

Solution Key

5.6 #1, 2, 5, 11, 18, 29

#1 B is similar to $A \Rightarrow B = M^{-1}AM$

C is similar to $B \Rightarrow C = N^{-1}BN$

$$\begin{aligned} \text{Then } C &= N^{-1}(M^{-1}AM)N \\ &= N^{-1}M^{-1}AMN \\ &= (MN)^{-1}AMN \quad \text{let } W=MN \\ &= W^{-1}AW \quad \Rightarrow A \text{ and } C \text{ are similar.} \end{aligned}$$

Any matrix that is similar to I

is $B = M^{-1}IM = I$! The only matrix similar to I is I !

#2 $A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$, all matrices that are similar to A are of

the form $B = M^{-1} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} M$

or equivalently have eigenvalues $1, -1$.

For example we can either pick an $M = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$

$$M^{-1} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

$$\begin{aligned} B_1 &= \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -2 & -1 \end{bmatrix} \end{aligned}$$

or we could just write any 2×2 matrix with eigenvalues $1, -1$:

$$B_2 = \begin{bmatrix} 1 & 4 \\ 0 & -1 \end{bmatrix} \quad \text{for example.}$$

#5 Show that if B is invertible, then BA is similar to AB .

(2)

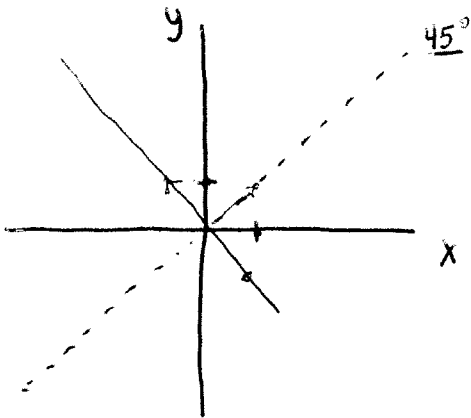
$$B^{-1}B = I$$

$$B^{-1}BA = A$$

$$B^{-1}BAB = \underline{AB}$$

So $M^{-1}BA M = AB$ with $M=B$.

#11



$$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = 0 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = 1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$T_V = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = 1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = 0 \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 1 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$T_V = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

The key to getting this matrix correctly is to use the new basis for all components of the computation.

5Q in text shows how the matrices are similar

$$T_V = M^{-1} T_V M$$

M takes a vector in V and changes the coordinates to V .

In this case the same vector can be written in two separate bases:

$$a \begin{bmatrix} 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 1 \\ -1 \end{bmatrix} = x \begin{bmatrix} 1 \\ 0 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$

M \uparrow vector in V \uparrow vector in V

#18

3

An example of a matrix that is not Hermitian but is normal is

$$A = \begin{bmatrix} 1 & i \\ i & 1 \end{bmatrix}$$

$$AA^H = \begin{bmatrix} 1 & i \\ i & 1 \end{bmatrix} \begin{bmatrix} 1 & -i \\ -i & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$A^H A = \begin{bmatrix} 1 & -i \\ -i & 1 \end{bmatrix} \begin{bmatrix} 1 & i \\ i & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

The key point is that you don't have to be Hermitian, skew-Hermitian, unitary or diagonal to be normal (i.e. to be diagonalizable).

I wanted you to show that projection matrices of the form

$p = AA^T$ is normal, since it comes up in SVD. Note that this matrix projects onto the column space of A .

$$pp^H = (AA^T)(AA^T)^T = AA^T(A^T)^T A^T = AA^T A A^T$$

$$p^H p = (AA^T)^T (AA^T) = (A^T)^T A^T A A^T = AA^T A A^T \checkmark$$

So when we do SVD, we will also be able to find enough eigenvectors to diagonalize AA^T .

You could have also shown it was symmetric.

#29 From notes in class we have

$$A = M^{-1} \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix} M$$

$$A^k = M^{-1} \begin{bmatrix} \lambda^k & k\lambda^{k-1} \\ 0 & \lambda^k \end{bmatrix} M$$

$$e^{At} = M^{-1} \begin{bmatrix} e^{\lambda t} & t e^{\lambda t} \\ 0 & e^{\lambda t} \end{bmatrix} M$$

if you apply these to the problem, you get the answer in the back of the text.

Section 6.1 #1,2,3,5,17

#1 Solution in text, $f(x,y) = x^2 + 4xy + 2y^2$

$= (x+2y)^2 - 2y^2$, the point is that even if all of the coefficients of a polynomial are positive, the polynomial can still be negative.

