| \|\bar{a}\| \cos \theta$$

$$\|\bar{b}\| \cos \theta = \frac{\bar{b} \cdot \bar{a}}{\|\bar{a}\|}$$

unit vector along \bar{a} is $\frac{\bar{a}}{\|\bar{a}\|}$

hence $\bar{p} = (\|\bar{b}\| \cos \theta) \frac{\bar{a}}{\|\bar{a}\|} = \frac{\bar{b} \cdot \bar{a}}{\|\bar{a}\|^2} \bar{a} = \frac{\bar{b}^T \bar{a}}{\|\bar{a}\|^2} \bar{a}$

$$= \hat{x} \bar{a} = \frac{\begin{bmatrix} \cos \theta & \sin \theta \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}}{\sqrt{1^2 + 0^2}} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

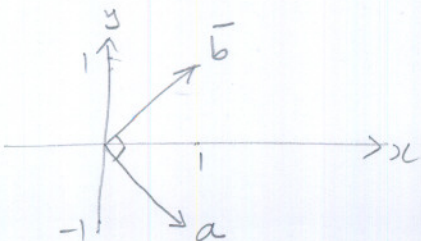
$$= \frac{\cos \theta}{1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \boxed{\begin{bmatrix} \cos \theta \\ 0 \end{bmatrix}}$$

(b) $\bar{p} = \hat{x} a$

$$= \frac{\begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}}{\sqrt{1^2 + 1^2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{0}{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \boxed{\begin{bmatrix} 0 \\ 0 \end{bmatrix}}$$

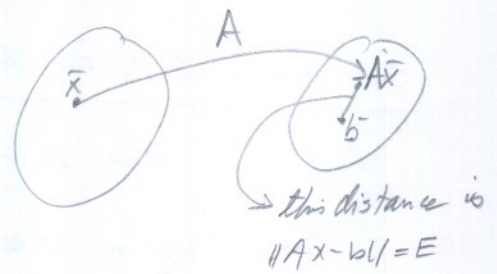
← this is because \bar{b} is orthogonal to \bar{a}

so projection of \bar{b} onto \bar{a} is $\bar{0}$.



section 3.3 #1

Find best least square solution \hat{x} to $3x=10, 4x=5$. what error E^2 is minimized.



Solution

$$A \bar{x} = \bar{b}$$

$$\left. \begin{array}{l} 3x=10 \\ 4x=5 \end{array} \right\} \Rightarrow \begin{bmatrix} 3 \\ 4 \end{bmatrix} x = \begin{bmatrix} 10 \\ 5 \end{bmatrix}$$

$$A \hat{x} = b$$

$$A^T A \hat{x} = A^T b$$

$$\hat{x} = (A^T A)^{-1} A^T b$$

$$= \left(\begin{bmatrix} 3 & 4 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right)^{-1} \begin{bmatrix} 3 & 4 \end{bmatrix} \begin{bmatrix} 10 \\ 5 \end{bmatrix} = \begin{bmatrix} 25 \end{bmatrix}^{-1} (30+20) = \frac{1}{25} 50 = \boxed{2}$$

$$\text{so } \boxed{\hat{x} = 2}$$

error being minimized is $E = \|Ax - b\| = \left\| \begin{bmatrix} 3 \\ 4 \end{bmatrix} x - \begin{bmatrix} 10 \\ 5 \end{bmatrix} \right\|$

$$= \left\| \begin{bmatrix} 3x \\ 4x \end{bmatrix} - \begin{bmatrix} 10 \\ 5 \end{bmatrix} \right\| = \left\| \begin{bmatrix} 3x-10 \\ 4x-5 \end{bmatrix} \right\| = \sqrt{(3x-10)^2 + (4x-5)^2}$$

$$\text{so } \boxed{E^2 = (3x-10)^2 + (4x-5)^2}$$

we minimize E^2 above.

to check that error vector $\begin{pmatrix} 10-3\hat{x} \\ 5-4\hat{x} \end{pmatrix}$ is \perp to $\begin{pmatrix} 3 \\ 4 \end{pmatrix}$, we take dot product and see if zero.