#2 In this section, we have matrices of the form $\begin{bmatrix} a & b \\ b & c \end{bmatrix}$

and can use the test for positive definiteness $a > 0$ and $ac > b^2$.

a) $A = \begin{bmatrix} 1 & 3 \\ 3 & 5 \end{bmatrix}$ $1 > 0$ $a > 0 \checkmark$ $ac = 5 \not> b^2 = 9$ not positive definite

$$f(x,y) = [x \ y] \begin{bmatrix} 1 & 3 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^2 + 6xy + 5y^2$$

b) $B = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$ $1 = a > 0 \checkmark$ $ac = 1 = b^2 \Rightarrow$ not positive definite (actually positive semi-definite)

$$f(x,y) = x^2 - 2xy + y^2$$

c) $C = \begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix}$ $a = 2 > 0 \checkmark$ $ac = 10 > b^2 = 9 \Rightarrow$ positive definite

$$f(x,y) = 2x^2 + 6xy + 5y^2$$

d) $D = \begin{bmatrix} -1 & 2 \\ 2 & -8 \end{bmatrix}$ $a = -1 < 0 \times$ not positive definite.

$$f(x,y) = -x^2 + 4xy - 8y^2$$

For part b) if we write $f(x,y)$ as a sum of squares

$$x^2 - 2xy + y^2 = (x - y)^2$$

so this function will be zero along $x - y = 0 \Rightarrow y = x$. you see it is not positive definite, but positive semi-definite as it always increases or stays zero (along $x = y$).

#3. Solution in text. The point is to make a connection with the next section where we show that having all positive eigenvalues is equivalent to being positive definite.

#5. The solution is in the text.

A couple of comments that might be useful:

c) to find the minimum value of $f(x, y)$ first you find the critical point (x_c, y_c) so that $\frac{\partial}{\partial x} f(x_c, y_c) = \frac{\partial}{\partial y} f(x_c, y_c) = 0$ and then you plug those values (x_c, y_c) to find the minimum of $f = f(x_c, y_c)$.

d) If $b=3$, $f(x, y) = \frac{1}{2}(x^2 + 6xy + 9y^2) - y$
 $= \frac{1}{2}(x+3y)^2 - y$

if we look at the line $x+3y=0 \Rightarrow x=-3y$

then as $y \rightarrow \infty$, $f(x, y) \rightarrow 0 - \infty$ and hence $f(x, y)$ has no minimum.

The key is that when you face a non-invertible matrix in the calculation (like when $b=3$), you go back to basics.

#17 $A^T A$ is important for SVD. You see how cl pick problems :)

$$\vec{x}^T A^T A \vec{x} = \underbrace{(A\vec{x})^T}_{R} \underbrace{(A\vec{x})}_{R} = \|A\vec{x}\|^2 = 0 \text{ only if } A\vec{x} = \vec{0}$$

Since A has linearly independent columns that only happens when $\vec{x} = \vec{0}$.

6.2 # 4, 6, 7, 8

(6)

4. If A is positive definite then it has positive eigenvalues.

$$A\vec{x} = \lambda\vec{x} \quad \text{with } \lambda > 0$$

to look at the eigenvalues of A^2 we multiply the eigenvalue equation by A

$$A^2\vec{x} = \lambda A\vec{x}$$

$$= \lambda^2\vec{x} \Rightarrow A^2 \text{ has eigenvalues } \lambda^2 \text{ hence is also positive.}$$

A^2 is positive definite.

$$A^{-1}A\vec{x} = \lambda A^{-1}\vec{x}$$

$$\vec{x} = \lambda A^{-1}\vec{x}$$

$$\frac{1}{\lambda}\vec{x} = A^{-1}\vec{x} \Rightarrow \text{the eigenvalues of } A^{-1} \text{ are } \frac{1}{\lambda} \text{ which are positive if } \lambda \text{ is positive.}$$

#6

$$A = \begin{bmatrix} 5 & 4 \\ 4 & 5 \end{bmatrix} \quad \text{for } (L\sqrt{D})(\sqrt{D}L^T) \Rightarrow R = \sqrt{D}L^T = \frac{1}{\sqrt{5}} \begin{bmatrix} 5 & 4 \\ 0 & 3 \end{bmatrix}$$

$$A = R^T R \quad (Q\sqrt{\Lambda})(\sqrt{\Lambda}Q^T) \Rightarrow R = \sqrt{\Lambda}Q^T = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 3 & 3 \end{bmatrix}$$

$$(Q\sqrt{\Lambda}Q^T)(Q\sqrt{\Lambda}Q^T) \Rightarrow R = Q\sqrt{\Lambda}Q^T = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

The point is that R is not unique but as long as you can write $A = R^T R$ with R having linearly independent columns, A is positive definite.

#7 solution in text, but \ll elaborate.

$$A = R^2 = (Q\sqrt{\Lambda}Q^T)(Q\sqrt{\Lambda}Q^T)$$

the eigenvalues of R are $\sqrt{\lambda_i}$ since $R = Q\sqrt{\Lambda}Q^T$

and since R^2 has eigenvalues λ_i (by problem 4) we see that $A\vec{x} = \lambda_i\vec{x}$ is P.D. then $\lambda_i > 0$ and $\sqrt{\lambda_i} > 0$.

#8 A is symmetric positive definite, C is invertible, we need to prove $B = C^T A C$ is symmetric positive definite.

$$\text{Symmetric } (C^T A C)^T = C^T A^T C = C^T A C \checkmark$$

$$\text{P.D. let } A = R^T R, \text{ then } B = C^T R^T R C, \text{ let } W = RC$$

$$B = W^T W$$

$RC\vec{x} = \vec{0}$ only if $C\vec{x} = \vec{0}$ since R has linearly independent columns & $C\vec{x} = \vec{0}$ when $\vec{x} = \vec{0}$ since C is invertible. Since $RC\vec{x} = \vec{0}$ only has $\vec{x} = \vec{0}$ as a solution,