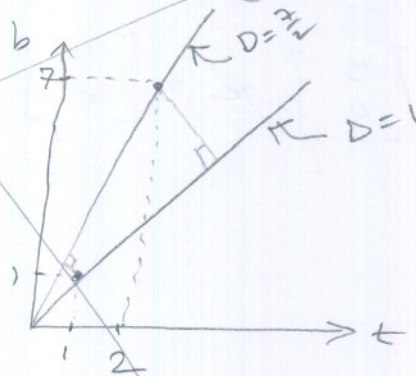
$$\begin{pmatrix} 10-3(2) \\ 5-4(2) \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 10-6 \\ 5-8 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 4 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

$$= (4)(3) + (-3)(4) = 0 \quad \boxed{\text{yes}}$$

Section 3.3 # 2

Suppose the values $b_1=1, b_2=7$ at times $t_1=1, t_2=2$ are fitted by a line $b=Dt$ through the origin. solve $D=1$, and $2D=7$ by least squares. and sketch the best line.

Answer



oops!
Please ignore →

in first case, $D=1$

Find $|E|^2$ and minimize. let E_1 be error from $(1,1)$ to line $D=1$, and let E_2 be error from $(2,7)$ to line $D=2$.

From diagram on right, in this case, we have

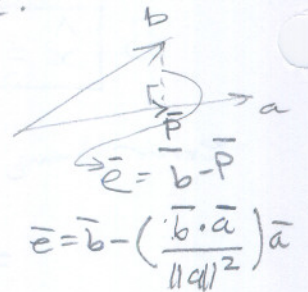
$$\bar{b} = (1,1)$$

$$\bar{a} = (1,1)$$

$$\text{so } \bar{e}_1 = (1,1) - \left(\frac{(1,1)(1,1)}{\|(1,1)\|^2} \right) (1,1)$$

$$= (1,1) - \left(\frac{2}{2} \right) (1,1) = 0$$

$$\text{so } |E_1| = 0.$$



for \bar{e}_2 , this is error between point $(2,7)$ to line $D=1$ here, $\bar{b} = (2,7), \bar{a} = (1,1)$.

$$\text{so } \bar{e}_2 = (2,7) - \left(\frac{(2,7)(1,1)}{2} \right) (1,1) = (2,7) - \left(\frac{9}{2} \right) (1,1)$$

$$= (2,7) - \left(\frac{9}{2}, \frac{9}{2} \right) = \left(2 - \frac{9}{2}, 7 - \frac{9}{2} \right) = \left(\frac{4-9}{2}, \frac{14-9}{2} \right)$$

$$\bar{e}_2 = \left(-\frac{5}{2}, \frac{5}{2} \right) \quad \text{so } |E_2| = \sqrt{\frac{25}{4} + \frac{25}{4}} = \sqrt{\frac{50}{4}} = \frac{5}{2} \sqrt{2}$$

$$\text{so } |E| = \frac{5}{2} \sqrt{2}$$

in the case fitting is done using $D=1$
i.e. $|E|^2 = \frac{25}{2} = \sqrt{12.5}$

For $D = \frac{7}{2}$ case

Section 3.3 # 2

Fit line through $(1,1)$, $(2,7)$ using least squares.

Solution

equation of line is $b = C - Dt$

write equations as if line goes through points:

Point $(1,1)$

$b=1, t=1 \Rightarrow$

$1 = C + D$

Point $(2,7)$

$b=7, t=2 \Rightarrow$

$7 = C + 2D$

$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 1 \\ 7 \end{bmatrix}$$

Solve by Least squares:

$$A^T A \hat{x} = A^T b$$

$$\hat{x} = (A^T A)^{-1} A^T b$$

but $A^T = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$ so $A^T A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix}$ so $(A^T A)^{-1} = \frac{1}{10-9} \begin{bmatrix} 5 & -3 \\ -3 & 2 \end{bmatrix}$

so $\hat{x} = \begin{bmatrix} 5 & -3 \\ -3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 7 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 7 \end{bmatrix} = \begin{bmatrix} -5 \\ -6 \end{bmatrix}$

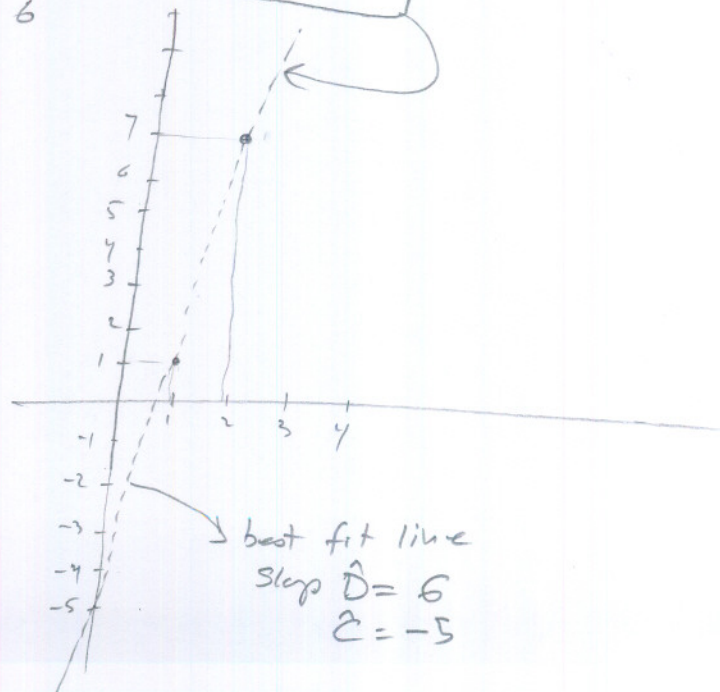
so $\hat{C} = -5, \hat{D} = -6$.

so best fit is line

$b = -5 + 6t$

@ $b=1 \Rightarrow t=1$
@ $b=7 \Rightarrow t=2$

intersect $b=-5$, slope = 6

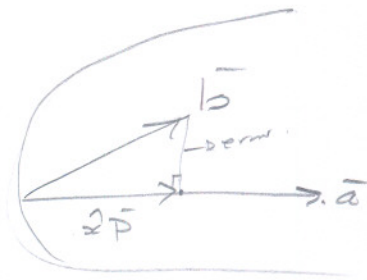


Section 3.3 #3

Solve $Ax=b$ by least squares and find $P=A\hat{x}$

$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$, $b = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, verify the error $b-p$ is \perp

the columns of A



Answer

$$A^T A \hat{x} = A^T b$$

$$\hat{x} = (A^T A)^{-1} A^T b$$

$$= \left(\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \frac{1}{4-1} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow \hat{x} = \begin{bmatrix} 1/3 \\ 1/3 \end{bmatrix}$$

$$\text{so } \bar{p} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1/3 \\ 1/3 \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 2/3 \end{bmatrix}$$

to verify error $\bar{b} - \bar{p}$ is \perp to columns of A :

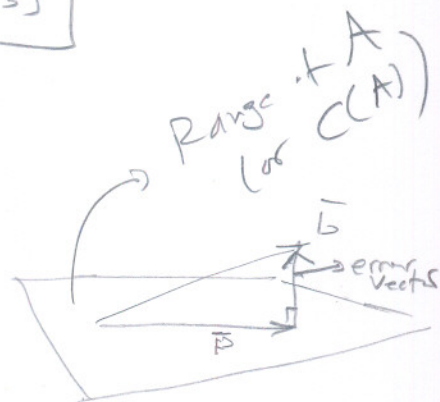
$$\bar{b} - \bar{p} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1/3 \\ 1/3 \\ 2/3 \end{bmatrix} = \begin{bmatrix} 2/3 \\ 2/3 \\ -1/3 \end{bmatrix}$$

to verify $\bar{e} \perp$ columns of A , take dot product with each col.

$$e^T \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 2/3 & 2/3 & -1/3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \frac{2}{3} - \frac{2}{3} = 0$$

$$e^T \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2/3 & 2/3 & -1/3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \frac{2}{3} - \frac{2}{3} = 0$$

} Verified ok.



$$\bar{p} + \bar{e} = \bar{b} \Rightarrow \bar{e} = \bar{b} - \bar{p}$$

section 3.3 # 4

$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$, $x = \begin{bmatrix} u \\ v \end{bmatrix}$, $b = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}$. Find \hat{x} using method of

$E^2 = \|Ax - b\|^2$ and minimize. and also by method of

$A^T A \hat{x} = A^T b$. why is $\hat{p} = \bar{b}$?

Answer

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}, x = \begin{bmatrix} u \\ v \end{bmatrix}, b = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}$$

$$E^2 = \|Ax - b\|^2 = \left\| \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} - \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} \right\|^2$$

$$= \left\| \begin{bmatrix} u \\ v \\ u+v \end{bmatrix} - \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} \right\|^2$$

$$E^2 = \left\| \begin{bmatrix} u-1 \\ v-3 \\ u+v-4 \end{bmatrix} \right\|^2 = (u-1)^2 + (v-3)^2 + (u+v-4)^2$$

$$\frac{d(E^2)}{du} = 0 \Rightarrow 2(u-1) + 2(u+v-4) = 2u-2+2u+2v-8=0$$
$$4u+2v-10=0$$

$$\frac{d(E^2)}{dv} = 0 \Rightarrow 2(v-3) + 2(u+v-4) = 2v-6+2u+2v-8=0$$
$$4v+2u-14=0$$

$$\text{so } \begin{cases} 4u+2v-10=0 \\ 4v+2u-14=0 \end{cases} \Rightarrow \begin{cases} u = \frac{10-2v}{4} \\ 4v+2\left(\frac{10-2v}{4}\right)-14=0 \Rightarrow 4v+5-v-14=0 \Rightarrow 3v=9 \\ \boxed{v=3} \end{cases}$$

$$\text{so } u = \frac{10-2(3)}{4} = \frac{10-6}{4} = 1$$

so $\boxed{u=1, v=3}$ ← this gives $\frac{d(E^2)}{du} = 0$ and $\frac{d(E^2)}{dv} = 0$.

so $\hat{x} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ that minimizes error in least square sense.

now find \hat{x} using $A^T A \hat{x} = A^T b$:

$$\hat{x} = (A^T A)^{-1} A^T b = \left(\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}^{-1} \begin{bmatrix} 5 \\ 7 \end{bmatrix}$$
$$= \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 5 \\ 7 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 3 \\ 9 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \text{ which matches method}$$

using calculus. →

$$\hat{x} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$\bar{P} = A \hat{x} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

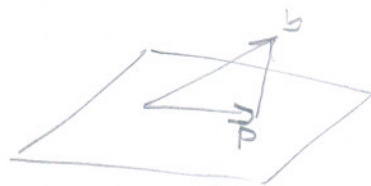
note: $\bar{P} = \bar{b}$.

notice that $\bar{P} = \bar{b}$ in this example.

The reason is that \bar{b} lives in $C(A)$.

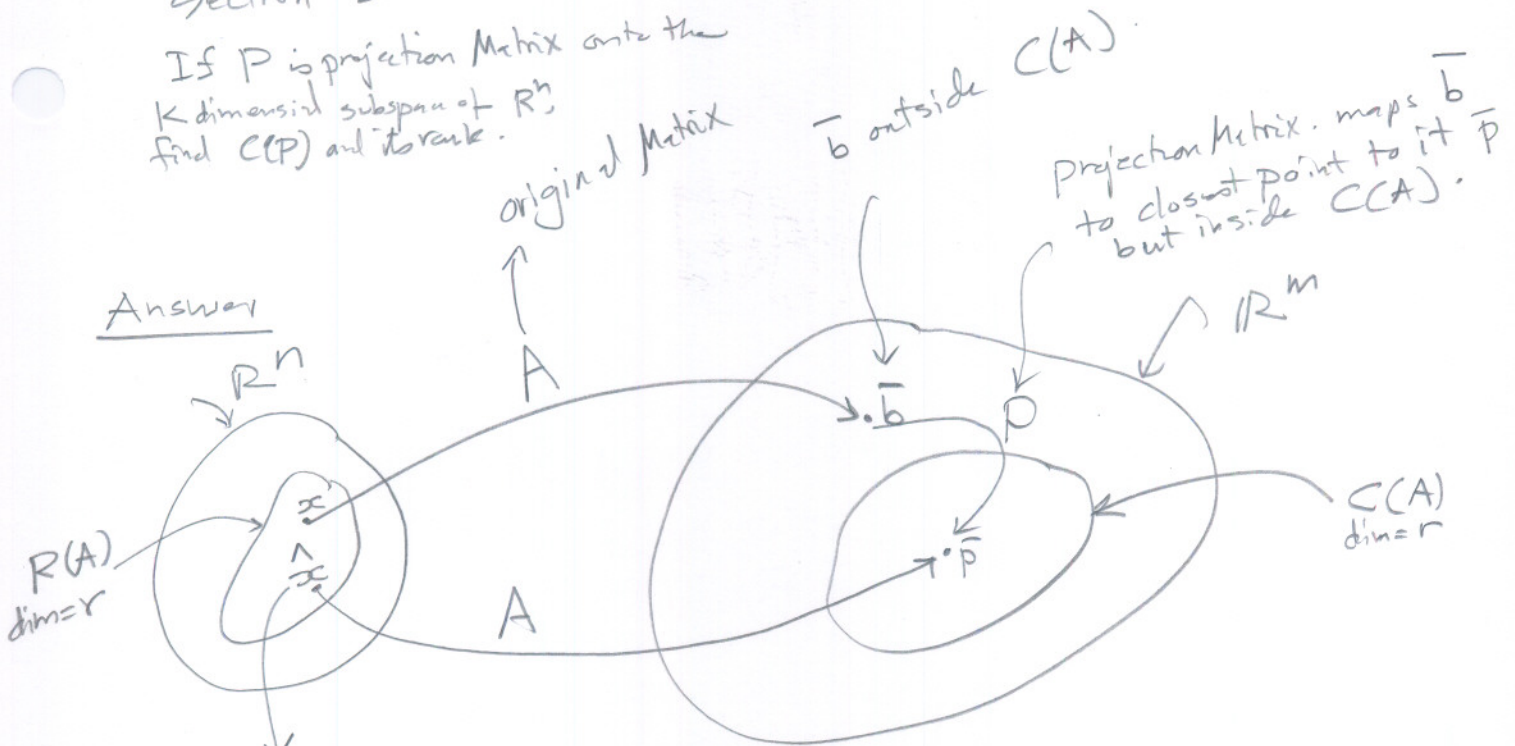
$$3 \text{ times } 1^{\text{st}} \text{ col of } A + 1 \text{ time } 2^{\text{nd}} \text{ col } A = \bar{b}$$

so \bar{b} is on the "plane" of $C(A)$. hence error is zero. $\bar{b} = \bar{P}$.



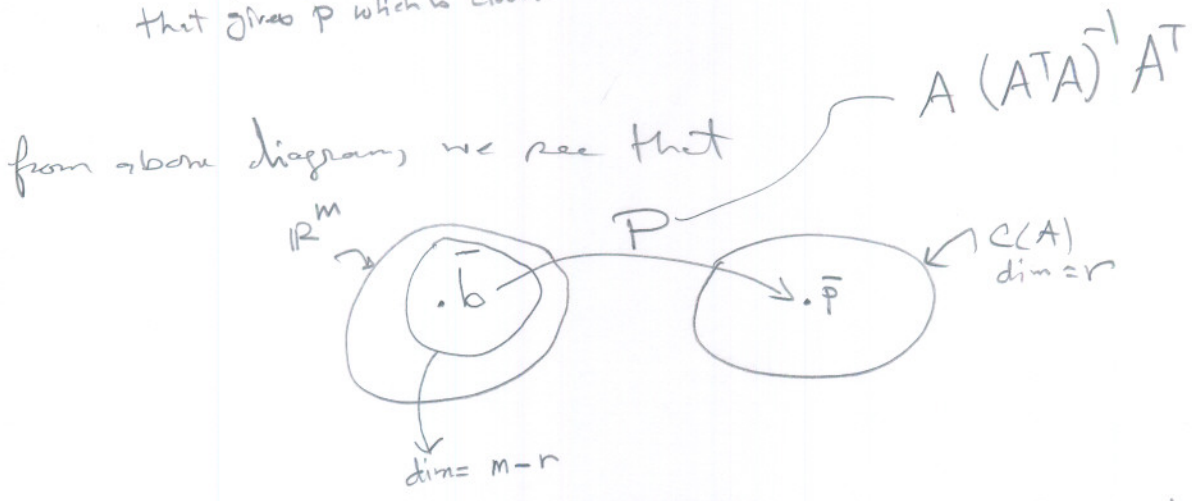
Section 3.3 # 8

If P is projection Matrix onto the k dimensional subspace of \mathbb{R}^m , find $C(P)$ and its rank.



Answer

This is least squares error solution.
 best approximation to solution that gives \bar{p} which is closest to \bar{b} . i.e. $A\hat{x}=\bar{p}$



from above diagram, we see that

so column space of P is $C(A)$.

we are told this has $\dim=k$

so $r=k$.

its rank = $m-r = m-k$

if A is square, then P rank = $n-k$ = $m-k$

$A = m \times n$

Section 3.3 # 14

The vectors $a_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$, $a_2 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ span a plane in \mathbb{R}^3 .
 Find the projection matrix P onto the plane and a nonzero vector \underline{b} that is projected to zero.

Answer

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\begin{aligned} P &= A(A^T A)^{-1} A^T = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \left(\begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3/2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1/2 & 0 \\ 1/2 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} = \boxed{\begin{bmatrix} 1/2 & 1/2 & 0 \\ 1/2 & 1/2 & 0 \\ 0 & 0 & 1 \end{bmatrix}} \end{aligned}$$

now solve for $P \underline{b} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

$$\text{so } \begin{bmatrix} 1/2 & 1/2 & 0 \\ 1/2 & 1/2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{so } b_3 = 0$$

$$\frac{1}{2} b_1 + \frac{1}{2} b_2 = 0 \Rightarrow b_1 = -b_2$$

$$\Rightarrow \underline{\bar{b}} = \begin{bmatrix} b_1 \\ -b_1 \\ 0 \end{bmatrix}$$

$$\underline{\bar{b}} = t \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

so $\underline{\bar{b}}$ is vector through point $(1, -1, 0)$

For $t=1$.

$$\text{it is } \boxed{\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}}$$